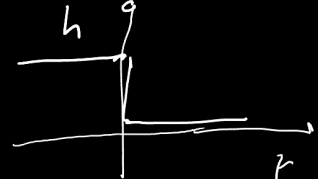


Generalized response function

$$\hat{C}_{ij}(t) = \langle \hat{C}_{ij}(t) \rangle$$

$$\hat{X}_i = \tau_i \hat{X}_i \quad \tau_i = \pm 1$$


 $(h(t) \text{ --- } \tau) \rightarrow (X_i(t)) = \beta h \langle X_i(t) X_i(0) \rangle$

ON SAGG representation relation

ENTROPY PRODUCTION RATE

$$dS = dS + dS_2 \quad dS \geq 0$$

$X_i$  extensive thermodynamic observable

affinity  $\mathbb{F}_i = \frac{\partial S}{\partial X_i} = F_i - F_i^{(2)}$

$\mu, T, p$  ensemble

$$T dS = dU + p dV - \sum_j \mu_j dN_j$$

$$\mathbb{F}_U = \frac{1}{T} - \frac{1}{T_2}; \quad \mathbb{F}_V = \frac{p}{T} - \frac{p_2}{T_2}; \quad \mathbb{F}_{N_j} = -\frac{\mu_j}{T} + \frac{\mu_j^{(2)}}{T_2}$$

fluxes:  $J_i = \frac{dX_i}{dt}$

$$\frac{dS}{dt} = \sum_i \mathbb{F}_i J_i \geq 0 \quad (\text{2nd Law})$$

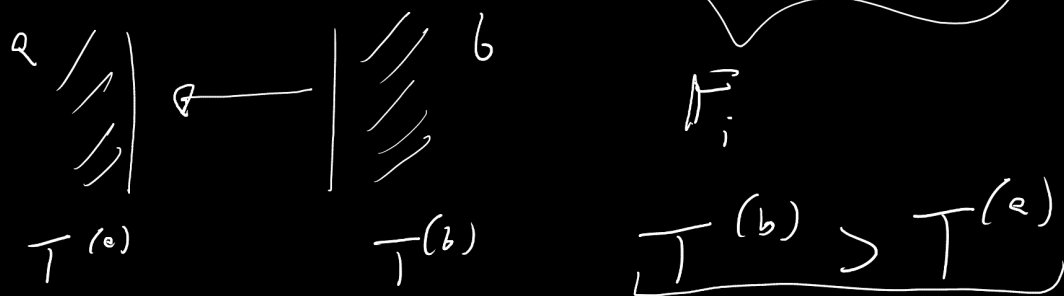
2 reservoirs (a, b)

$$X_i = X_i + X_i^{(a)} + X_i^{(b)}$$

$$X_i \text{ conserved} \Rightarrow dX_i = 0 = dX_i + dX_i^{(a)} + dX_i^{(b)}$$

$$\rightarrow dX_i^{(a)} = -dX_i^{(b)} \rightarrow J_i^{(a)} = -J_i^{(b)} \approx dX_i^{(a)} + dX_i^{(b)}$$

$$\frac{dS}{dt} \approx \sum_i \left( \frac{\partial S_a}{\partial X_i^{(a)}} - \frac{\partial S_b}{\partial X_i^{(b)}} \right) J_i^{(a)}$$



$$\frac{dS}{dt} \approx \underbrace{\left( \frac{1}{T^{(a)}} - \frac{1}{T^{(b)}} \right)}_{F_u > 0} \underbrace{J_u^{(a)}}_{> 0} \geq 0$$

