

Engineering and Environmental Geophysics

Seismic prospecting

Outline

Methods for engineering geophysics

- seismic methods (refraction / reflection / surface wave)
- electrical methods (ERT)
- E-M methods (FDEM, RADAR)
- case histories



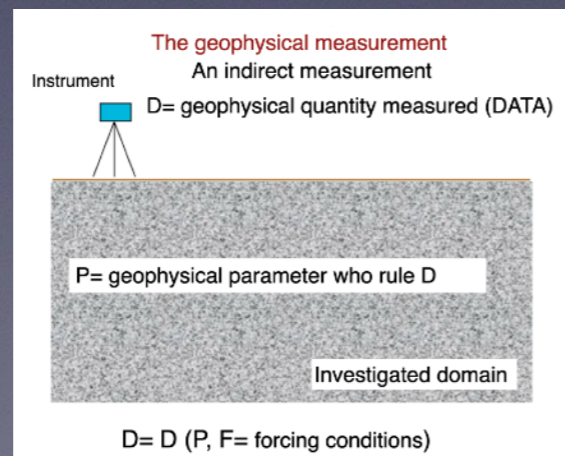
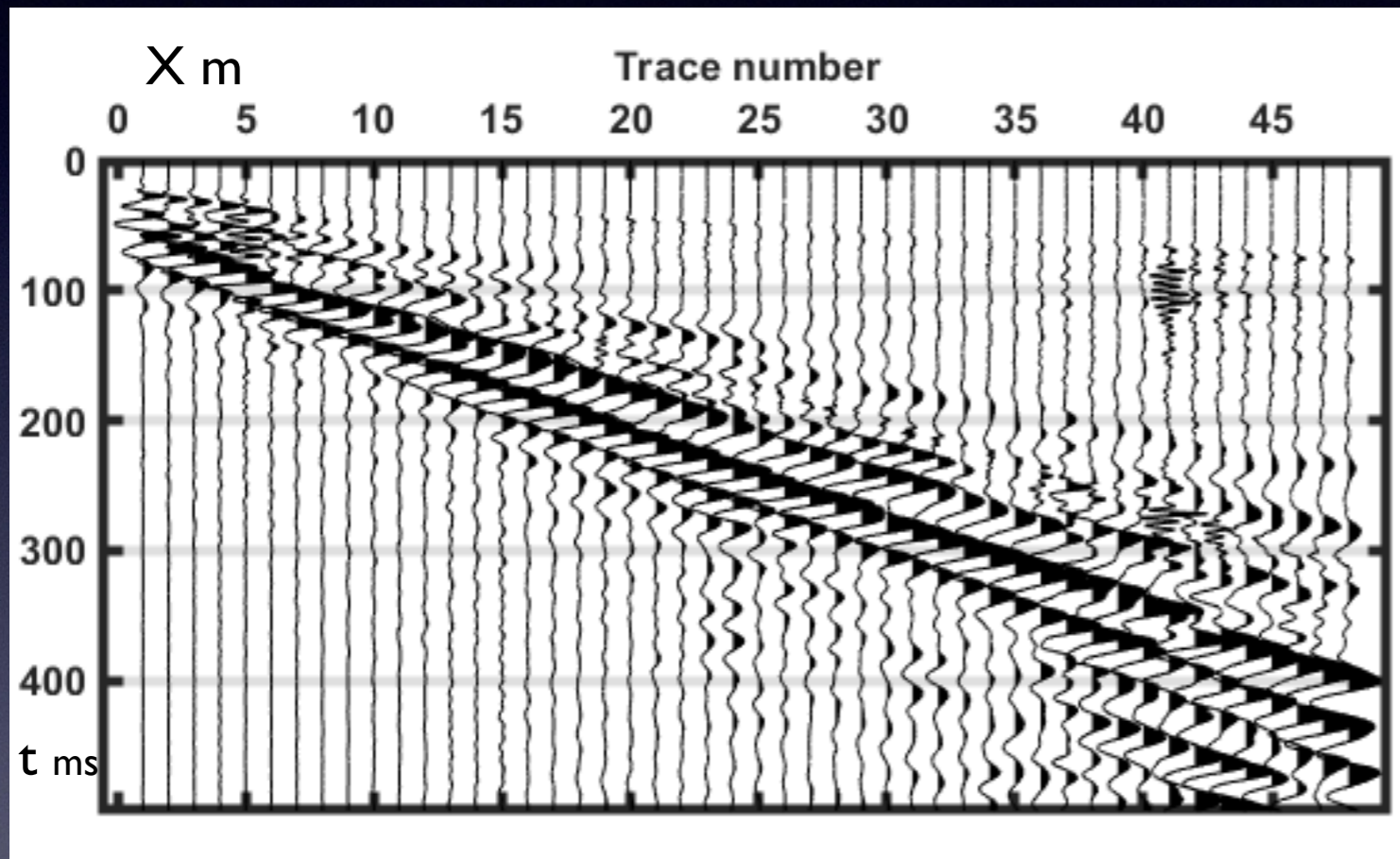
Method	Structure	Dynamic
Seismic	++	
Electro-Magnetic	+	++
DC resistivity methods ERT	++	++
Ground Penetration Radar	++	+
Distributed Temp. Sensing		++
Magnetics	+	
Gravimetry	+	+
Spectral Induced Polarization	+	
Self Potential		+
Borehole logs	++	+

Physical Properties (P)

- Seismic Elastic moduli and density
- Gravimetry : Density
- Magnetic meth. Magnetic susceptibility
- ERT meth. Electrical resistivity
- Electro-magnetic meth. Electrical conductivity
- Induced Polarization Electrical complex conductivity
- Spontaneous Potentials Electrical conductivity
- Ground penetrating Radar Dielectric constant

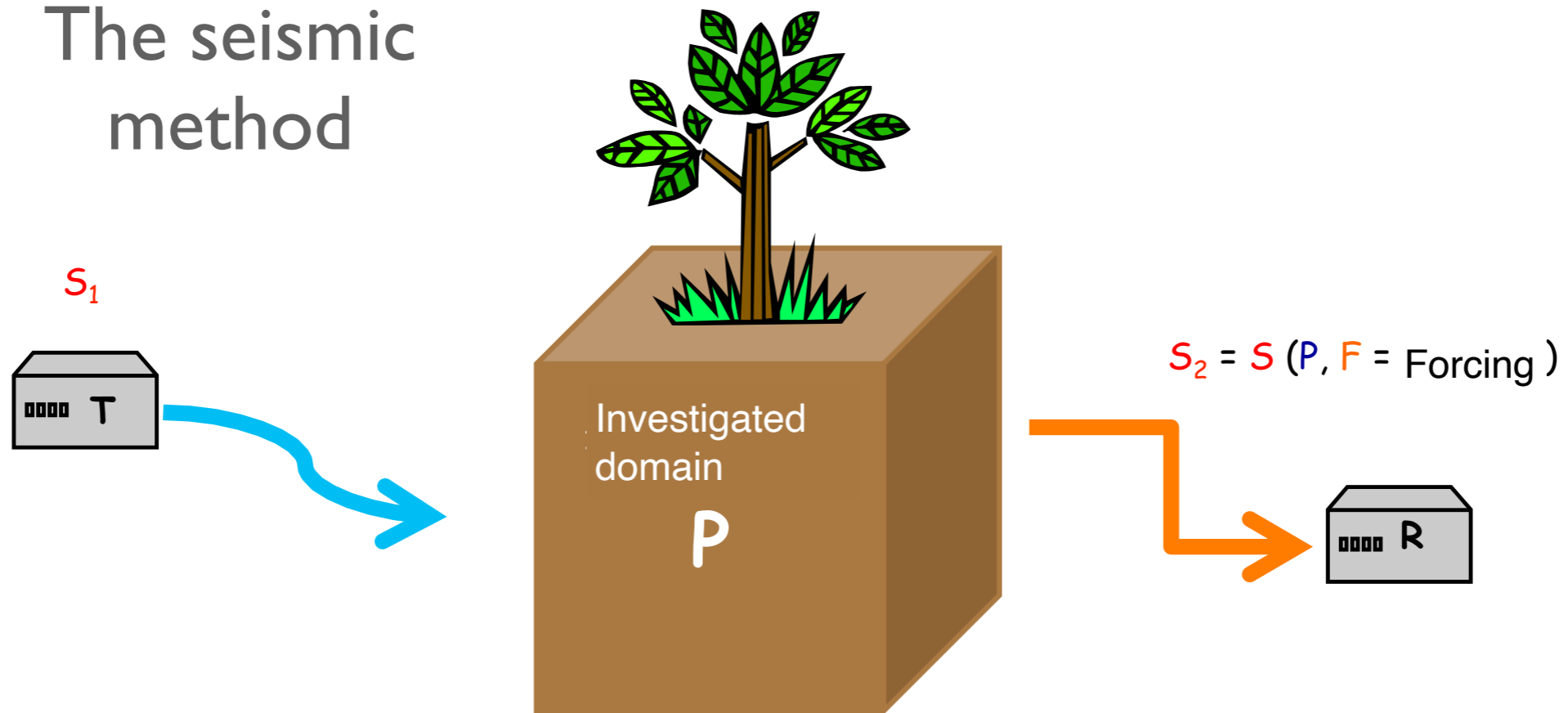
Seismic Methods

Study the wave elastic propagation in the subsoil and furnish the mechanical parameters



