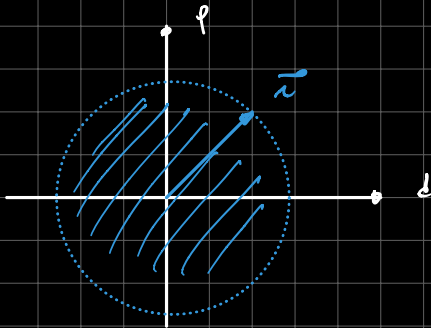
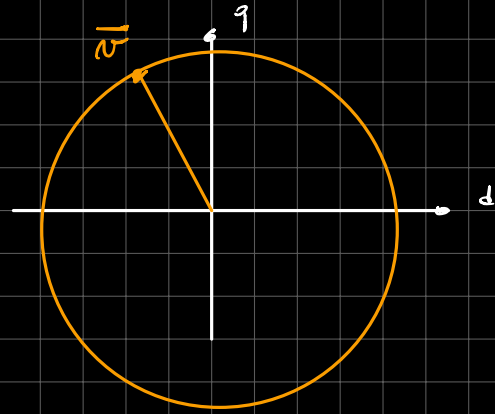


# DIAGRAMMI LIMITE DELLA MACCHINA SINCRONA

Limite di corrente



Limite di tensione



$$\vec{v}^R = R \vec{i}^R + L \frac{d\vec{i}^R}{dt} + j \omega_m \lambda^R$$

$$\begin{cases} V_d = R I_d - \omega_m^e L I_q \\ V_q = R I_q + \omega_m^e (\lambda_m + L I_d) \end{cases} \approx 0$$

$$m = \frac{3}{2} p \lambda_m I_q$$

$\omega_m^e$  come parametro

$$|\vec{i}| \leq I_m \quad I_d^2 + I_q^2 \leq I_m^2$$

$$|\vec{v}| \leq U_m \quad V_d^2 + V_q^2 \leq U_m^2$$

$$(\omega_m^e L I_q)^2 + [\omega_m^e (\lambda_m + L I_d)]^2 \leq U_m^2$$

$$\left( I_d + \frac{\lambda_m}{L} \right)^2 + I_q^2 \leq \left( \frac{U_m}{\omega_m^e L} \right)^2$$

centro  $\left( -\frac{\lambda_m}{L}; 0 \right)$

raggio  $\left( \frac{U_m}{\omega_m^e L} \right)$

Nota: centro si ottiene

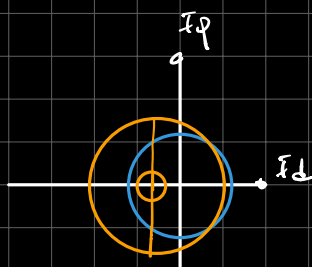
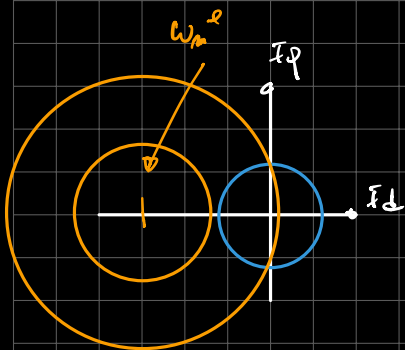
$$V_d = 0 = -\omega_m^e L I_q$$

$$I_q = 0$$

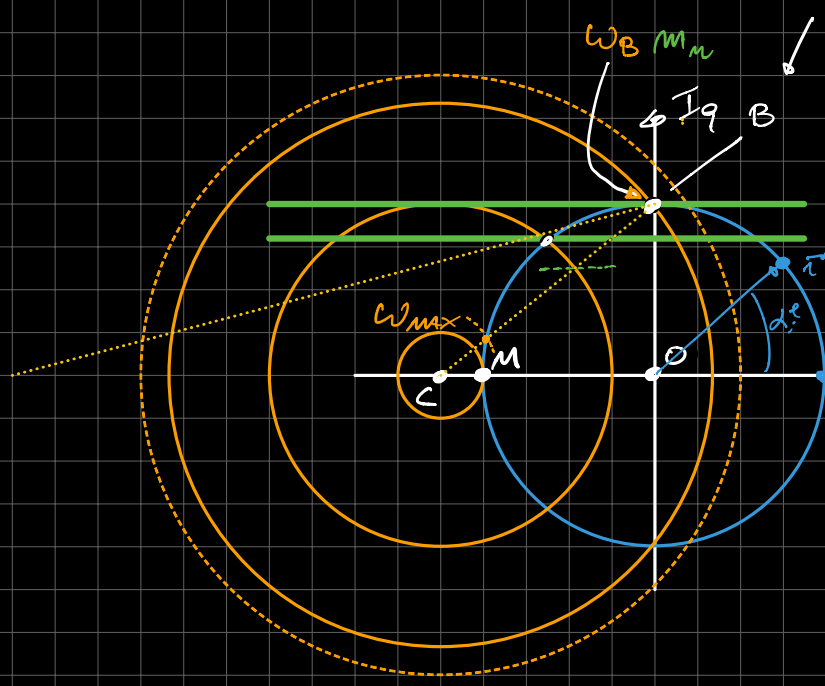
$$V_q = 0 = \omega_m^e (\lambda_m + L I_d)$$