$J_u^{(b)} = -J_u^{(a)} < 0$

ENTROPY PRODUCTION RATE FOR CONTINUOUS SYSTEM

$S(\vec{x}); X_i(\vec{x}^0)$  (assumption of local equilibrium)

$$dS = \sum_i F_i dX_i \quad \left( F_i = \frac{\partial S}{\partial X_i} \right)$$

intensive quantities  $s = \frac{S}{V}; x_i = \frac{X_i}{V} \quad F_i = \frac{\partial s}{\partial x_i}$

$$\underline{ds = \sum_i F_i dx_i}$$

current densities  $\vec{j}_s = \sum_i F_i \vec{j}_i$  current density for  $s$

entropy is not conserved:

$$\frac{dS}{dt} = \frac{\partial S}{\partial t} + \vec{\nabla} \cdot \vec{j}_s$$

"volume" term      "surface" term

$x_i$  are conserved  $\rightarrow \frac{dx_i}{dt} = \frac{\partial x_i}{\partial t} + \vec{\nabla} \cdot \vec{j}_i = 0$

continuity equation

$$\frac{\partial S}{\partial t} = \sum_i F_i \frac{\partial x_i}{\partial t}$$

$$\vec{\nabla} \cdot \vec{j}_s = \vec{\nabla} \cdot \left( \sum_i F_i \vec{j}_i \right) = \sum_i \left( \vec{\nabla} F_i \cdot \vec{j}_i + F_i \vec{\nabla} \cdot \vec{j}_i \right)$$

$$\frac{dS}{dt} = \frac{\partial S}{\partial t} + \vec{\nabla} \cdot \vec{j}_s = \sum_i F_i \left( \frac{\partial x_i}{\partial t} + \vec{\nabla} \cdot \vec{j}_i \right) + \sum_i \vec{\nabla} F_i \cdot \vec{j}_i$$

$$\frac{dS}{dt} = \sum_i \vec{\nabla} F_i \cdot \vec{j}_i$$

continues operation

$$\frac{dS}{dt} = \sum_i F_i J_i$$

$$\vec{H}_i = \vec{\nabla} F_i(\vec{r})$$

$$F_i = F_i - F_i^{(1)}$$

Phenomenological equations involving transport kinetic coefficients

$(\mathcal{M}_{ij}; \underline{L}_{ij} \rightarrow \text{Onsager kinetic coefficients})$  kinetic coefficients

(Linear response theory)

Definition of  $M$  coefficients:

$$\left[ \langle \dot{X}_i \rangle = \frac{d}{dt} \langle X_i \rangle = - \sum_k M_{ik} \langle X_k(t) \rangle \right]_{\mathcal{F}}$$

(near equilibrium averages)

(if observable  $\frac{d}{dt} \langle X_i \rangle = - M_{ii} \langle X_i(t) \rangle$ )

( $\langle X_i \rangle_0 = 0$ )  $\rightarrow$  exponential decay of  $\langle X_i(t) \rangle$

Ansatz resp. relation  $\langle X_i(t) \rangle = \langle X_i(t) X_j(0) \rangle_0$

$$\frac{d}{dt} \langle X_i(t) X_j(0) \rangle_0 = - \sum_k M_{ik} \langle X_k(t) X_j(0) \rangle_0$$

if  $\tau_i = \tau_j = 1 \rightarrow \langle X_i(t) X_j(0) \rangle_0 = \langle X_j(t) X_i(0) \rangle_0$

$$\frac{d}{dt} \dots \sum_k M_{ik} \langle X_k(t) X_j(0) \rangle_0 = \sum_k M_{jk} \langle X_k(t) X_i(0) \rangle_0$$

Define  $L_{ij} = \sum_k M_{ik} \langle X_k X_j \rangle_0$  ( $\langle X_k(0) X_j(0) \rangle_0$ )

$t=0 \rightarrow L_{ij} = L_{ji}$  (Symmetric Onsager matrix ( $\tau_i = \tau_j = 1$ ))

$$\Rightarrow \langle \dot{X}_i \rangle = \frac{d}{dt} \langle X_i \rangle = \sum_k L_{ik} \langle F_k \rangle$$

general definition for  $L_{ij}$  (+  $\mathcal{F}(\mathbb{F}_k^2)$ )

$$L_{ik} = \frac{\partial \langle J_i \rangle}{\partial F_k} \quad \overline{F}_k = 0 \quad \forall k$$