Physics parameter P
=
Elastic properties

The seismic method



S_1 = Signal =

Elastic wave source

S_2 = Signal =

Induced vibration

P = Physical parameter

Elastic moduli/ density



Borehole seismic

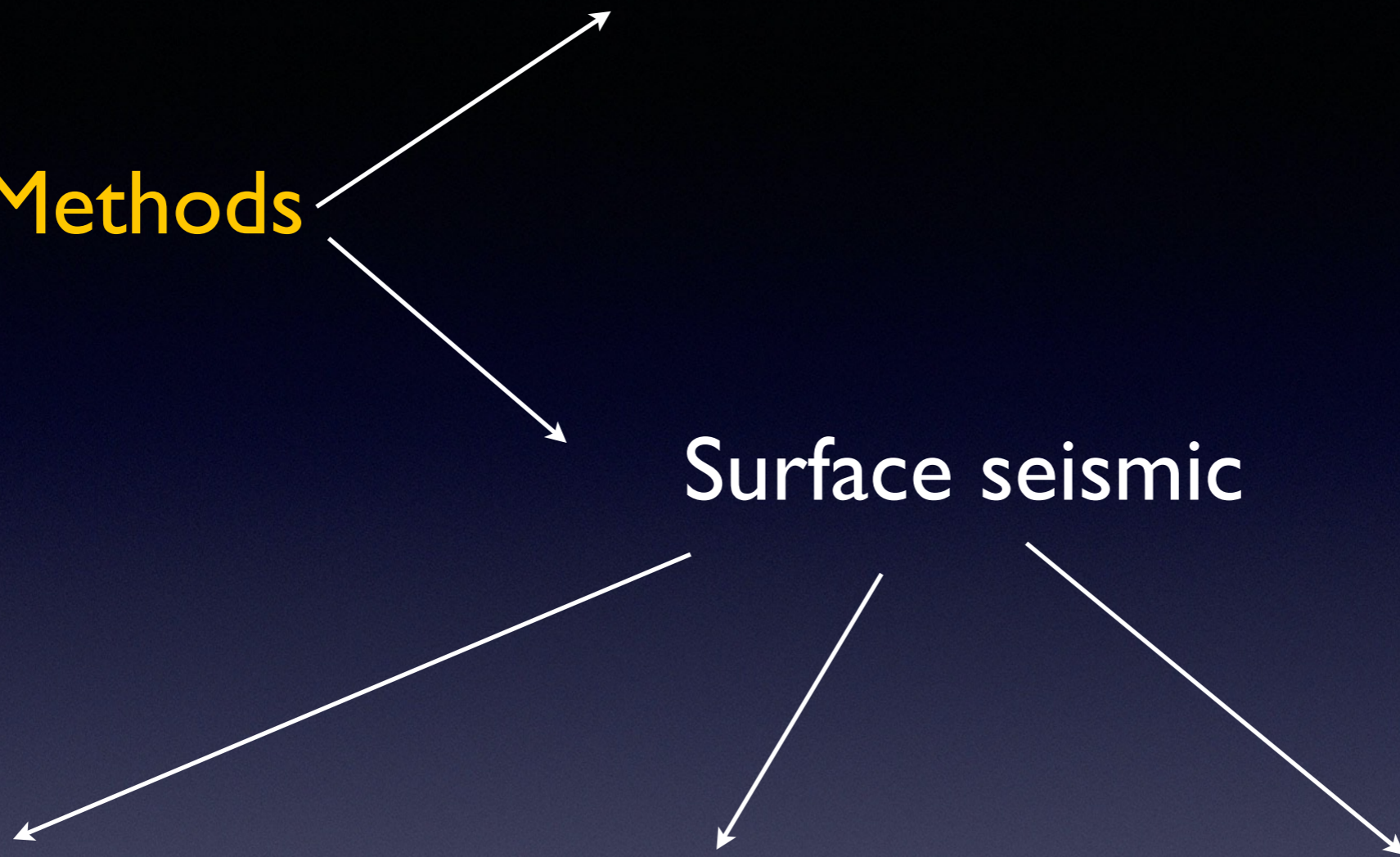
Seismic Methods

Surface seismic

Reflection
seismic

Refraction
seismic

Surface wave
seismic



Seismic Methods

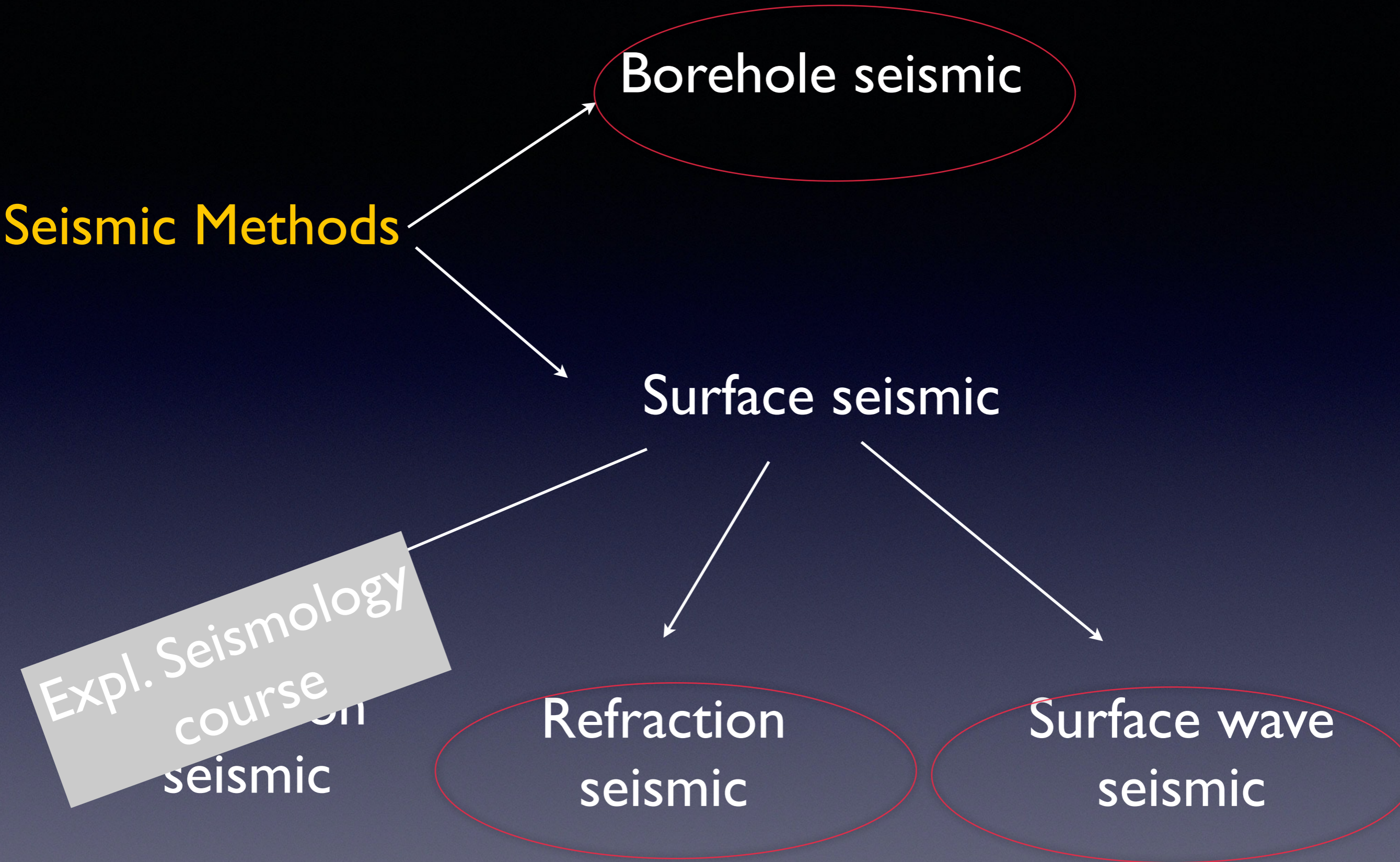
Borehole seismic

Surface seismic

Refraction seismic

Surface wave seismic

Expl. Seismology course on seismic

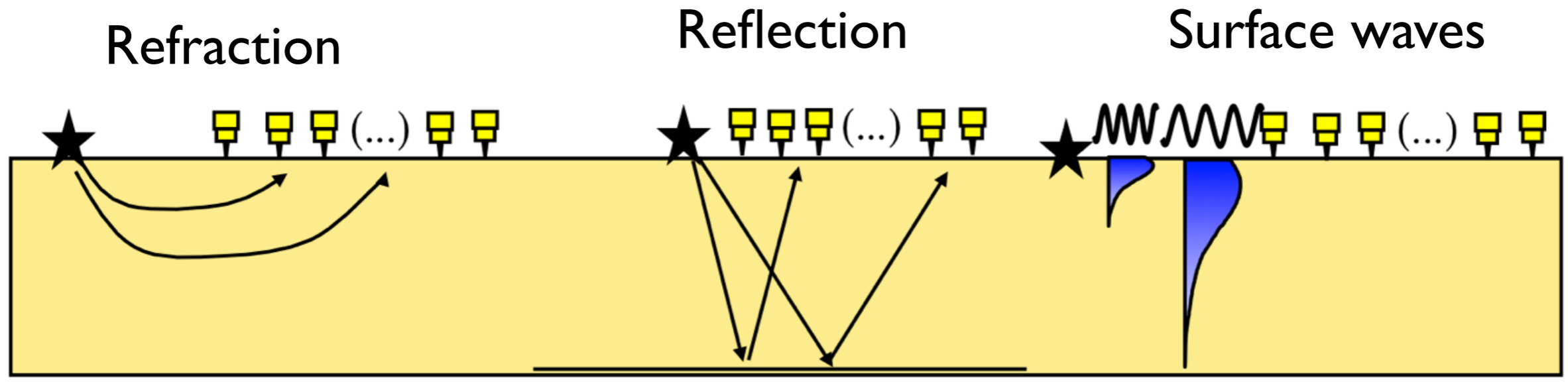
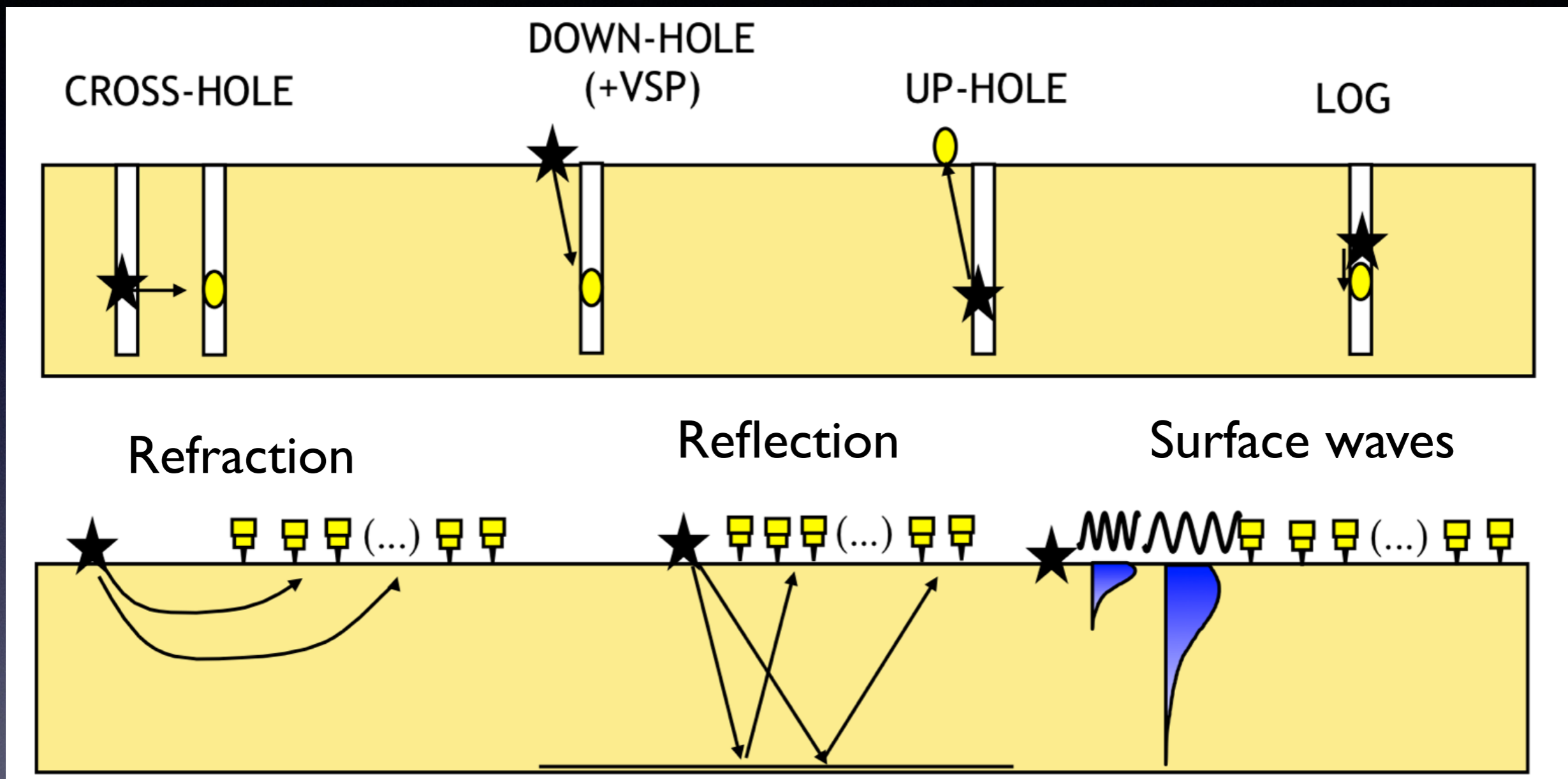


Seismic Methods

- Methods
- Equipments
- surveys design
- processing

Seismic Methods

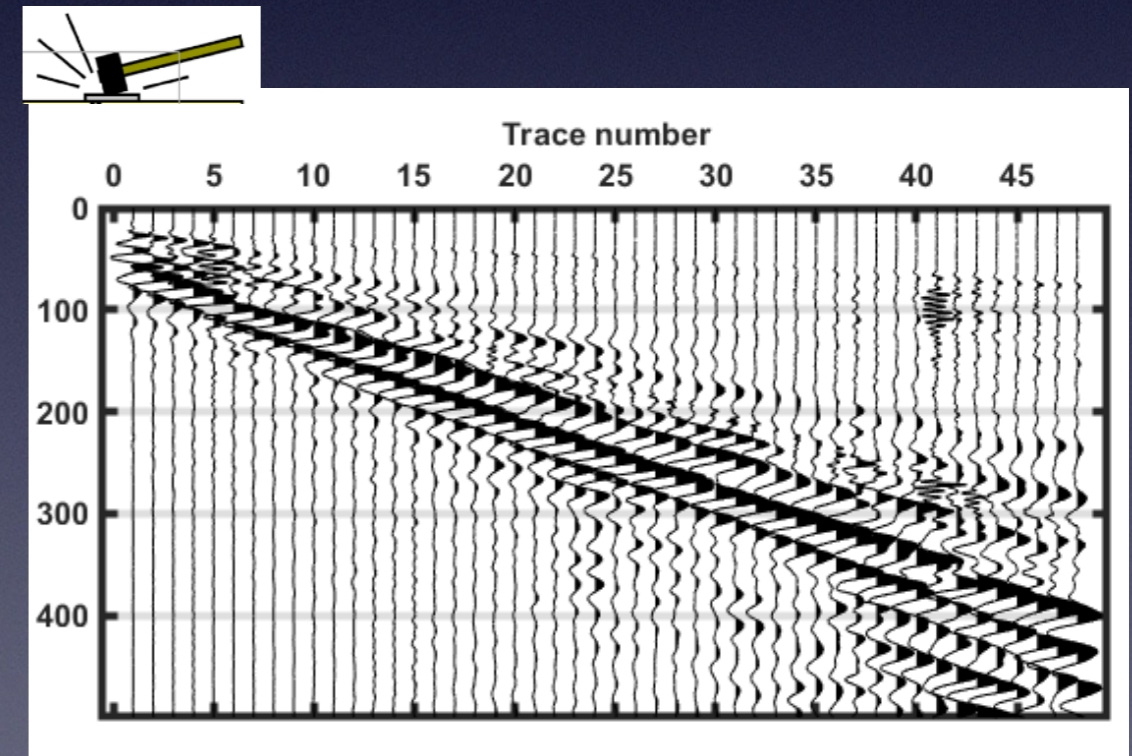
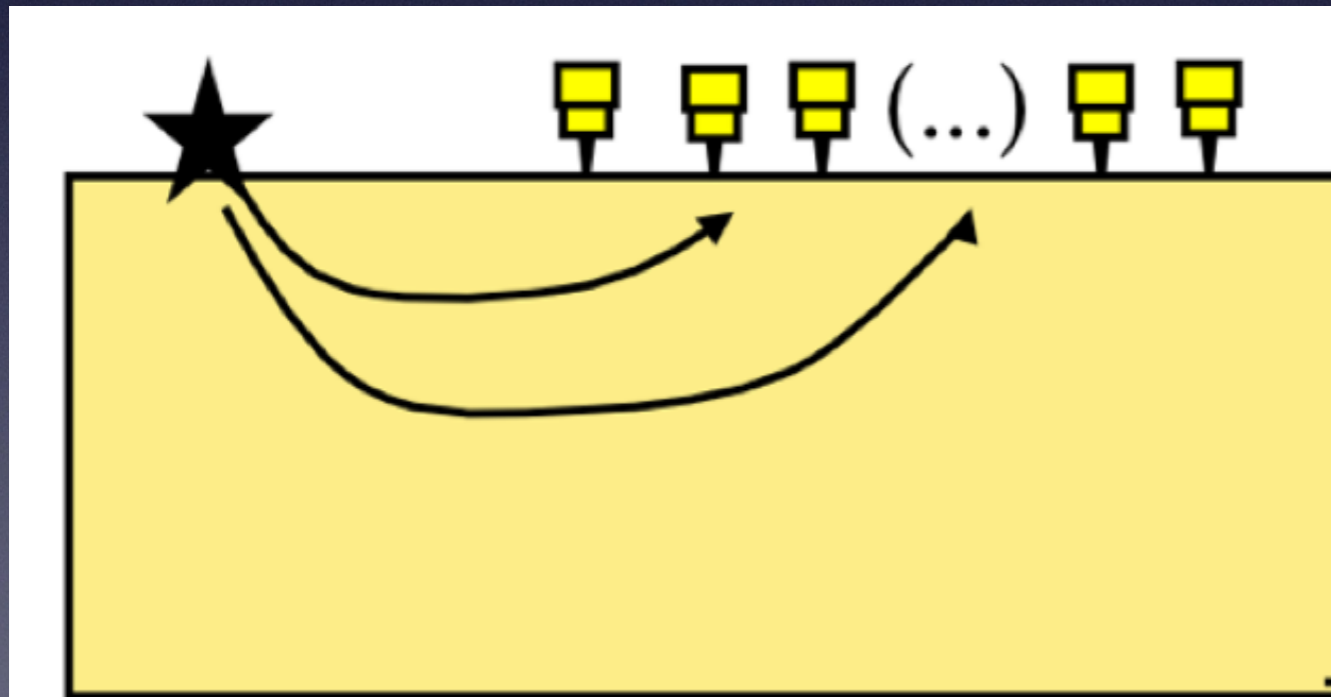
Borehole Seismic



Surface seismic

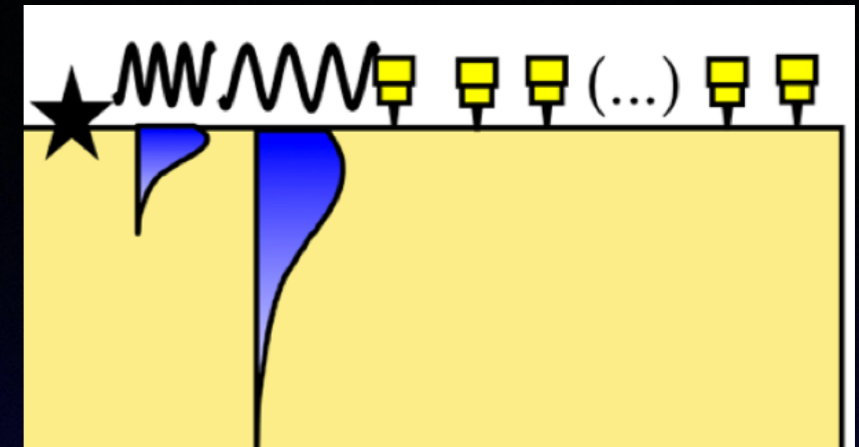
Surface methods

Energy and receivers on surface



Surface methods

Surface wave methods



Study the DISPERSION of surface wave d

To retrieve (indirectly) V_s

$$V_{s,30} = \frac{30}{\sum_{i=1,n} H_i / \underline{V_{s_i}}} \quad [m/s]$$

e.g. seismic soil
classification
parameter

Seismic method

wave motion - Wave equation

$u, v, w =$ displacement in x, y, z

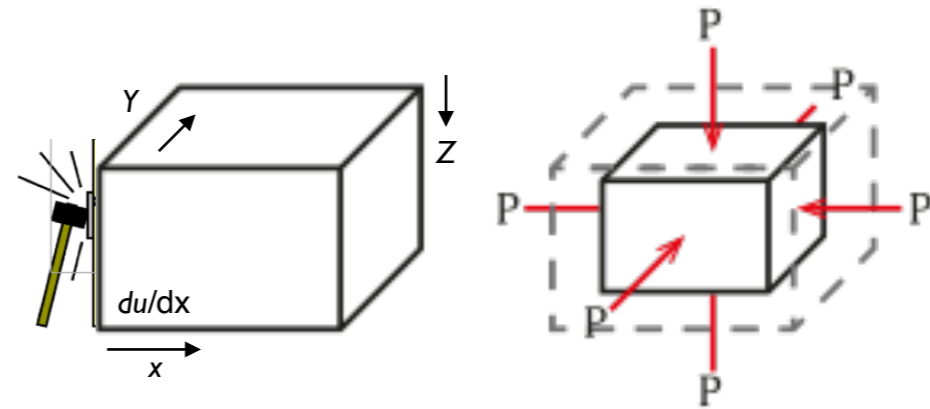
strain (ϵ) tensor

$$\epsilon_{xx} = du/dx$$

$$\epsilon_{yy} = dv/dy$$

$$\epsilon_{zz} = dw/dz$$

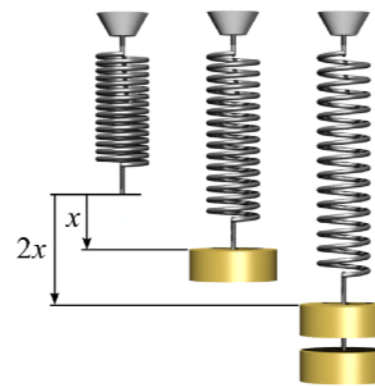
Stress-strain



...a relation between strain and stress...

Dilatation $\rightarrow \Delta = \epsilon_{xx} + \epsilon_{yy} + \epsilon_{zz}$

Hooke law (isotropic media)



Normal stress
(Example for x)

$$\sigma_x = \lambda \Delta + 2 \mu \epsilon_x \quad \text{for } x, y, z$$

Pure shear stress
(Example for y)

$$\sigma_y = \mu \epsilon_y \quad \text{for } i \neq j$$

lamè constant

λ	μ
compress.	Shear

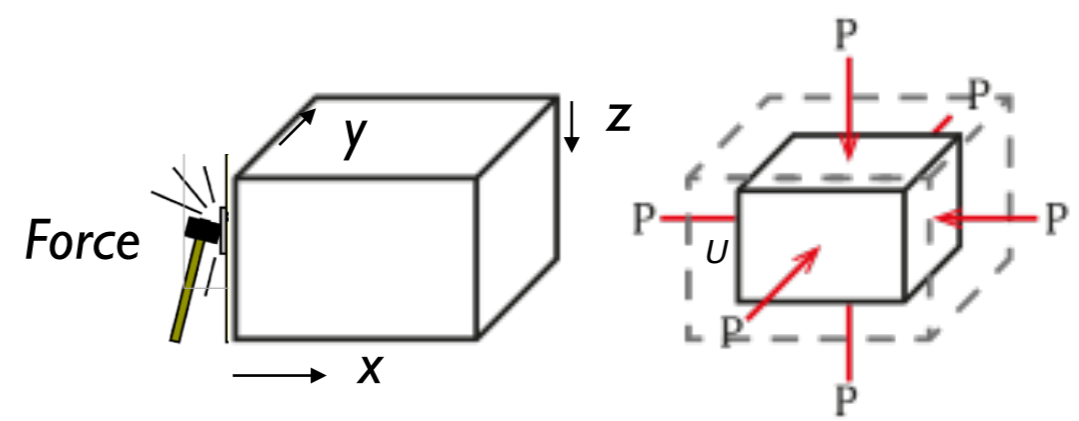
Seismic method wave motion - Wave equation

Mass of the cube $dm = \rho dx dy dz$ density

Newton Law $F = m \cdot a$

$$\rho \frac{d^2 u}{dt^2} = \frac{d\sigma_{xx}}{dx} + \frac{d\sigma_{xy}}{dy} + \frac{d\sigma_{xz}}{dz}$$

stress



Displacement u

Hooke law

$$\rho \frac{d^2 u}{dt^2} = (\lambda + \mu) \frac{d\Delta}{dx} + \mu \Delta^2 u$$

dilatation

diff for x, y, z

Lame parameters

Dilatation

$$\rho \frac{d^2 \Delta}{dt^2} = (\lambda + 2\mu) \nabla^2 \Delta$$

laplacian

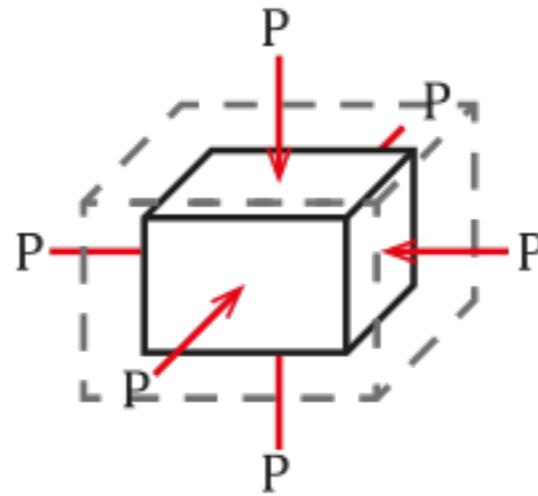
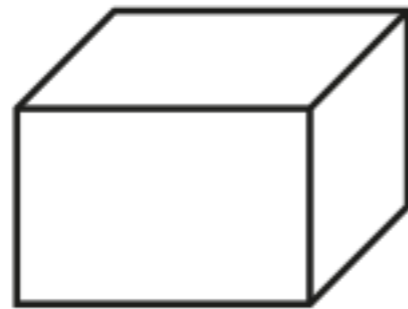
Wave Equation !