$$I_d = -\frac{\lambda_m}{L}$$

$$I_{ch} = -\frac{\lambda_m}{L}$$



Punto B ADE

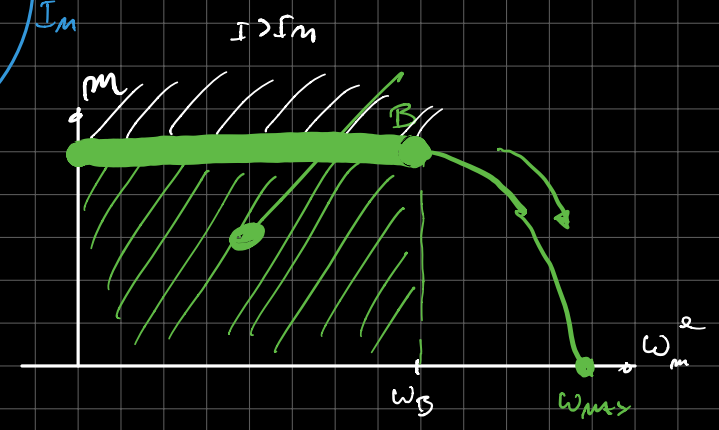


$$m = \frac{3}{2} p \lambda_m I_m$$

$$I_q = I_m$$

$$\overline{OB} = \text{MTPA} \quad \omega_m^e \leq \omega_B$$

"COSTANTE"



$$m = \frac{3}{2} p \lambda_m |\vec{i}| \sin \alpha$$

$$\frac{dm}{d\alpha} = 0 = \cos \alpha \quad \alpha = \frac{\pi}{2}$$

CALCOLO  $\omega_B$   $(\omega_B L I_q)^2 + \omega_B^2 (\lambda_m + L I_d)^2 = U_m^2$  con  $I_q = I_m$   $I_d = 0$

$$\omega_B^2 (L I_m)^2 + (\omega_B \lambda_m)^2 = U_m^2$$

$$\omega_B = \frac{U_m}{\sqrt{\lambda_m^2 + (L I_m)^2}}$$

CALCOLO  $\omega_{max}$

$$U_d^2 + U_q^2 = U_m^2$$

$$I_d = -I_m$$

$$I_q = 0$$

$$\omega_m^e = \omega_{max}$$

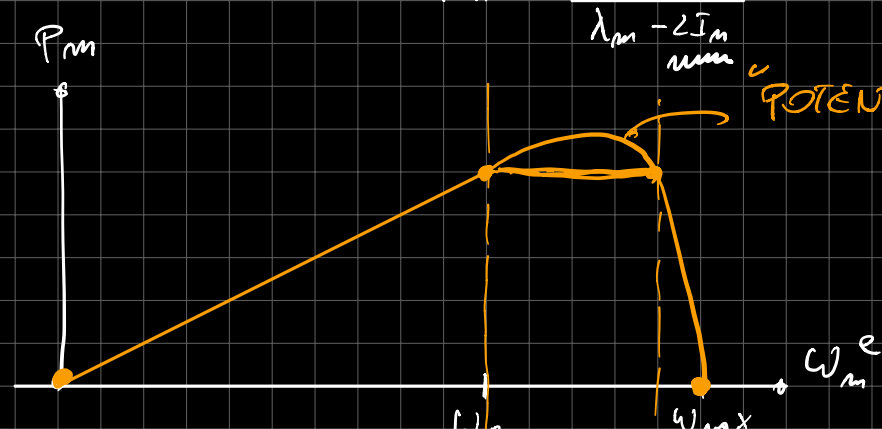
$$(\omega_{max} L I_q)^2 + \omega_{max}^2 (\lambda_m + L I_d)^2 = U_m^2$$