Start from  $\textcircled{*}$  to recover  $\textcircled{+}$

Answer req. rel.:

$$\frac{d}{dt} \langle x_i(t) x_j(0) \rangle_0 = \sum_k L_{ik} \langle F_k(t) x_j(0) \rangle_0$$

$$= \sum_k M_{ik} \langle x_k(t) x_j(0) \rangle_0$$

$$\sum_k M_{ik} \langle x_k(t) x_j(0) \rangle_0 = - \sum_k L_{ik} \langle F_k(t) x_j(0) \rangle_0$$

$$\langle F_k(0) x_j(0) \rangle_0 = - \delta_{kj}$$

$$\Rightarrow \boxed{\sum_k M_{ik} \langle x_k x_j \rangle_0 = L_{ij}} \quad \textcircled{+}$$

$$\textcircled{*} \quad \frac{d\mathcal{F}}{dt} = \sum_i J_i F_i = \sum_{ij} L_{ij} F_i F_j$$

a bilinear form in  $F_i, F_j$

$d\mathcal{F}/dt > 0$  at  $F_i > 0$  (at least one  $i$ )

$$\Rightarrow \left[ L_{ii} > 0 \quad \text{and} \quad \det L > 0 \right]$$

$$\frac{d^2 \mathcal{F}}{dt^2} = 2 \sum_{i,j} L_{ij} \sum_k \frac{\partial F_i}{\partial x_k} \left( \frac{dx_k}{dt} \right) F_j$$

$L_{ij} = L_{ji}$

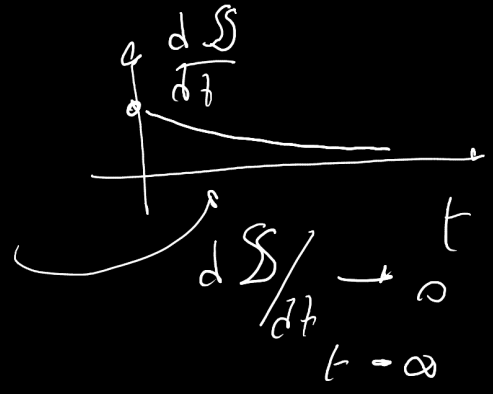
$$= 2 \sum_{i,k} \frac{\partial F_i}{\partial x_k} J_i J_k = 2 \sum_{i,k} \frac{d^2 \mathcal{F}}{\partial x_i \partial x_k} J_i J_k$$

$J_i = \sum_j L_{ij} F_j$        $F_i = \frac{d \mathcal{F}}{dx_i}$

$\mathcal{F}(\{x_i\})$  is a concave function of  $\{x_i\}$

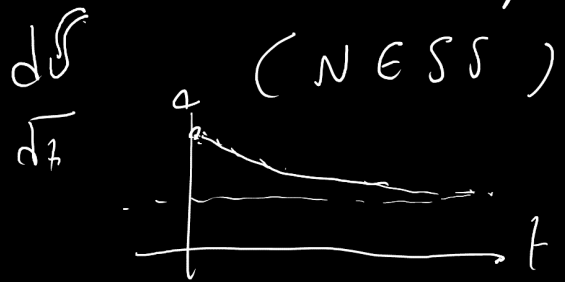
$d^2 \mathcal{F} / dx_i dx_j$  is a negative form

$$\frac{d^2 \mathcal{F}}{dt^2} \leq 0 \rightarrow \frac{d \mathcal{F}}{dt} \text{ always decreases}$$



2 possible scenarios:

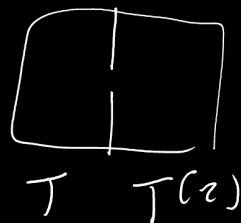
- relaxation to equilibrium
- relaxation to a stationary non-equilibrium state



$\frac{d \mathcal{F}}{dt} \rightarrow$  finite positive value  
 $t \rightarrow \infty$