Lame parameters

In seismic are most used the compressibility modulus

*Bulk modulus **K** (rather than λ)*

*The increment in pressure need to cause
an increase of density*



$$K = \lambda + \left(\frac{2}{3} G \right)$$

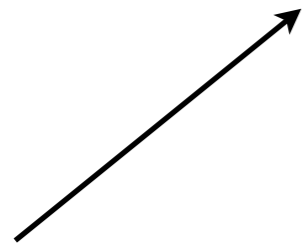
*And shear modulus expressed as **G** (rather than μ)*

$$G = \mu$$

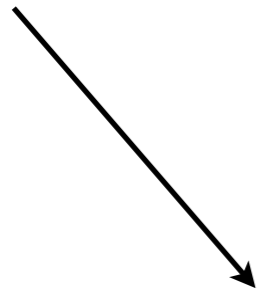
Seismic method

wave motion - Wave equation

Compressional wave
(P waves)



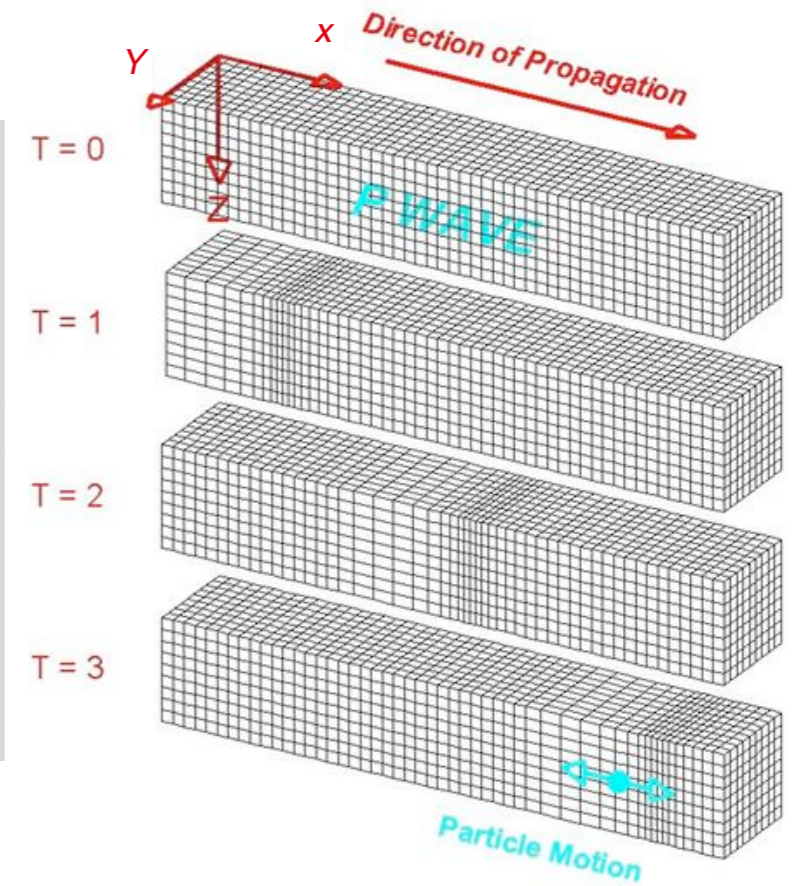
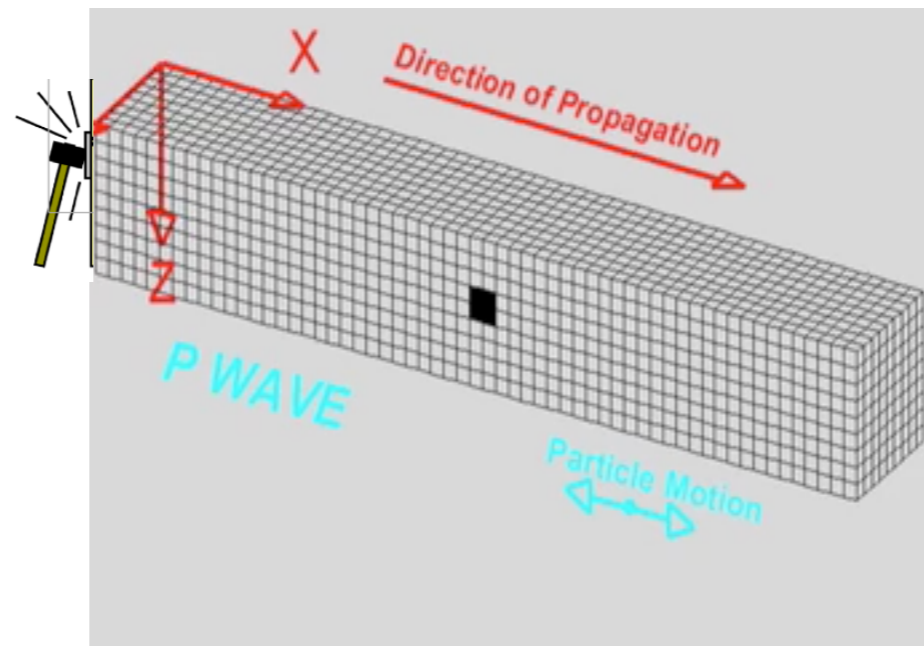
BODY WAVES



Shear waves
(S wave)

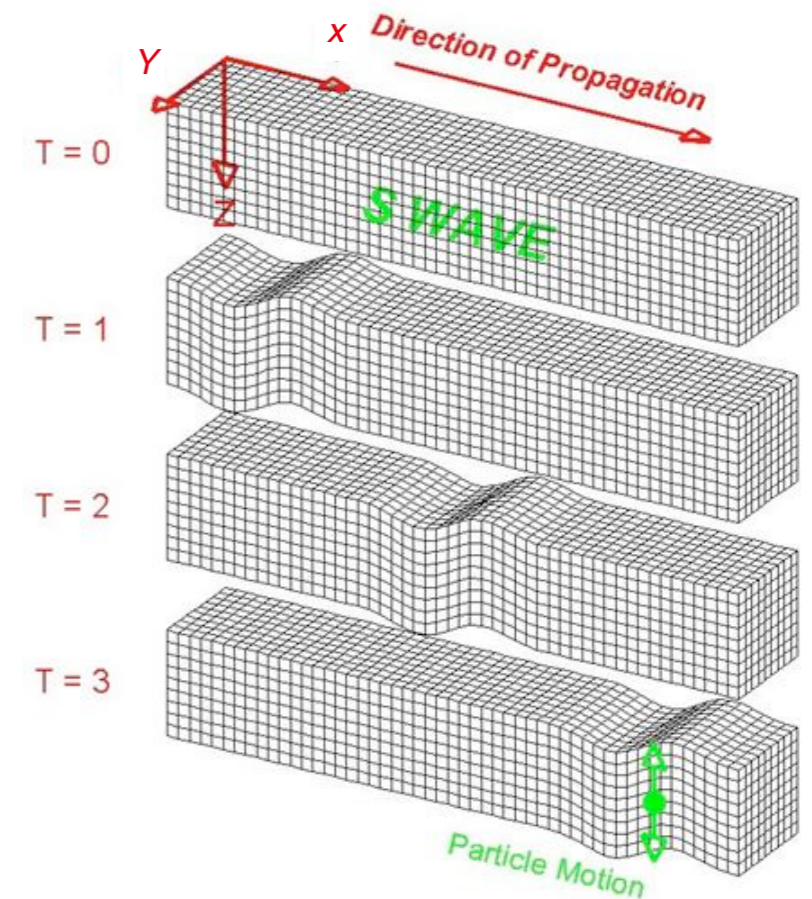
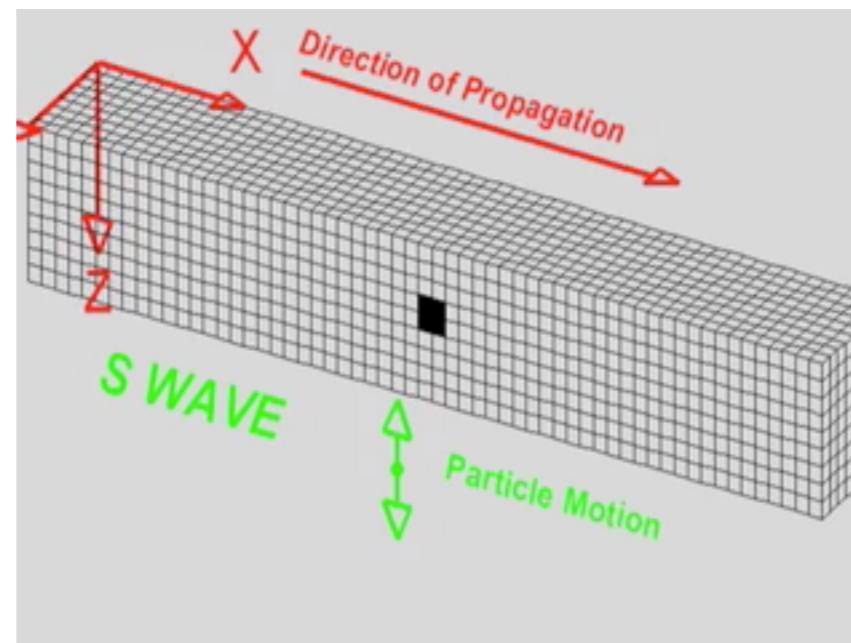
volumetric deformation

ϵ



shear deformation

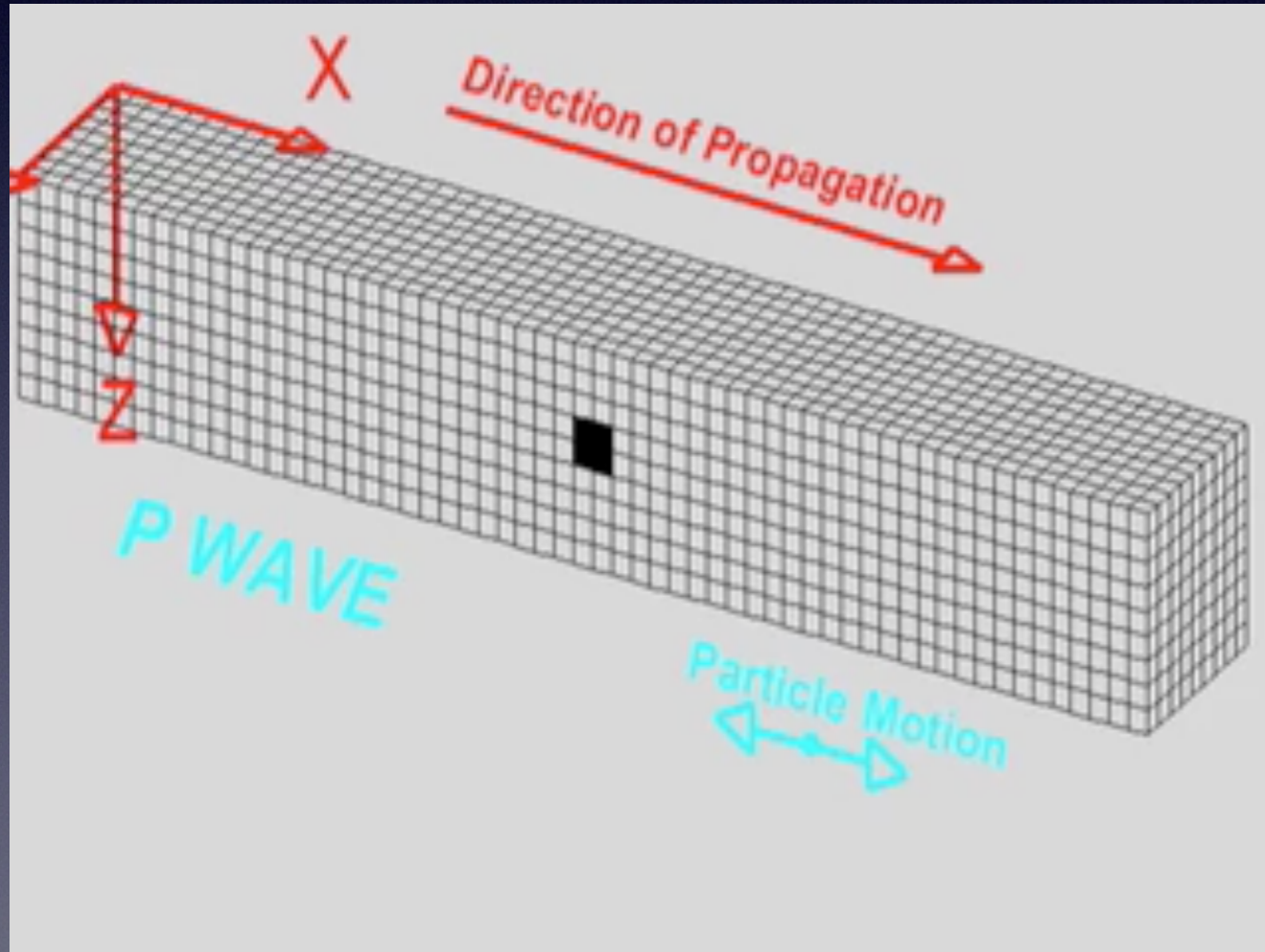
Ω



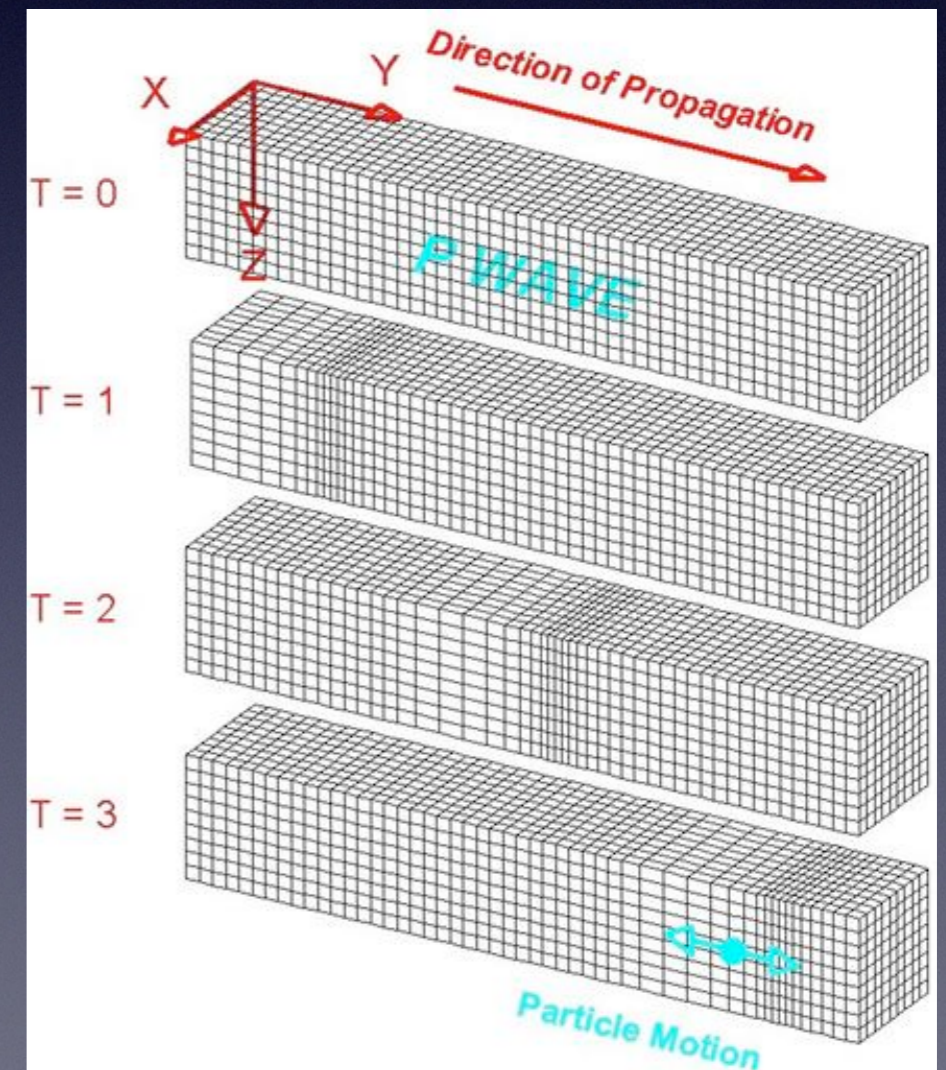
P

P-waves

Compressional wave
(onde P)