$$\omega_{max}^2 (\lambda_m - L I_m)^2 = U_m^2$$

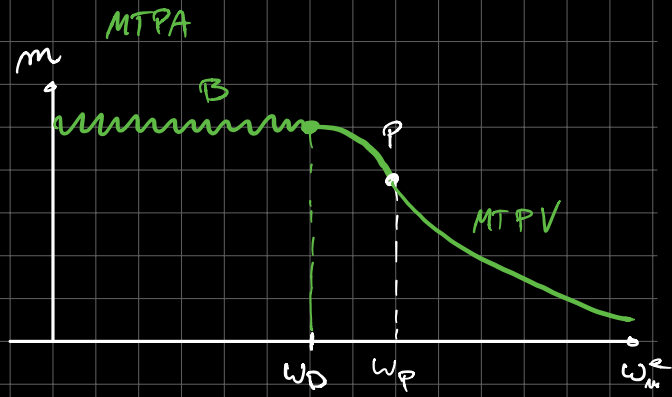
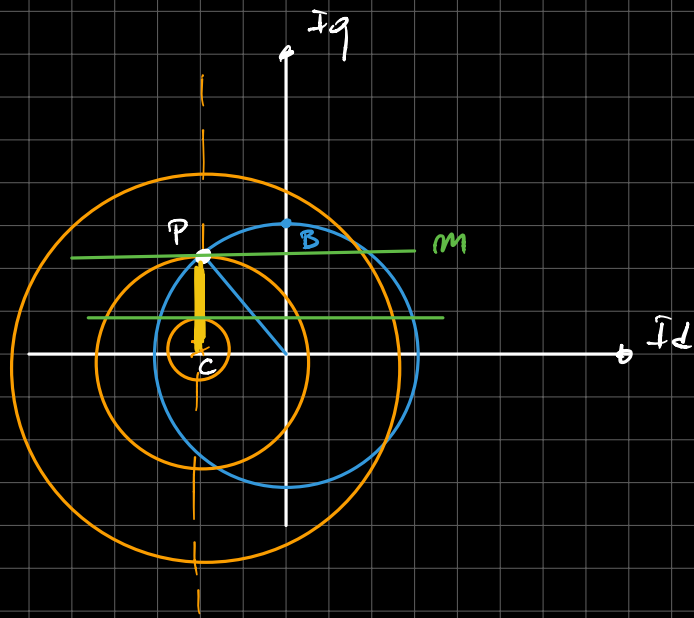
$$\omega_{max} = \frac{U_m}{\lambda_m - L I_m}$$

$L I_m \ll \lambda_m \quad \omega_B \approx \omega_{max}$

"POTENZA COSTANTE"



Controllo DC  $\omega_p$  mod  $P_m = \text{cost}$



Note:  $I_d < 0$

$$\begin{cases} \lambda_d = \lambda_m + 2 I_d \\ \lambda_q = 2 I_q \end{cases}$$

↓  
↓  
↑ Differenziale

Esempio

$V_{m,rms} = 250 \text{ V}$

concatenata

$I_{m,rms} = 200 \text{ A}$

$K_G = 0,6$

$\frac{V_{rms}}{\text{rad/s}}$

concatenata

$L = 0,15 \text{ mH}$

$R \approx 0$

$Z_p = 8$

$\lambda_m = ?$

concatenata

$$V_m = \frac{\sqrt{2} \cdot 250}{\sqrt{3}} = 204 \text{ V}$$

$$K_G \omega_m = V_{rms} = \frac{\sqrt{3} E}{\sqrt{2}} = \sqrt{\frac{3}{2}} \omega_m \lambda_m = \sqrt{\frac{3}{2}} \omega_m P \lambda_m$$

$$I_m = \sqrt{2} \cdot 200 = 282,8 \text{ A}$$

$$\lambda_m = \sqrt{\frac{2}{3}} \frac{K_G}{P} = \sqrt{\frac{2}{3}} \frac{0,6}{9} = 0,122 \text{ Vs}$$