# Mechano thermal effect (coupled transport)

(fixed Volume)



energy and  
particle  
fluxes  
coupled

$$dS = \frac{dU}{T} - \frac{\mu}{T} dN$$

$$F_U = \frac{1}{T} - \frac{1}{T_r}; \quad F_N = -\frac{\mu}{T} + \frac{\mu_r}{T_r} \quad (\text{observables } U, N)$$

$$J_U = \frac{dU}{dt}; \quad J_N = \frac{dN}{dt}$$

ONSAAGER MATRIX

$$\begin{cases} J_U = L_{UU} F_U + L_{UN} F_N \\ J_N = L_{NU} F_U + L_{NN} F_N \end{cases}$$

① Thermal equilibrium:  $F_U = 0$  ( $T = T_r$ )

$$J_U = L_{UN} \left( \frac{\mu_r - \mu}{T} \right) \quad (\text{for } F_N \neq 0)$$

$$J_U / J_N = \frac{L_{UN}}{L_{NN}} \quad \mu_r \neq \mu$$

② Thermomechanical effect:

steady state with  $J_N = 0$

$$F_N / F_U = - \frac{L_{UN}}{L_{NN}}; \quad J_U = F_U \left[ L_{UU} - \frac{L_{UN}^2}{L_{NN}} \right]$$

$$F_N, F_U \neq 0$$

$$= \frac{\det L}{L_{NN}} F_U$$

APPENDIX :  $\langle \overline{F}_k X_j \rangle_0 = -\delta_{kj}$

$$\left( L_{ij} = \sum_k \overline{\Pi}_{ik} \langle X_k X_j \rangle_0 \Leftrightarrow \langle \overline{J}_i \rangle = \sum_k L_{ik} \langle \overline{F}_k \rangle \right)$$

$$\langle \overline{F}_k X_j \rangle_0 = \int \prod_k dx_k \overline{F}_k X_j \exp(\mathcal{J}(\{x_n\}))$$

( $x_k^*$  = equilibrium values)  $\int \prod_k dx_k \exp(\mathcal{J}(\{x_n\}))$

$$\mathcal{J}(\{x_n\}) \simeq \mathcal{J}(\{x_n^*\}) + \frac{1}{2} \sum_{ij} \frac{\partial^2 \mathcal{J}}{\partial x_i \partial x_j} \Big|_{x_k = x_k^* + \Delta x_k} \Delta x_i \cdot \Delta x_j$$

$\Delta x_i = x_i - x_i^*$ ;  $\frac{\partial^2 \mathcal{J}}{\partial x_i \partial x_j}$  is a negative form

$$\overline{F}_k = \frac{\partial \mathcal{J}}{\partial x_k} \simeq \sum_i \frac{\partial^2 \mathcal{J}}{\partial x_k \partial x_i} \Delta x_i \quad \left. \begin{array}{l} \Delta x_i \\ x_j = x_j^* + \Delta x_j \end{array} \right\} x_j^* = \langle x_j \rangle_0$$

$$\langle \overline{F}_k X_j \rangle_0 \simeq \sum_i \frac{\partial^2 \mathcal{J}}{\partial x_k \partial x_i} \Big|_{x_\ell = x_\ell^* + \Delta x_\ell} \langle \Delta x_i \Delta x_j \rangle_0$$

( $x_j = \Delta x_j$ ; ( $x_j^* = 0$ ))

$$\simeq \sum_i \frac{\partial^2 \mathcal{J}}{\partial x_k \partial x_i} \Big|_{x_\ell = x_\ell^* + \Delta x_\ell} \cdot \left( - \left( \frac{\partial^2 \mathcal{J}}{\partial x^2} \right)^{-1}_{ij} \Big|_{x_\ell = x_\ell^* + \Delta x_\ell} \right)$$

$$\simeq - \left( \mathbb{1} \right)_{kj} = -\delta_{kj}$$