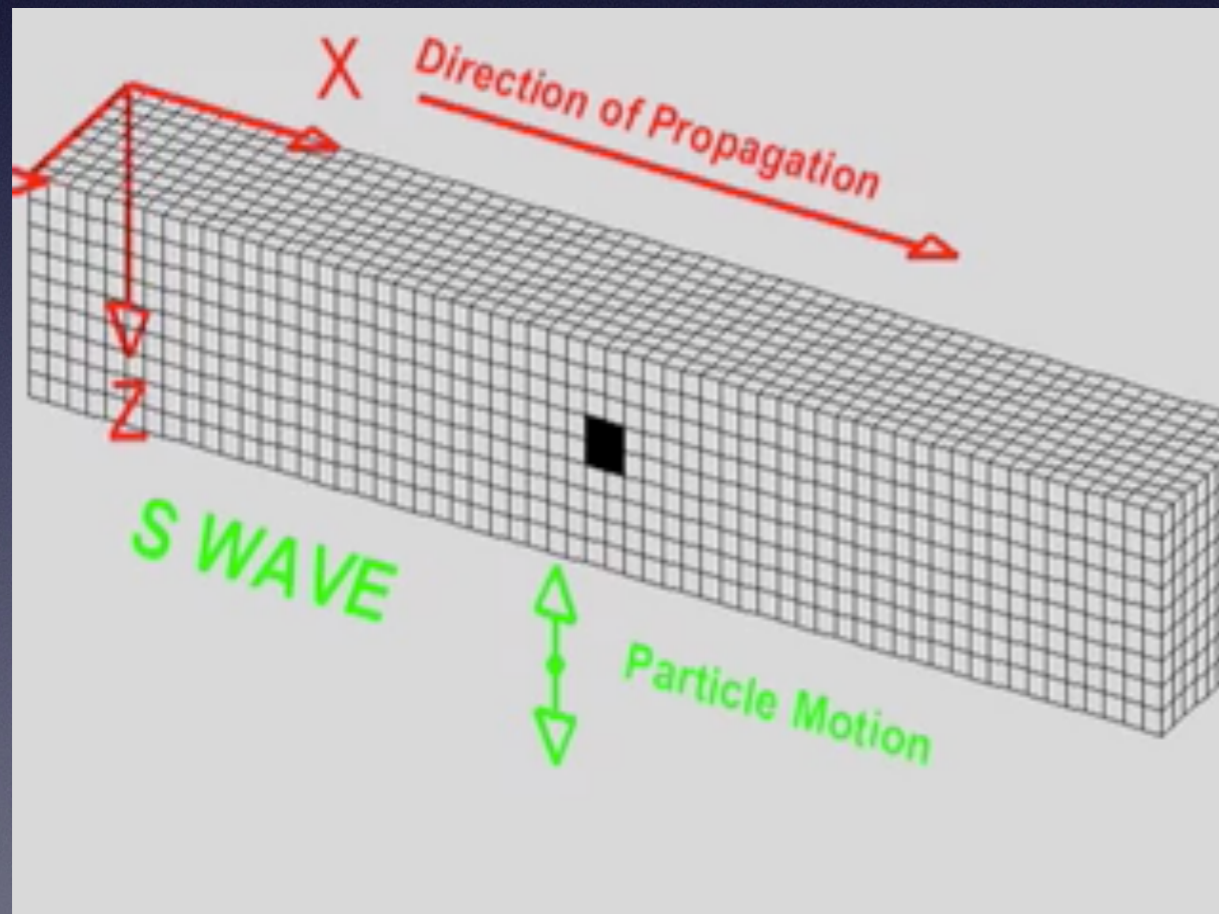
Volumetric deformation ϵ



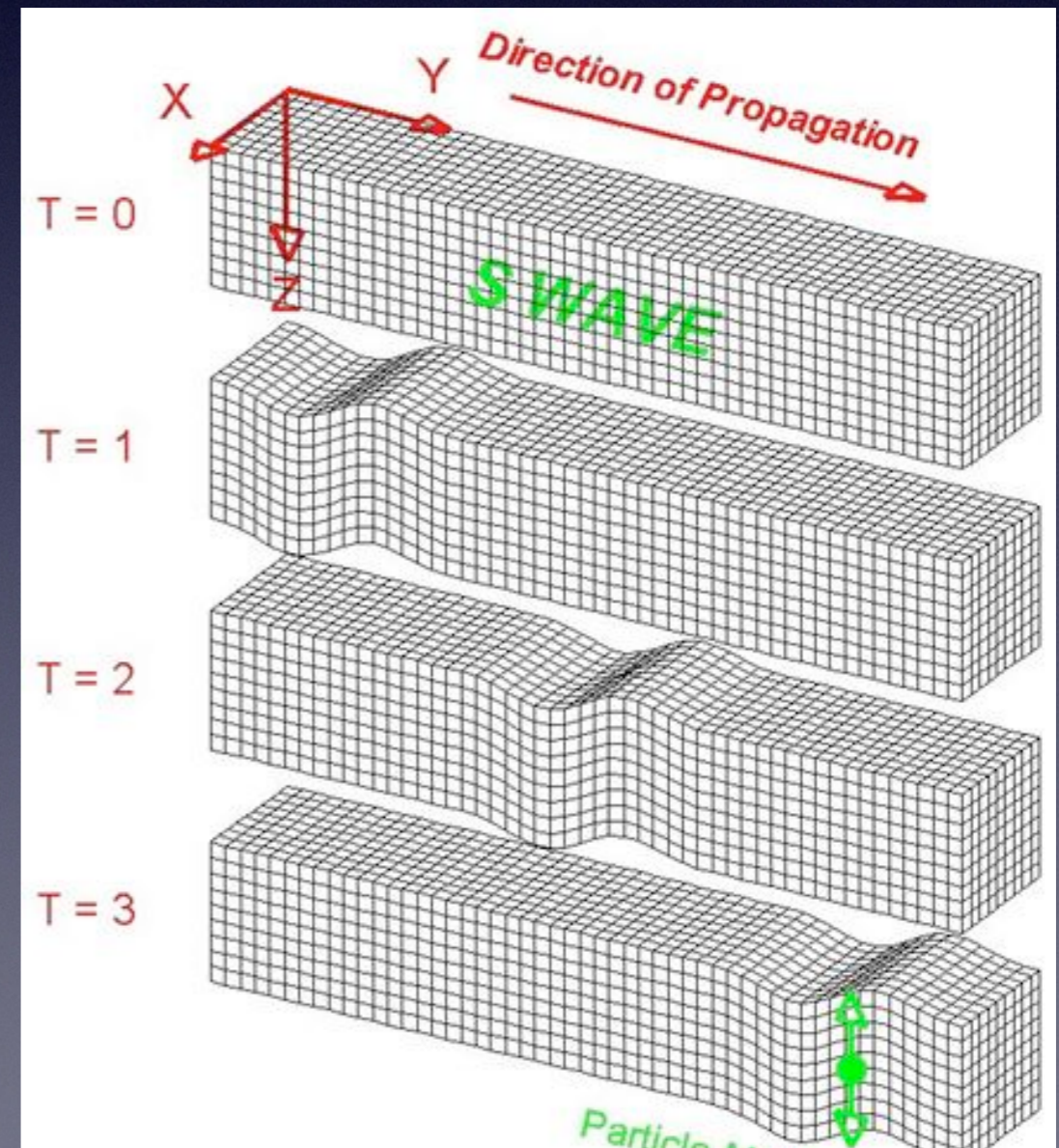
S

S-waves

Shear wave



Tangential deformation Ω



Wave propagation in homogenous, elastic, isotrope media

Body waves

Solution of differential wave equation

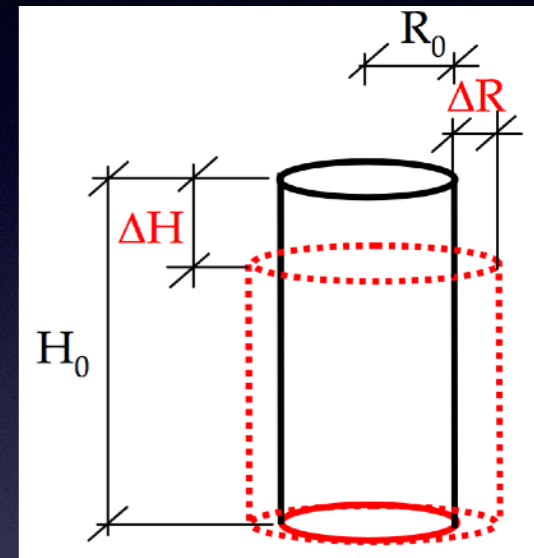
P wave

$$\frac{\partial^2 \bar{\varepsilon}}{\partial t^2} = \frac{\lambda + 2G}{\rho} \nabla^2 \bar{\varepsilon}$$

Volumetric deformation (strain)

$$\varepsilon = \frac{\Delta V}{V_0}$$

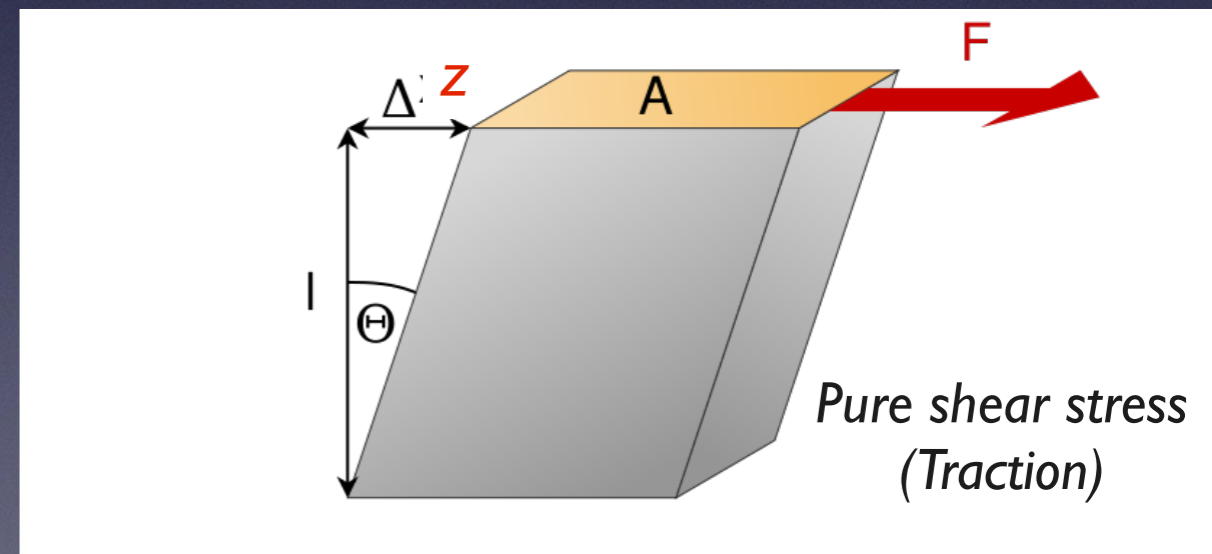
dVolume
Volume Iniziale



S wave

$$\frac{\partial^2 \Omega}{\partial t^2} = \frac{G}{\rho} \cdot \nabla^2 \Omega$$

Tangential deformation Ω



G = shear modulus
 λ = compression modulus
 ρ = density

Wave propagation in homogenous, elastic , isotrope media

Solution of differential wave equation

$$\rho \frac{d^2 \Delta}{dt^2} = (\lambda + 2G) \nabla^2 \Delta$$

P wave

$$\frac{\partial^2 \bar{\varepsilon}}{\partial t^2} = \frac{\lambda + 2G}{\rho} \nabla^2 \bar{\varepsilon}$$

Relationship

$$\frac{\partial^2 \bar{\varepsilon}}{\partial t^2} = [\text{velocity of propagation}] \nabla^2 \bar{\varepsilon}$$

S wave

$$\frac{\partial^2 \Omega_z}{\partial t^2} = \frac{G}{\rho} \nabla^2 \Omega_z$$

Relationship

$$\frac{\partial^2 \Omega_x}{\partial t^2} = [\text{velocity of propagation}] \nabla^2 \Omega_x$$

Wave propagation in homogenous, elastic , isotrope media

Solution of differential wave equation

P wave

$$\frac{\partial^2 \bar{\varepsilon}}{\partial t^2} = \frac{\lambda + 2G}{\rho} \nabla^2 \bar{\varepsilon}$$

V_P^2  Velocity of
Propagation P wave

$$V_P = \sqrt{\frac{\lambda + 2G}{\rho}}$$

S wave

$$\frac{\partial^2 \Omega_z}{\partial t^2} = \frac{G}{\rho} \nabla^2 \Omega_z$$

V_S^2  Velocity of
Propagation S wave

$$V_S = \sqrt{\frac{G}{\rho}}$$

**In
liquids**
 $G = 0$
 $V_S = 0$

Body wave

P Wave

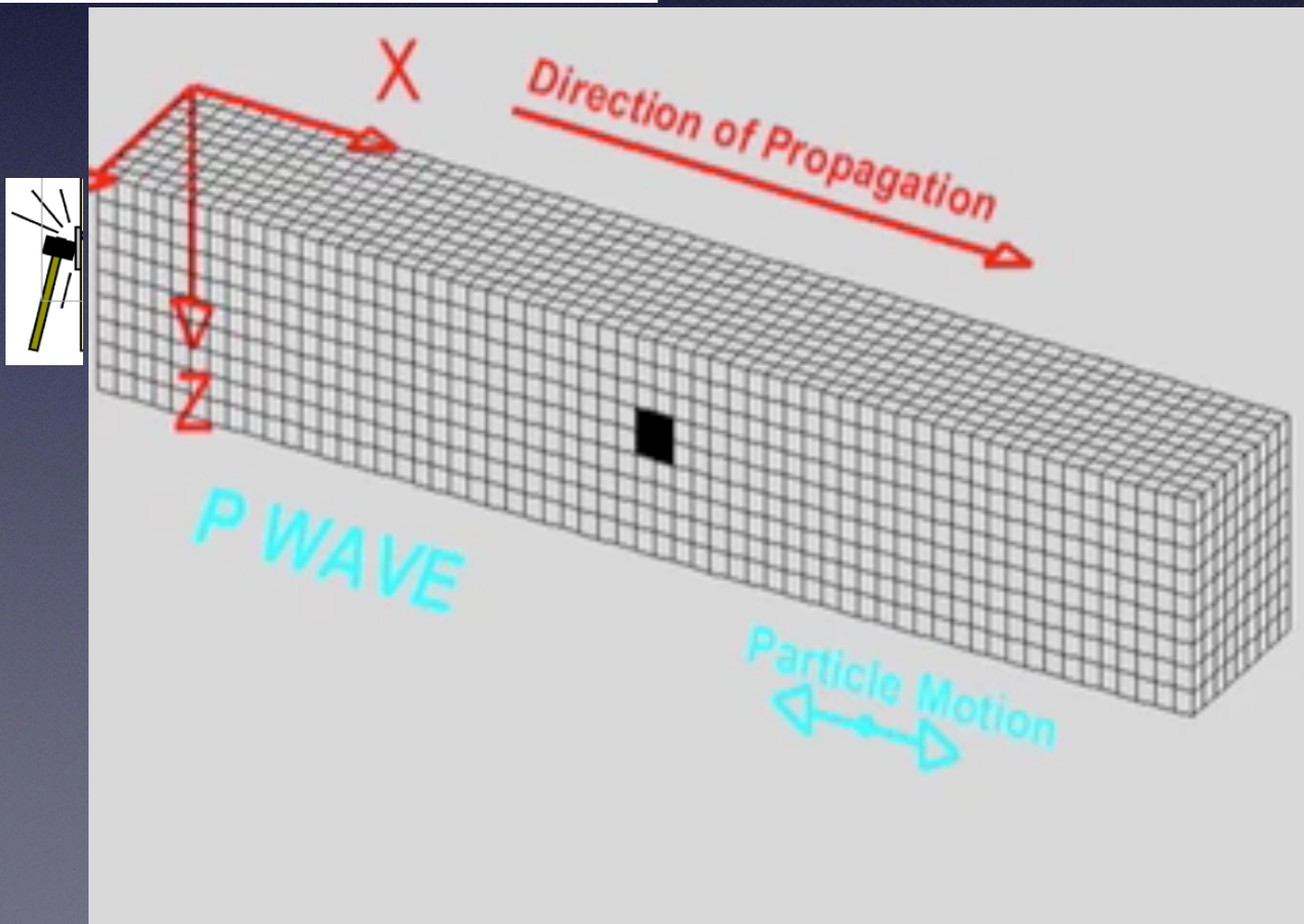
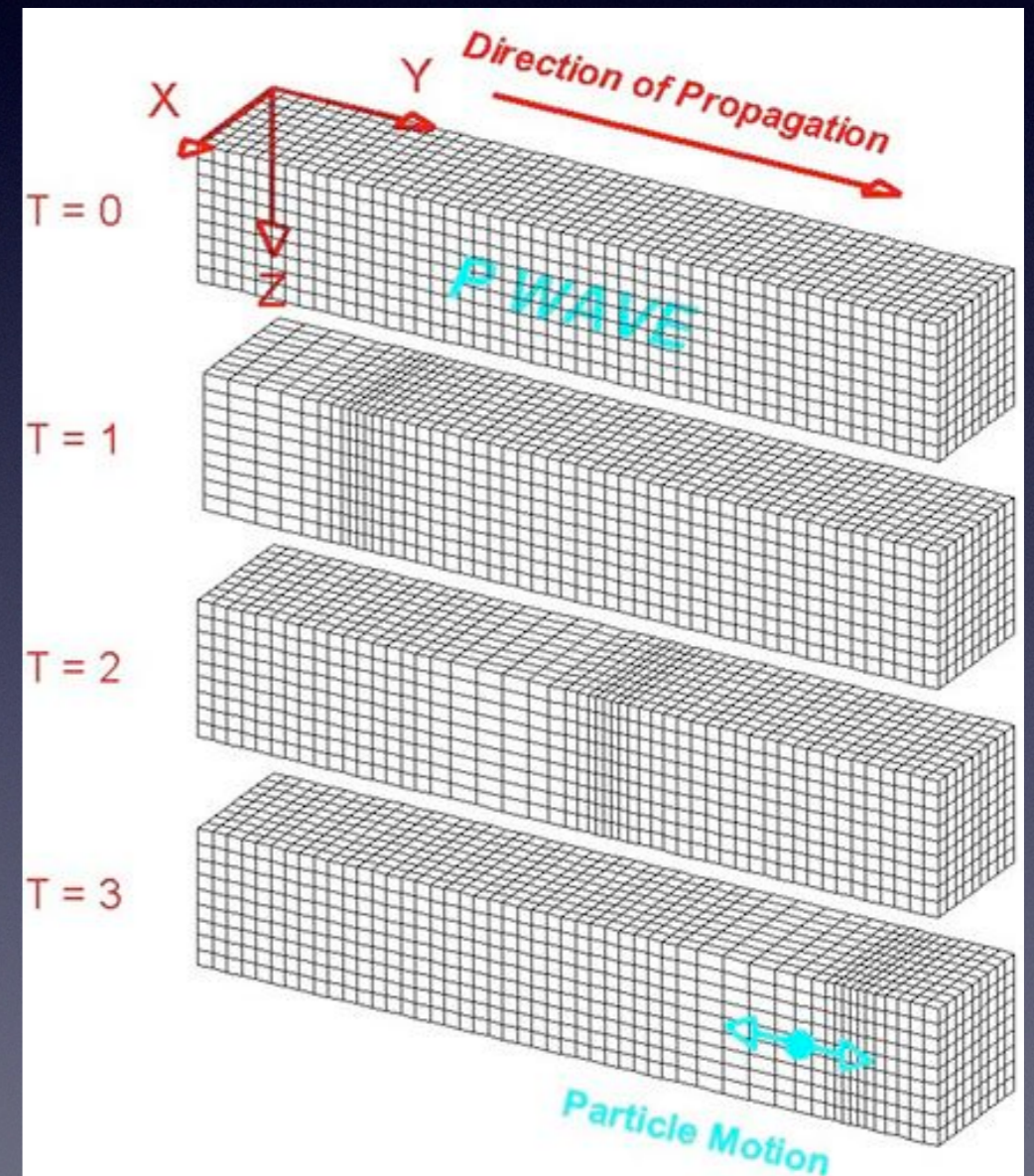
Compression and dilatation

Compressibility

$$V_P = \sqrt{\frac{\lambda + 2G}{\rho}}$$

Shear modulus

density



Body waves

S waves

Shear waves

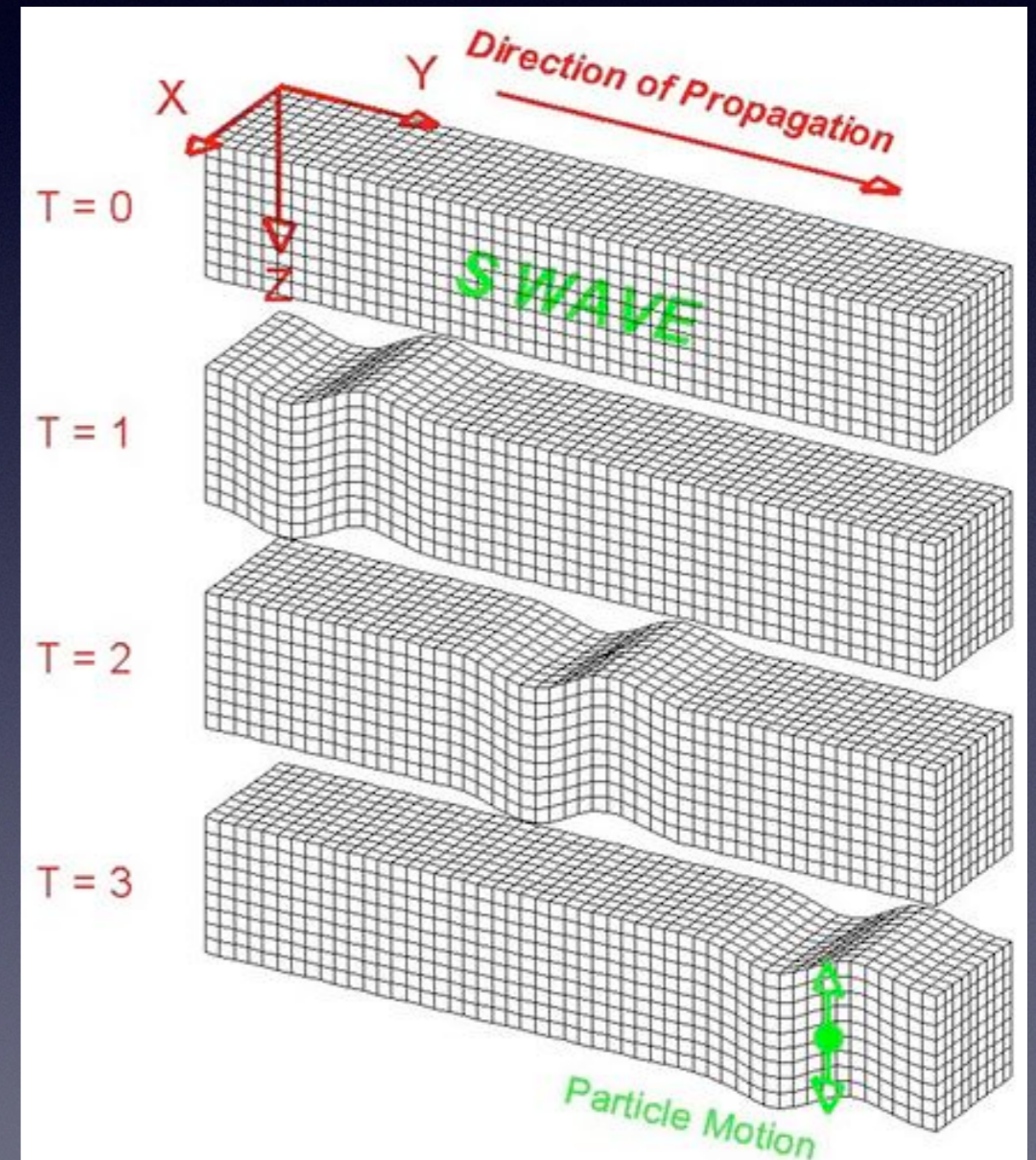
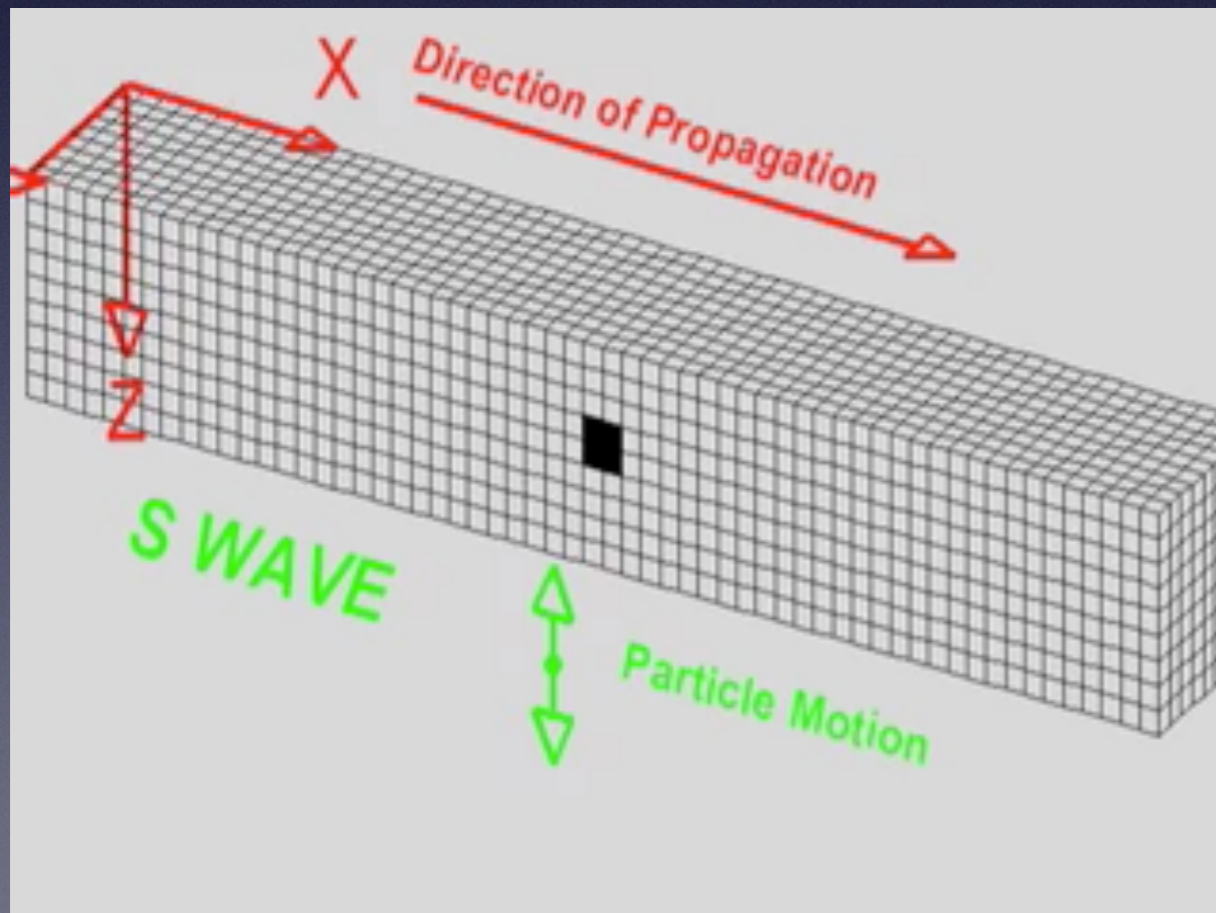
In fluids

$$G = 0$$

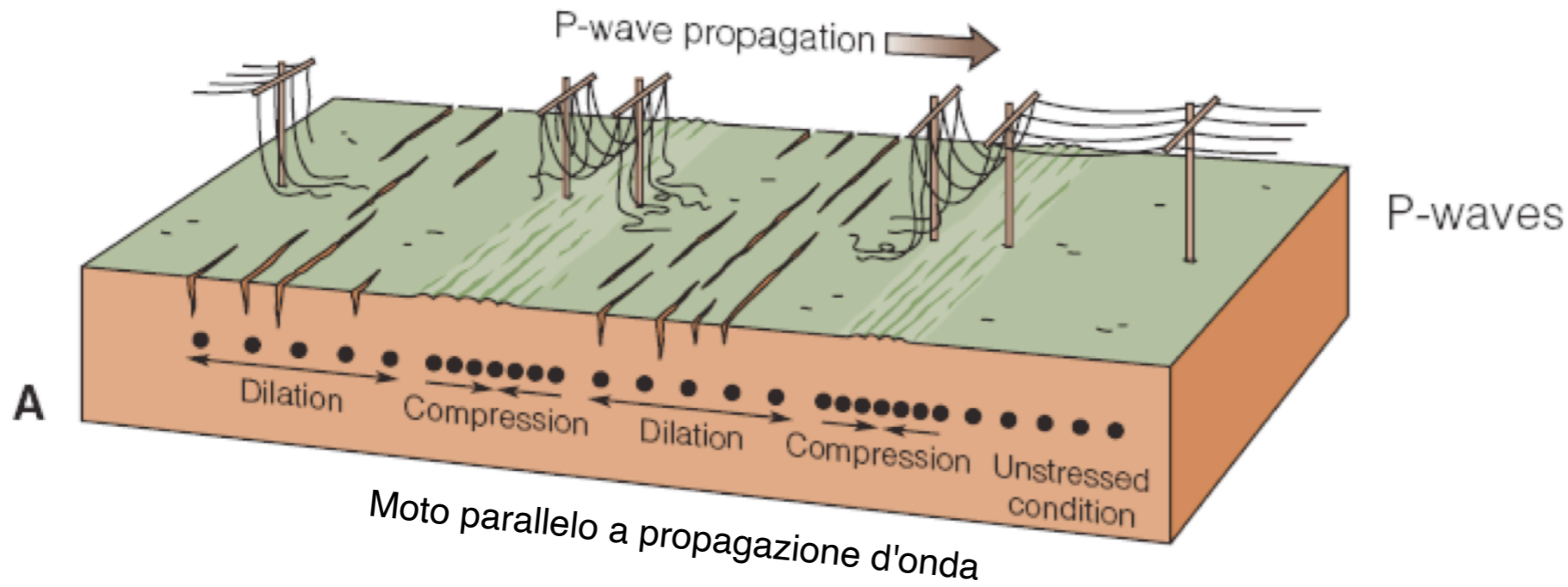
$$V_s = 0$$

$$V_s = \sqrt{\frac{G}{\rho}}$$

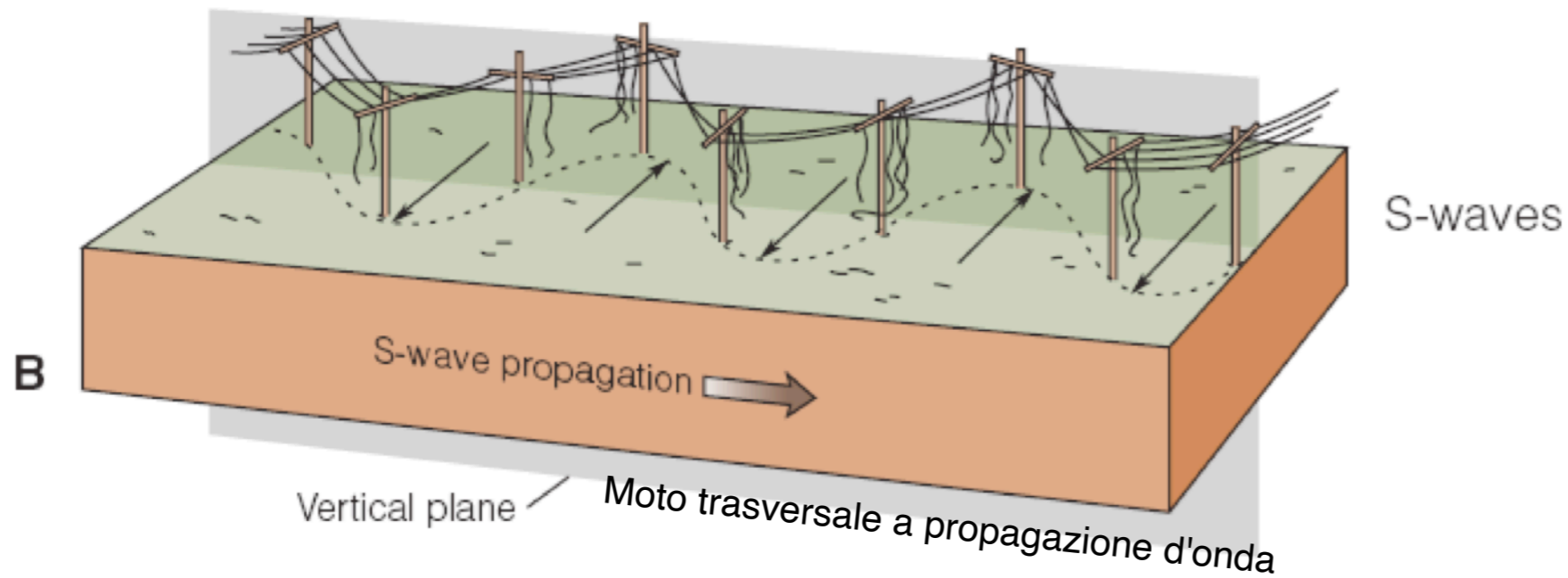
Shear modulus
NB not dependent
on compressibility!
density



Seismic waves



P
compressional



S
Shear

P Velocity ≈ 1.9 S velocity

Type of formation	P wave velocity (m/s)	S wave velocity (m/s)	Density (g/cm ³)	Density of constituent crystal (g/cm ³)
Scree, vegetal soil	300-700	100-300	1.7-2.4	-
Dry sands	400-1200	100-500	1.5-1.7	2.65 quartz
Wet sands	1500-2000	400-600	1.9-2.1	2.65 quartz
Saturated shales and clays	1100-2500	200-800	2.0-2.4	-
Marls	2000-3000	750-1500	2.1-2.6	-
Saturated shale and sand sections	1500-2200	500-750	2.1-2.4	-
Porous and saturated sandstones	2000-3500	800-1800	2.1-2.4	2.65 quartz
Limestones	3500-6000	2000-3300	2.4-2.7	2.71 calcite
Chalk	2300-2600	1100-1300	1.8-3.1	2.71 calcite
Salt	4500-5500	2500-3100	2.1-2.3	2.1 halite
Anhydrite	4000-5500	2200-3100	2.9-3.0	-
Dolomite	3500-6500	1900-3600	2.5-2.9	(Ca, Mg) CO ₃ 2.8-2.9
Granite	4500-6000	2500-3300	2.5-2.7	-
Basalt	5000-6000	2800-3400	2.7-3.1	-
Gneiss	4400-5200	2700-3200	2.5-2.7	-
Coal	2200-2700	1000-1400	1.3-1.8	-
Water	1450-1500	-	1.0	-
Ice	3400-3800	1700-1900	0.9	-
Oil	1200-1250	-	0.6-0.9	-

Surface waves

For constructive interference at the boundary with air

2 types: Rayleigh waves
Love waves

Differently from body waves (3d) they propagate in 2d,
Attenuation is less f(distance r) :

$$r^{-0.5}$$

Rather than

$$r^{-1}$$

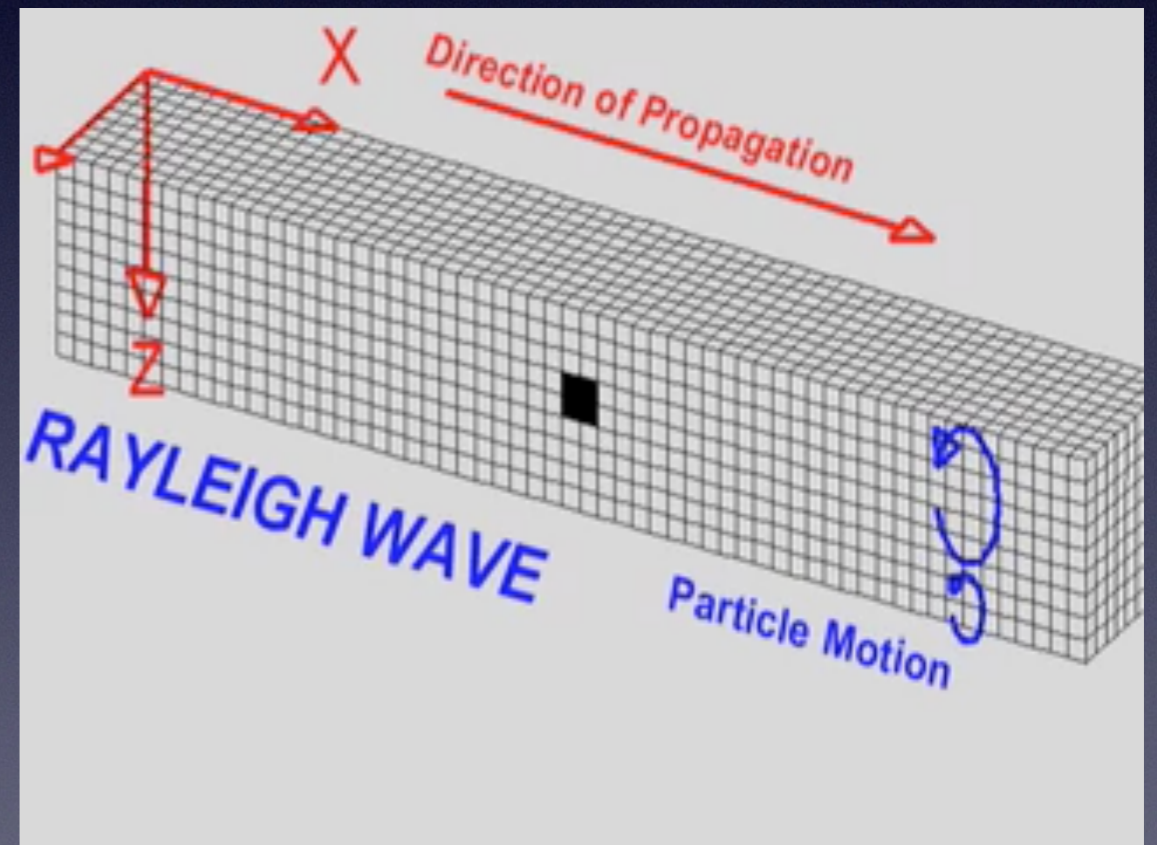
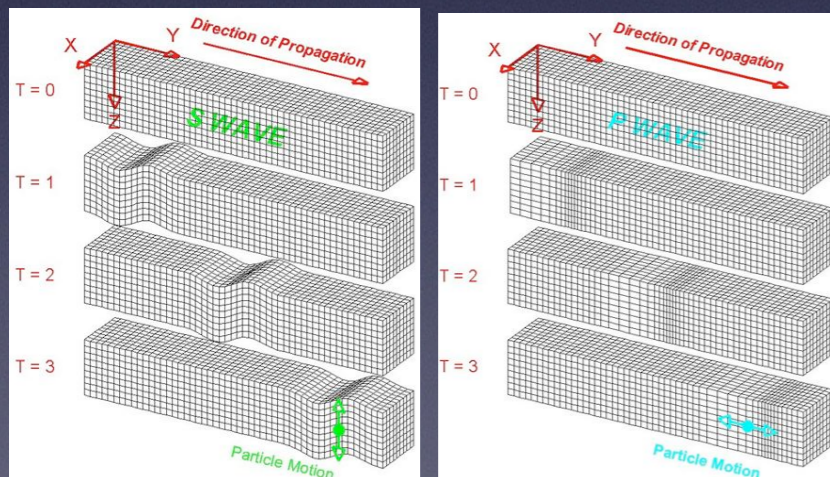
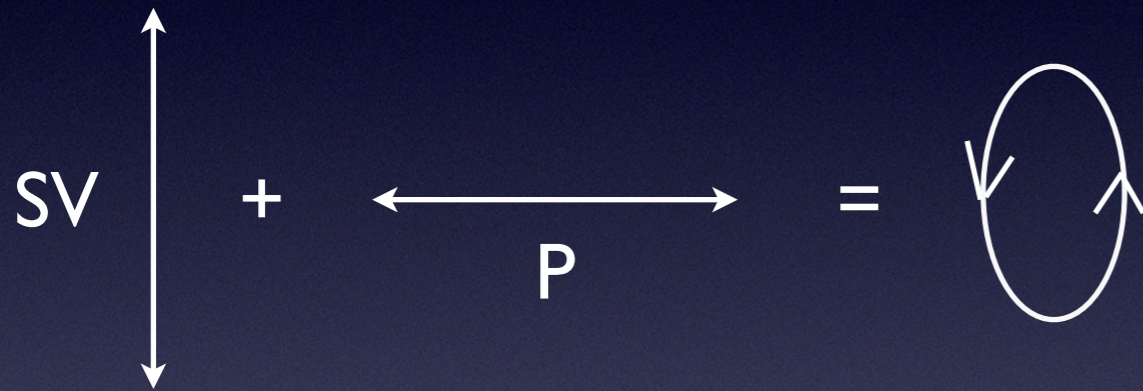
Surface waves

body waves

Rayleigh waves are mostly adopted

Generated from P and SV waves interference at surface

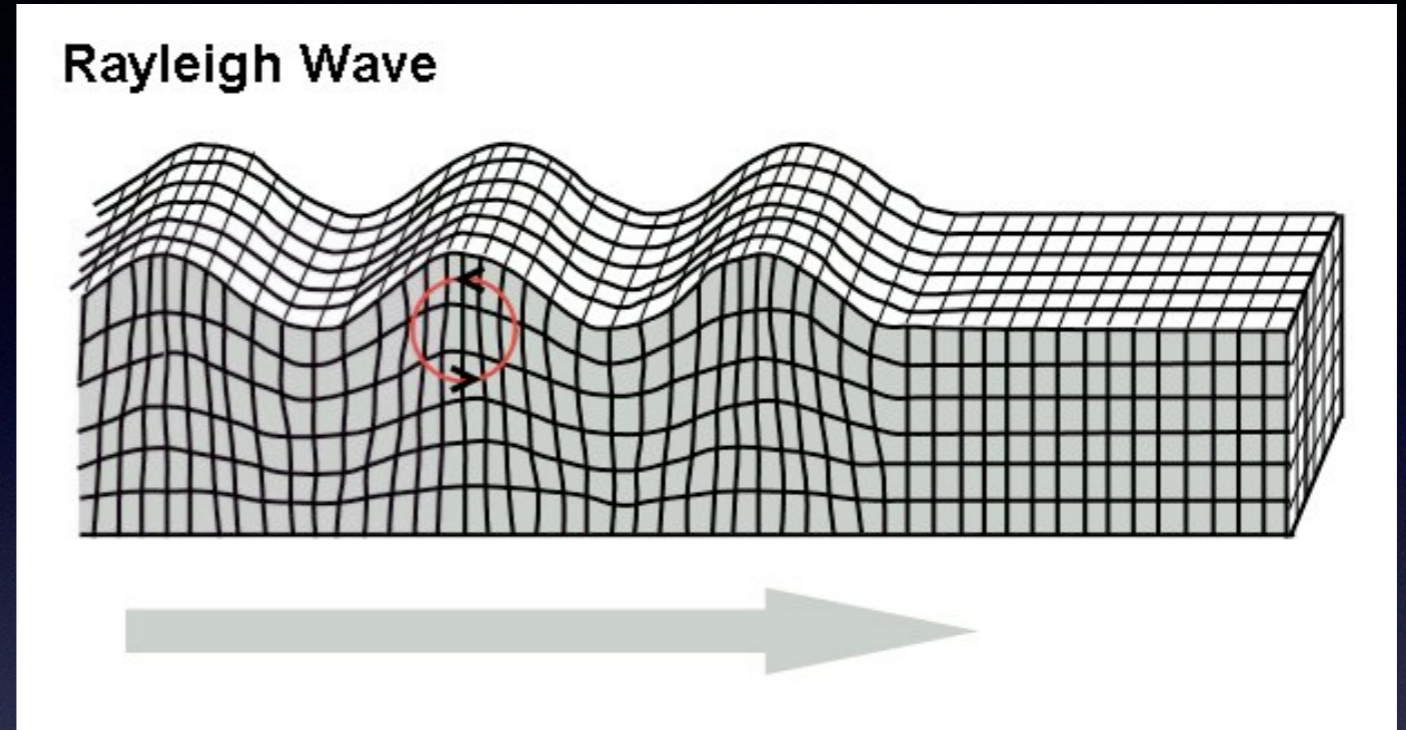
SV = S wave vertically polarised



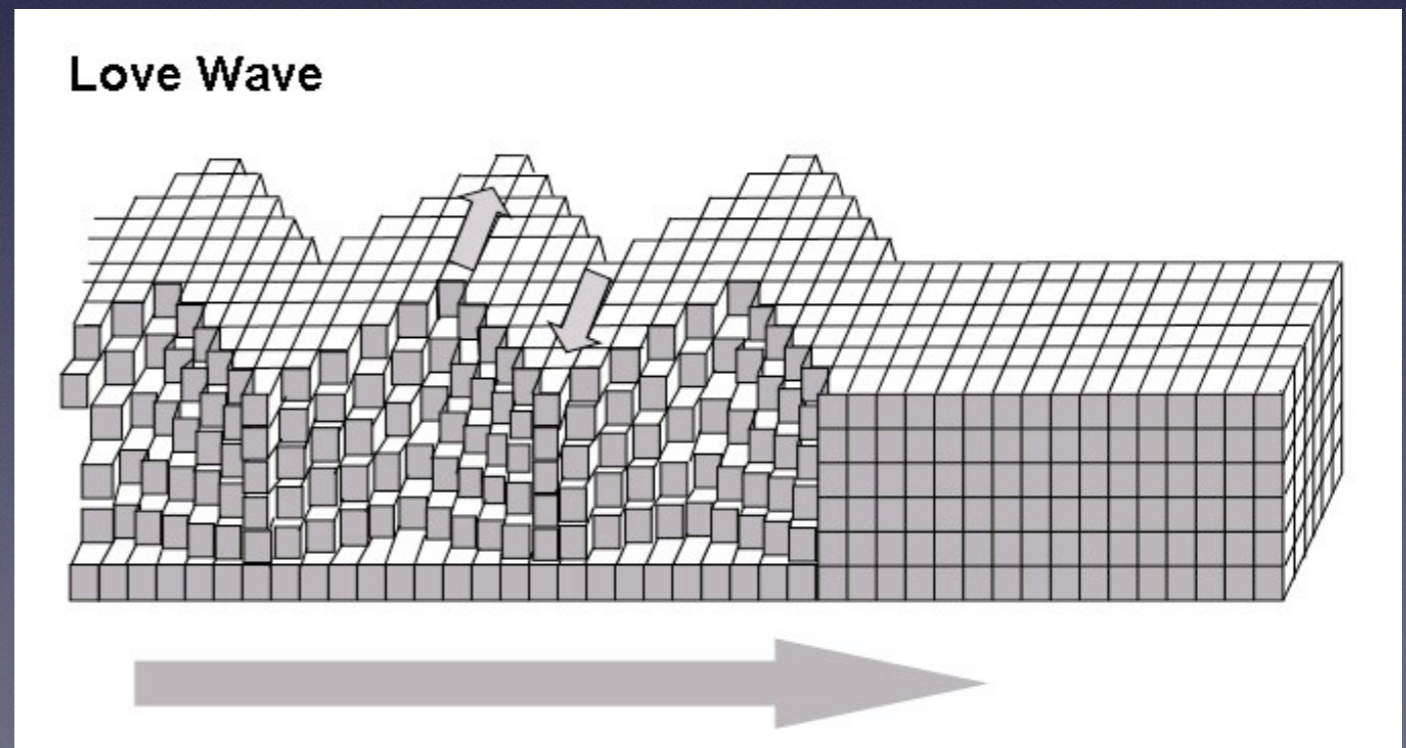
- Motus is elliptical

Surface waves

Rayleigh waves



Love waves



Seismic waves



P waves
(Compressional)

S wave
(Shear)

Rayleigh waves

Love waves
(S wave polarised in surface)



Body waves

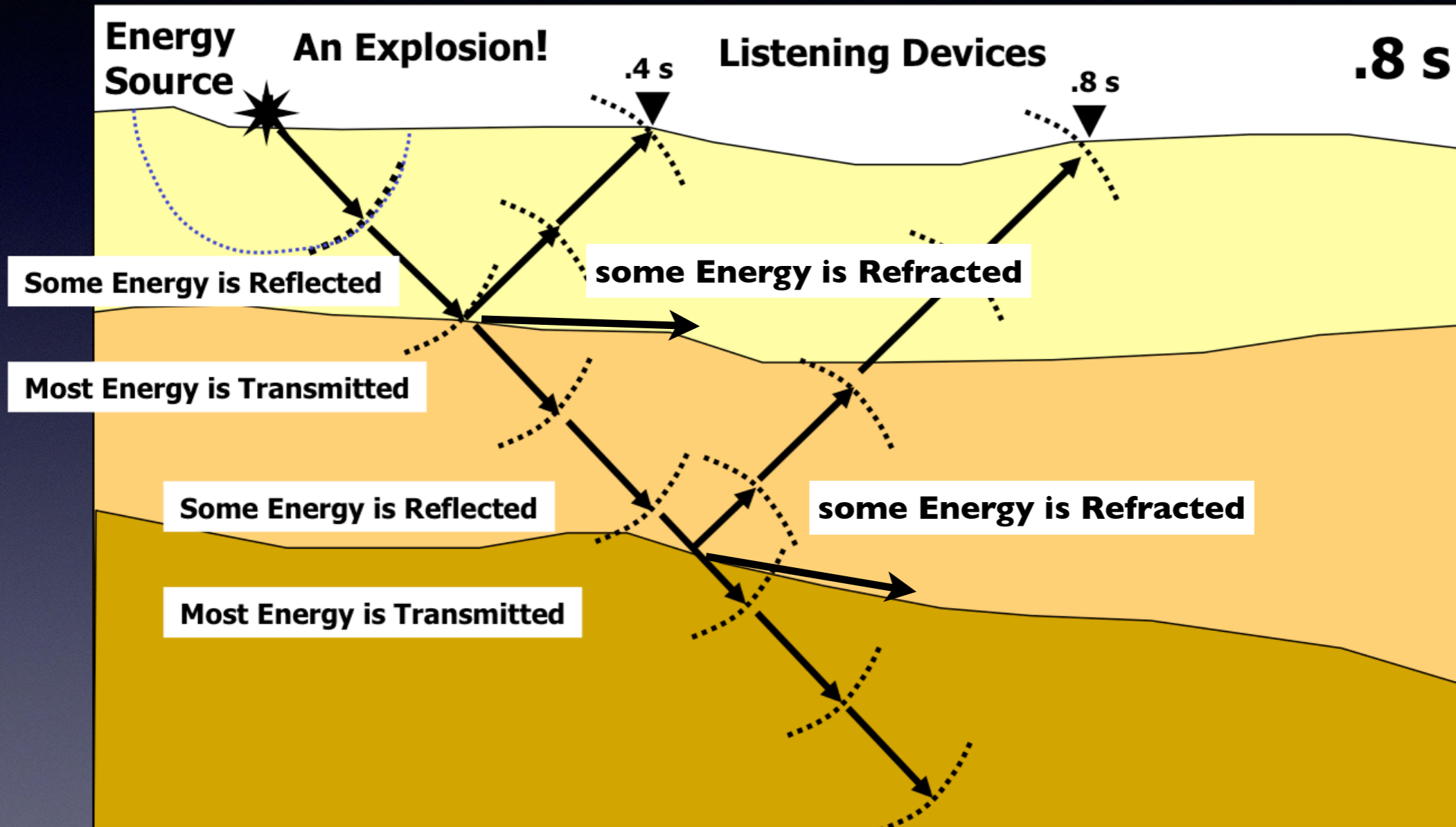


Surface waves

Seismic method

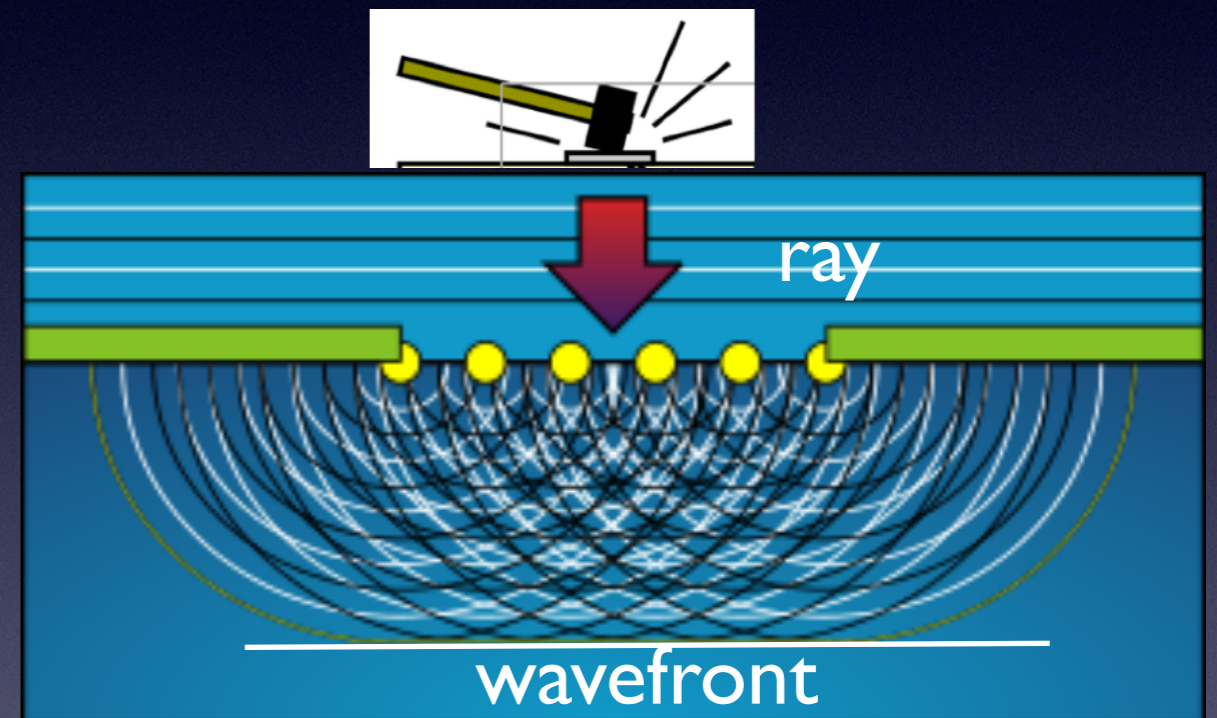
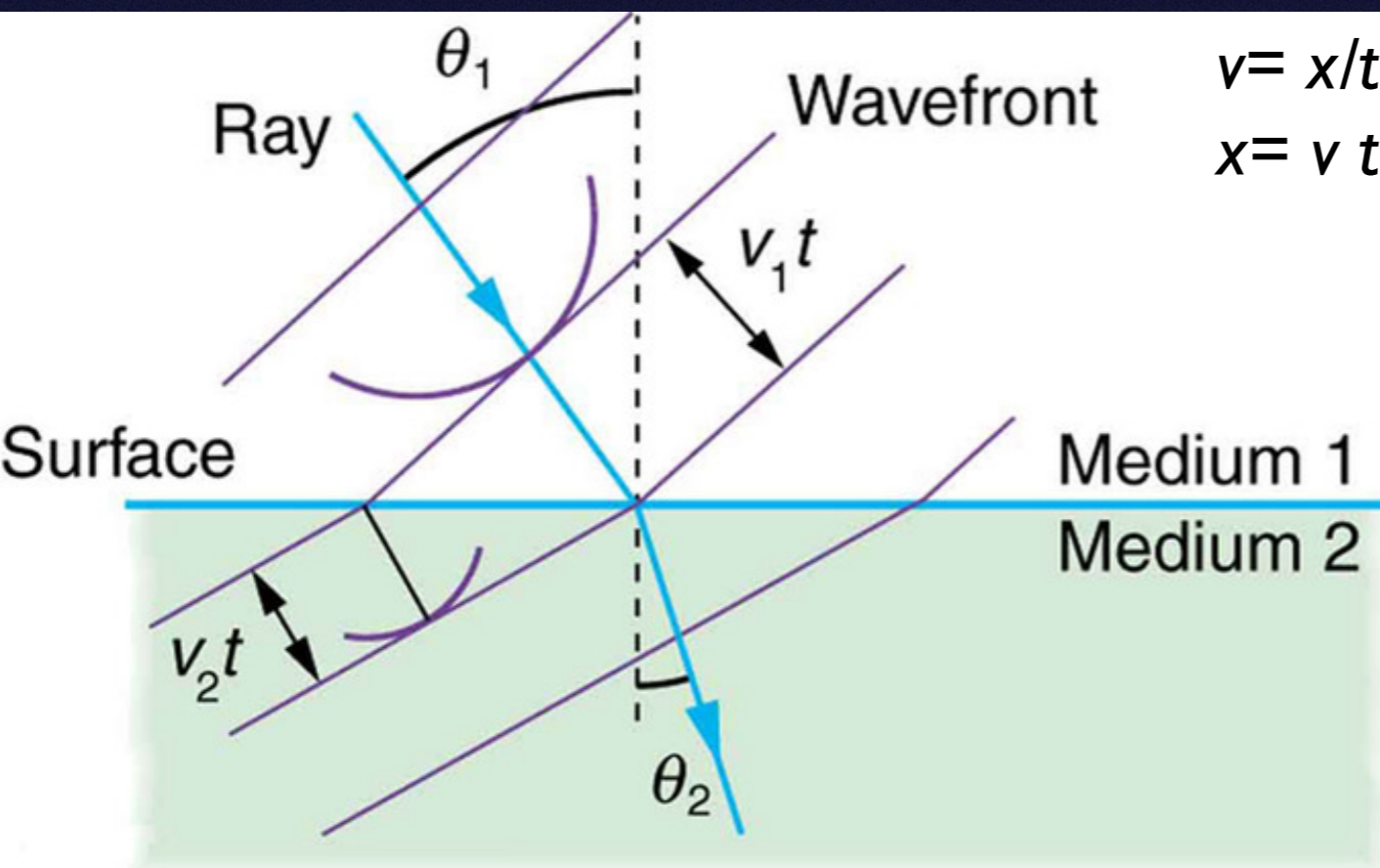
Back at surface

Seismic energy is transmitted/**reflected/refracted**

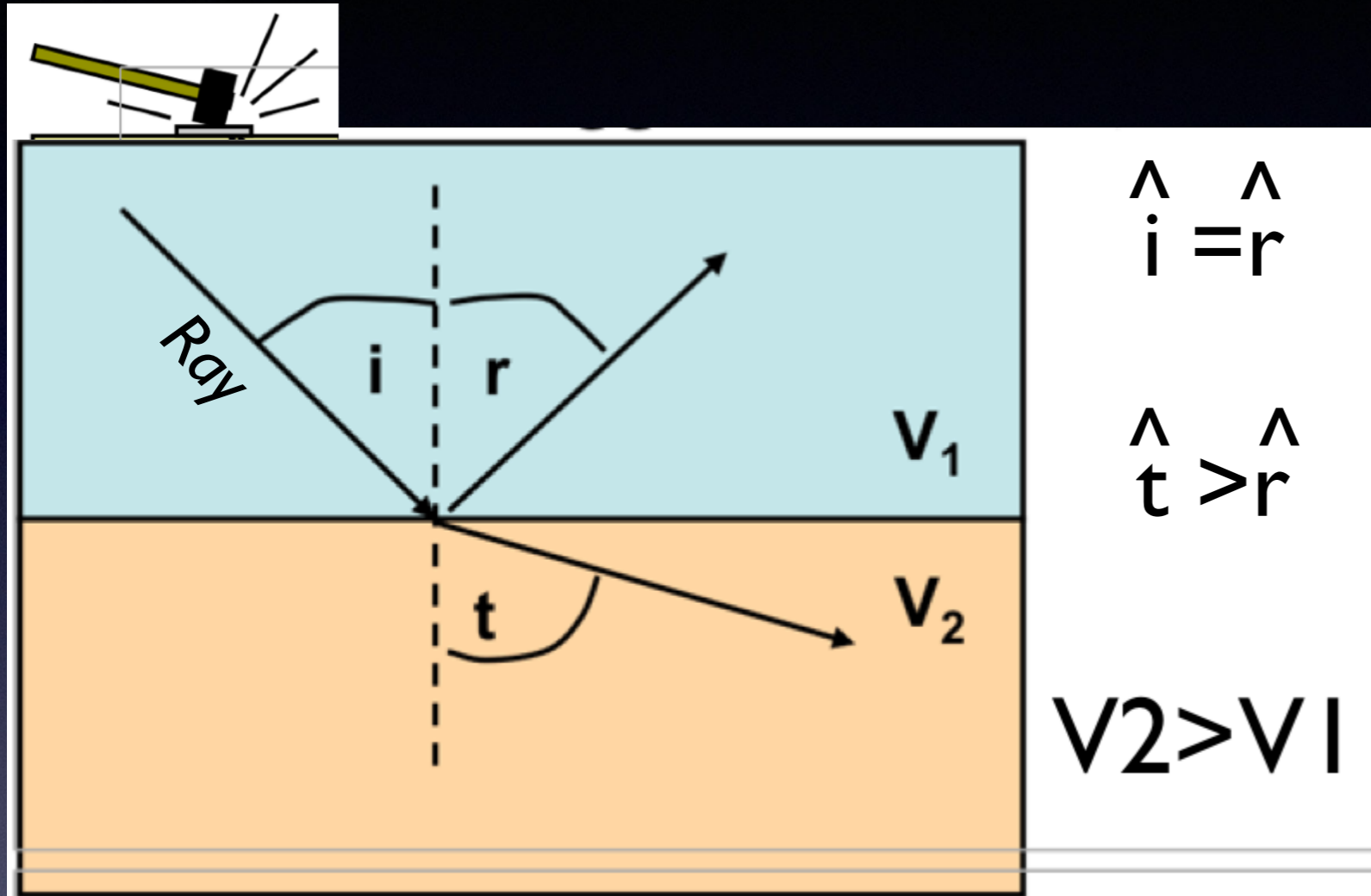


Huygens-Fresnel principle

Given a source (S) generating a spheric wavefront, , each point of the primary wavefront act as a secondary source generating waves of the same characteristics of the primary one (wavelength, frequency, velocity d'onda),
 except if the media changes...



Snell Law



$$\hat{i} = \hat{r}$$

$$\hat{t} > \hat{r}$$

$$v_2 > v_1$$

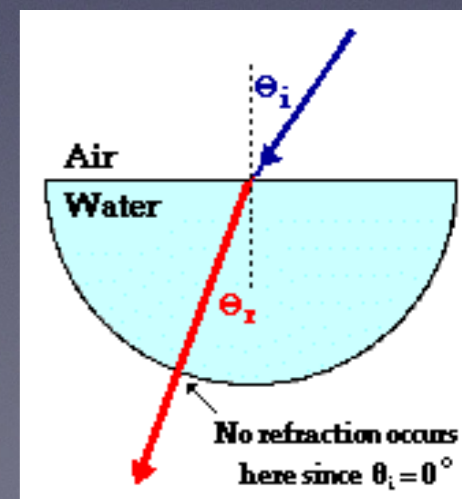
In presence of impedance contrast the ray is reflected with the same incidence angle

Acoustic Impedance Contrast $= \frac{\rho_2 v_2}{\rho_1 v_1} > 1$



Reflection

...in water...



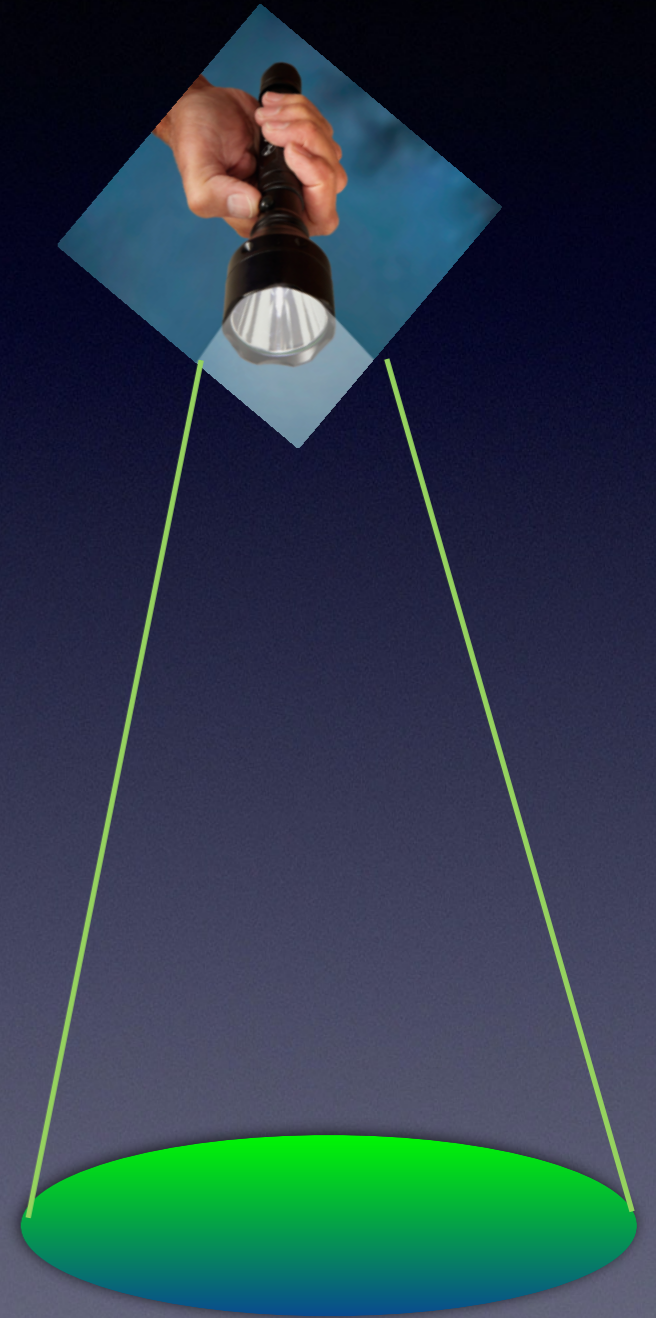
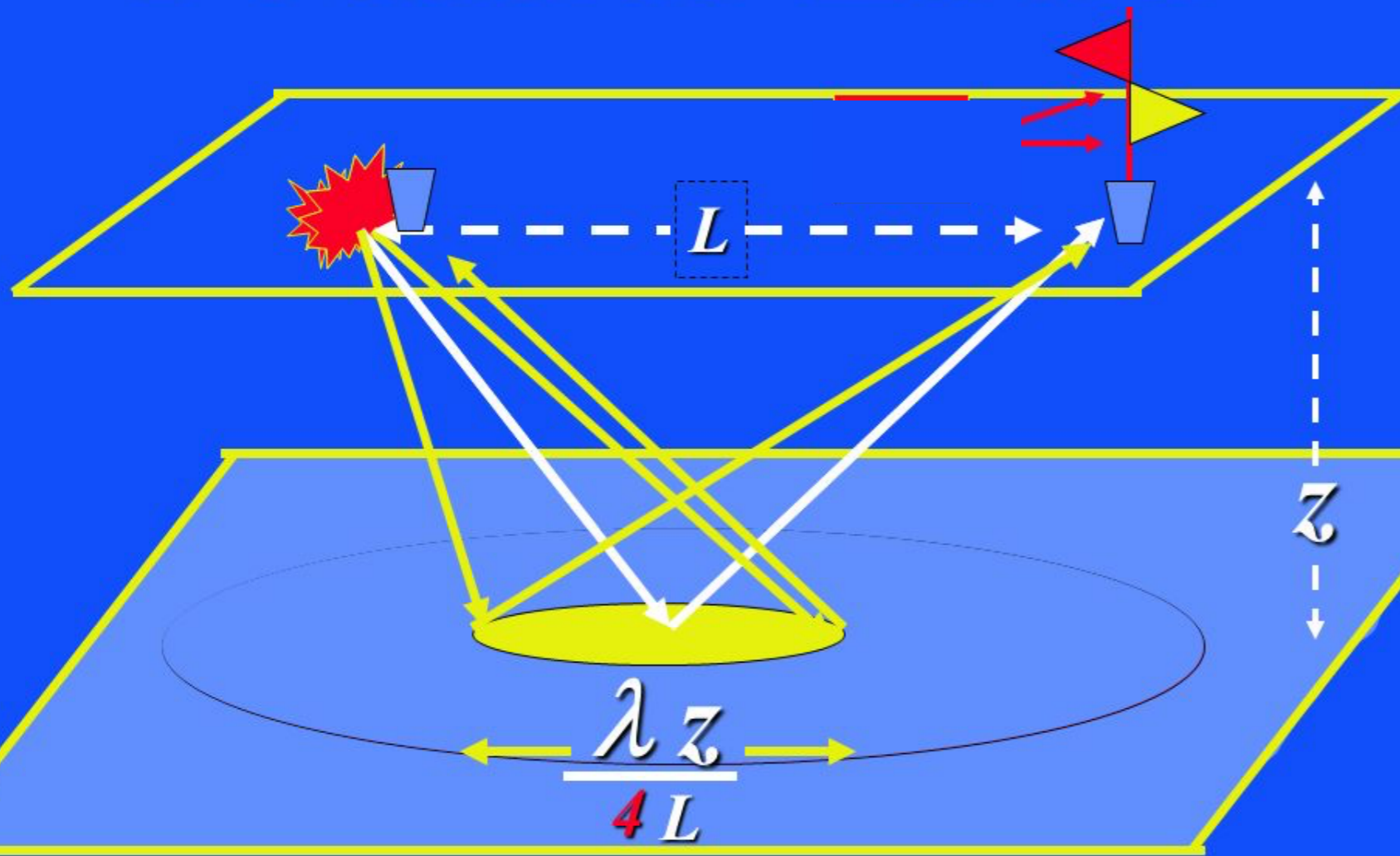
Seismic method

λ = wavelength
 L = total length array
 z = depth

RESOLUTION: the 'Fresnel zone'

$$f(\lambda, L, z)$$

Fresnel Zone



$$\lambda = V / f$$

Seismic methods

RESOLUTION: the 'Fresnel zone'

$$f(\lambda, L, z)$$

$$\lambda = v / f$$

Vertical and horizontal resolution Fresnel zone

Vertical Resolution of a seismic pulse: $\frac{1}{4}$ - $\frac{1}{8}$ of a wavelength

Example: $v=2\text{km/s}$, 50Hz \rightarrow resolution $\approx 10\text{ m}$

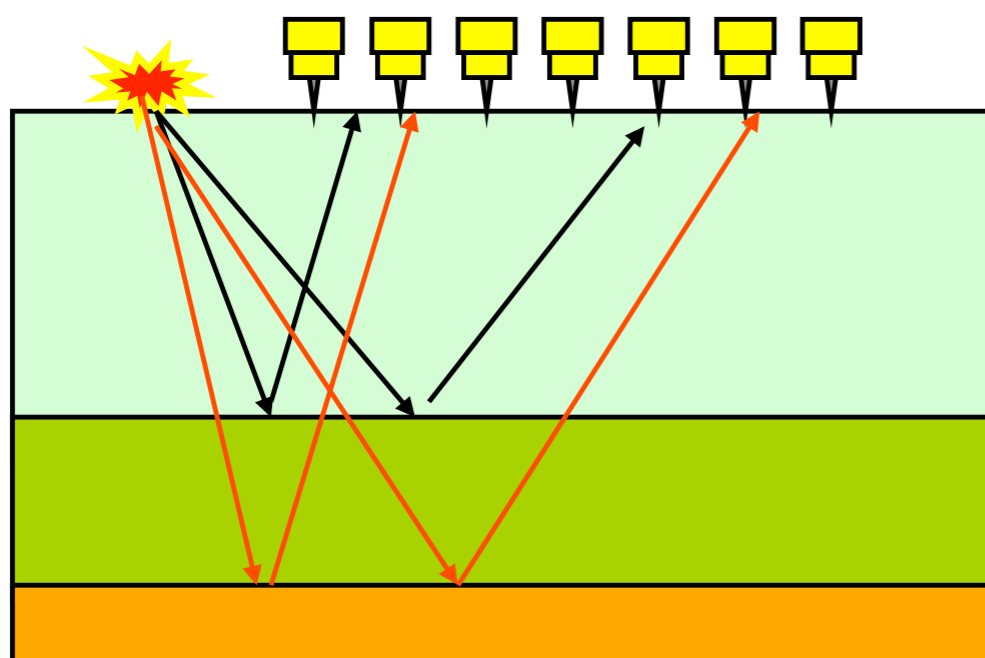
\rightarrow Sharpening of the pulse desirable \rightarrow Deconvolution \rightarrow towards impulse response of medium

Horizontal Resolution determined by the detector spacing and the Fresnel zone: $w=(2z\lambda)^{1/2}$ for $z \gg \lambda$.

@ 100 m depth
 $w \approx 90\text{ m}$

REFLECTION SEISMIC

Reflections

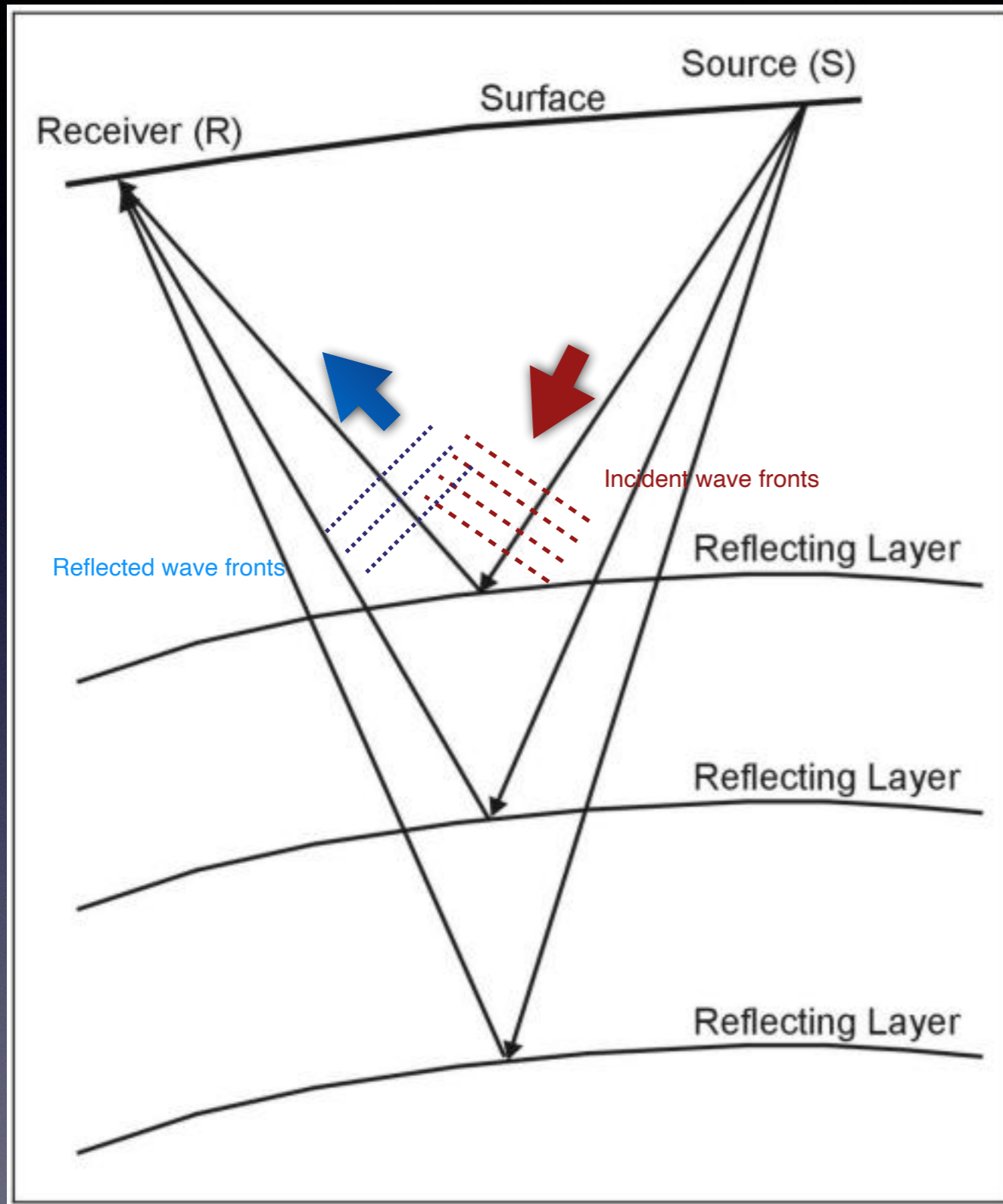


Oil & Gas

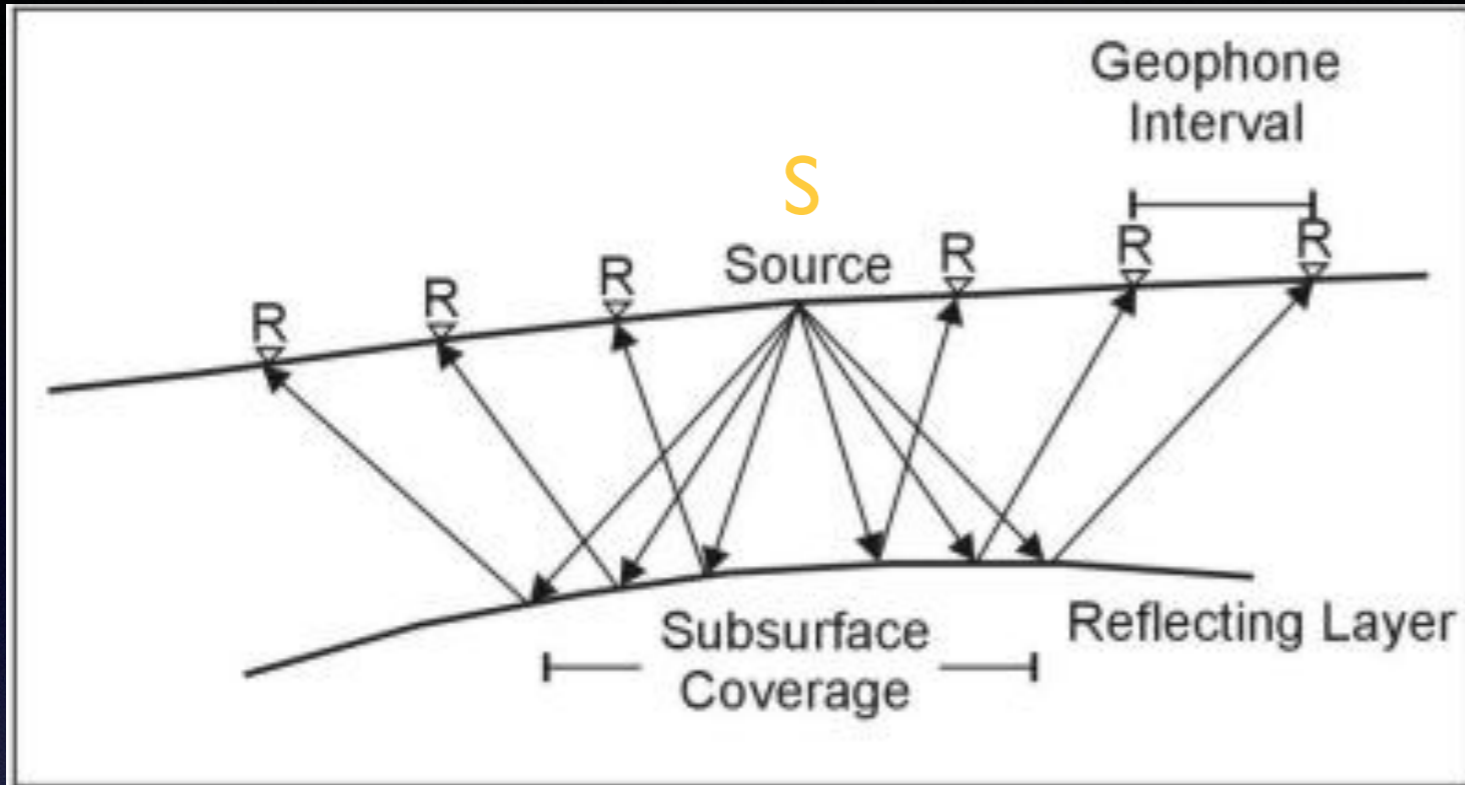
We generate waves that reflect on surface interface, having information on shape and depths if DEEP Structures

REFLECTION SEISMIC

Reflection from different Layering in the subsoil

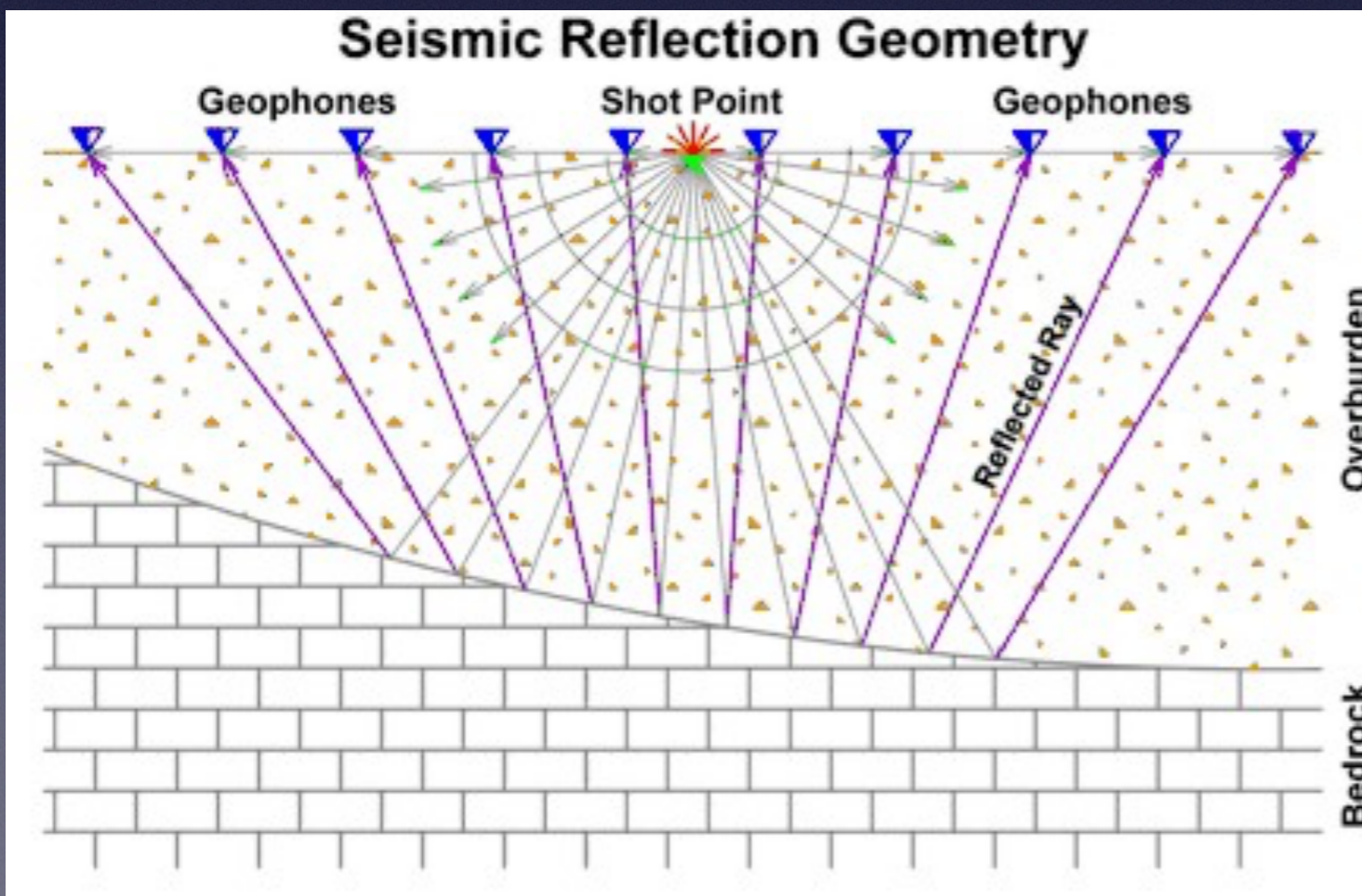


Seismic method



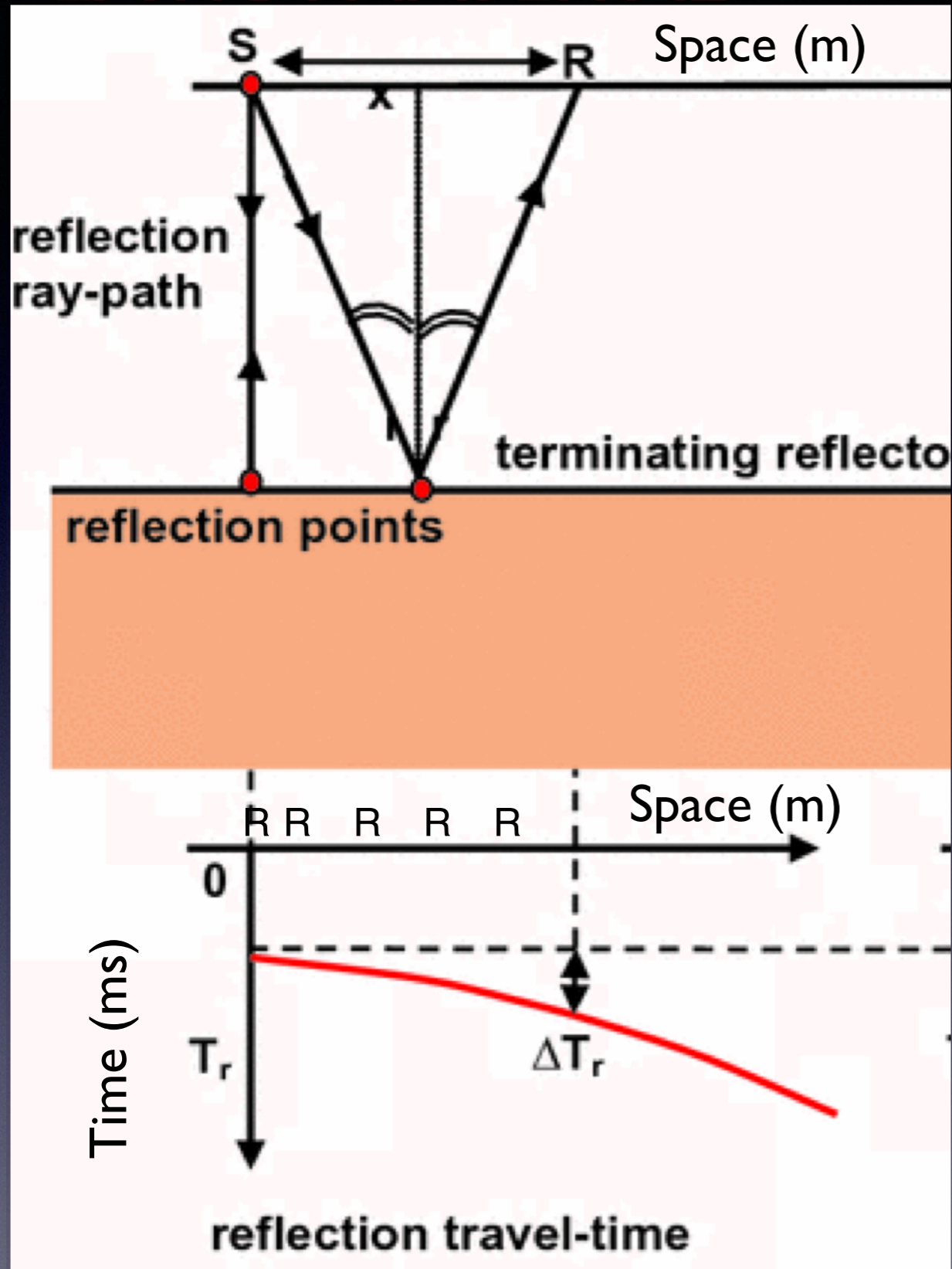
Recording signal emitted by the source **S** using the receiver **R**

R are the receivers

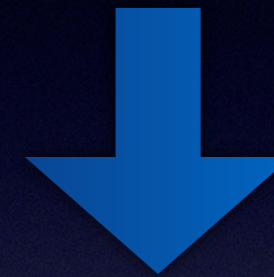


Geophones

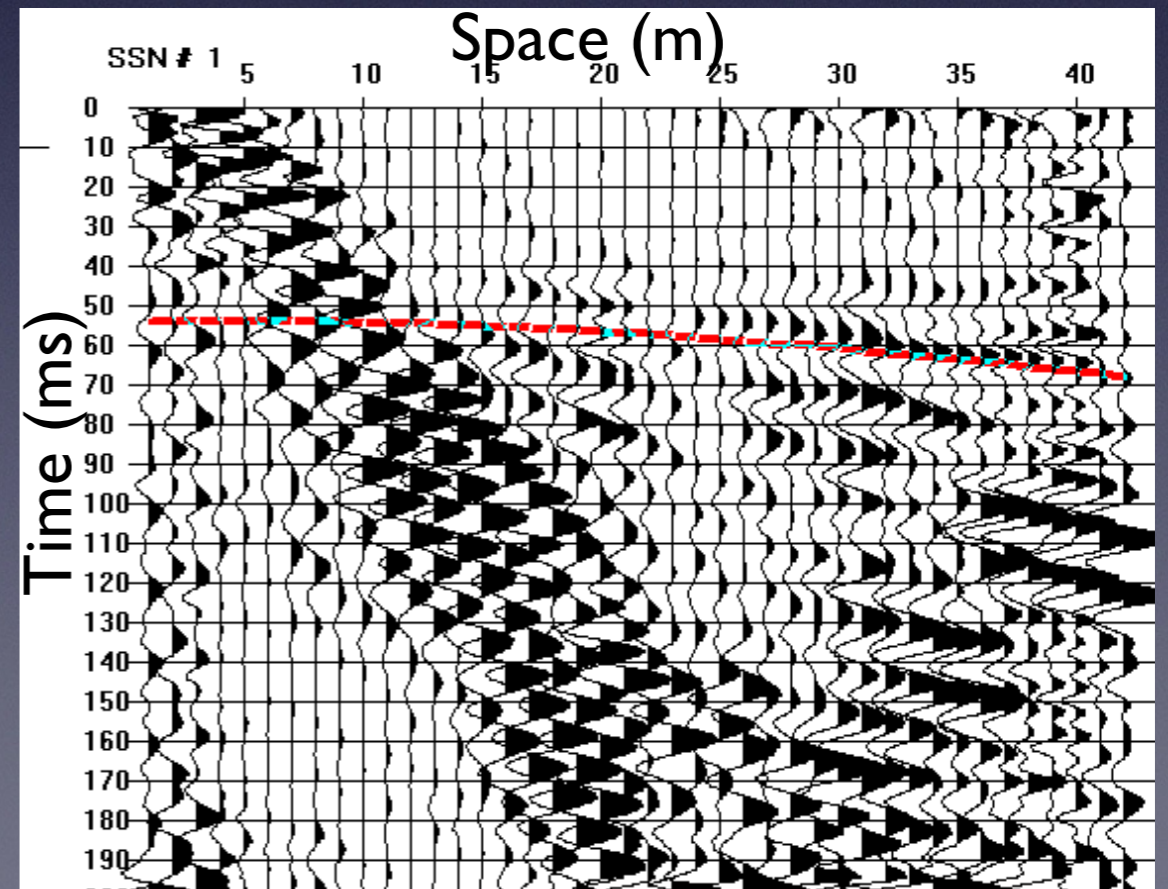
EXTRA MATERIAL



Record signal in time



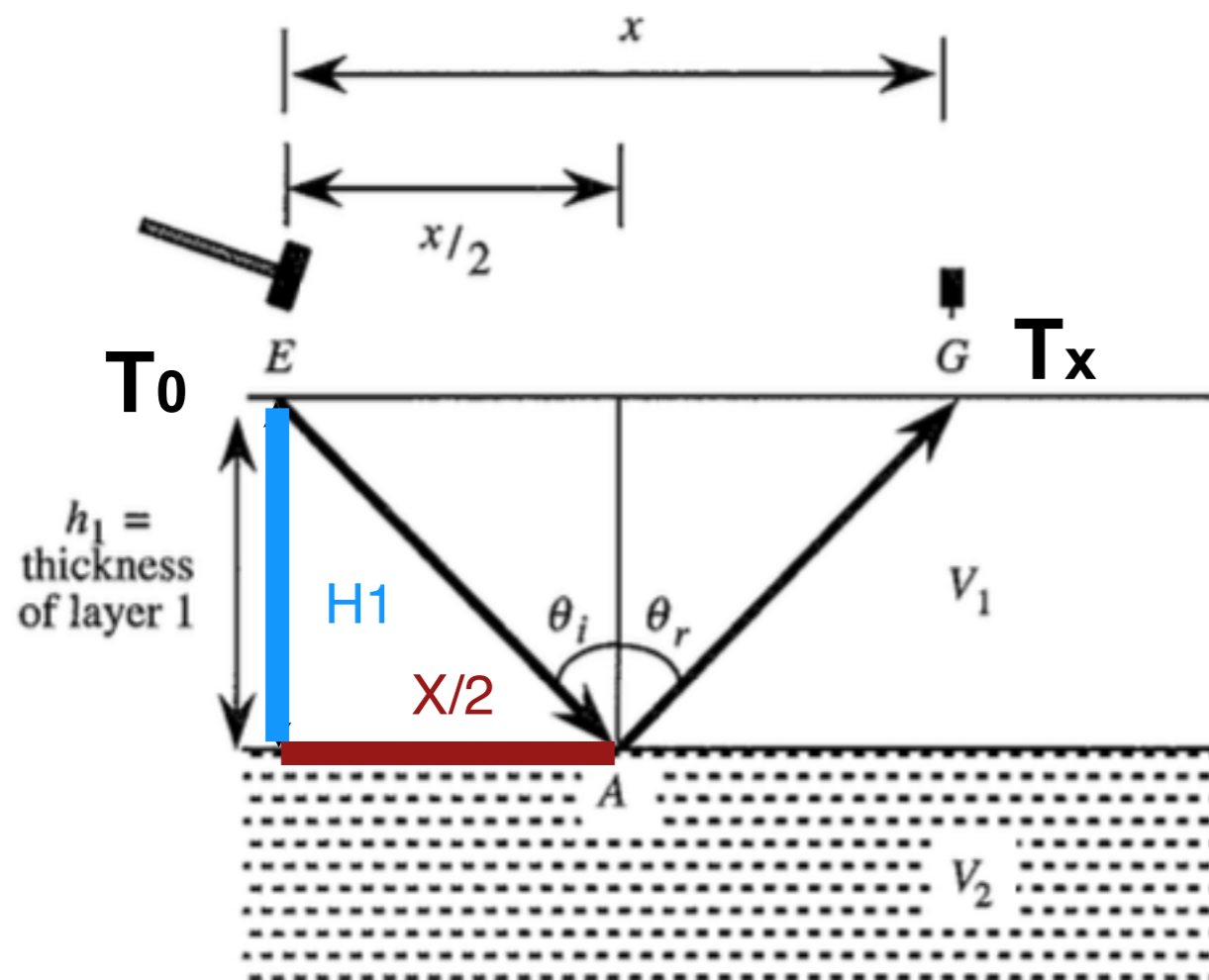
Seismogram space/time



Two Way travel Time TWT

EXTRA MATERIAL

Seismic Reflection



$$\text{Time} = \frac{\text{space}}{\text{Velocity}}$$

$$\text{time} = \frac{EA + AG}{V_1}$$

$$EA = AG = \left[\left(\frac{x}{2} \right)^2 + h_1^2 \right]^{1/2}$$

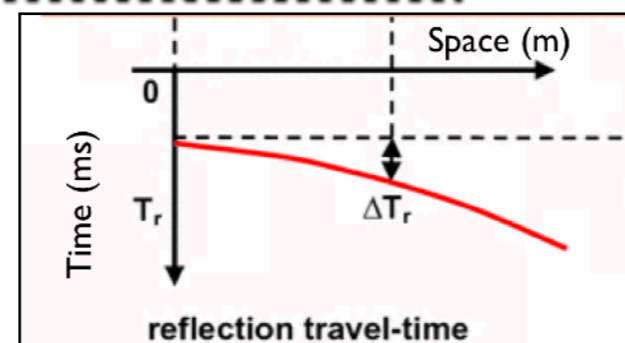
$$\text{time} = \frac{(x^2 + 4h_1^2)^{1/2}}{V_1}$$

$$T_0 = 2h/V_1$$

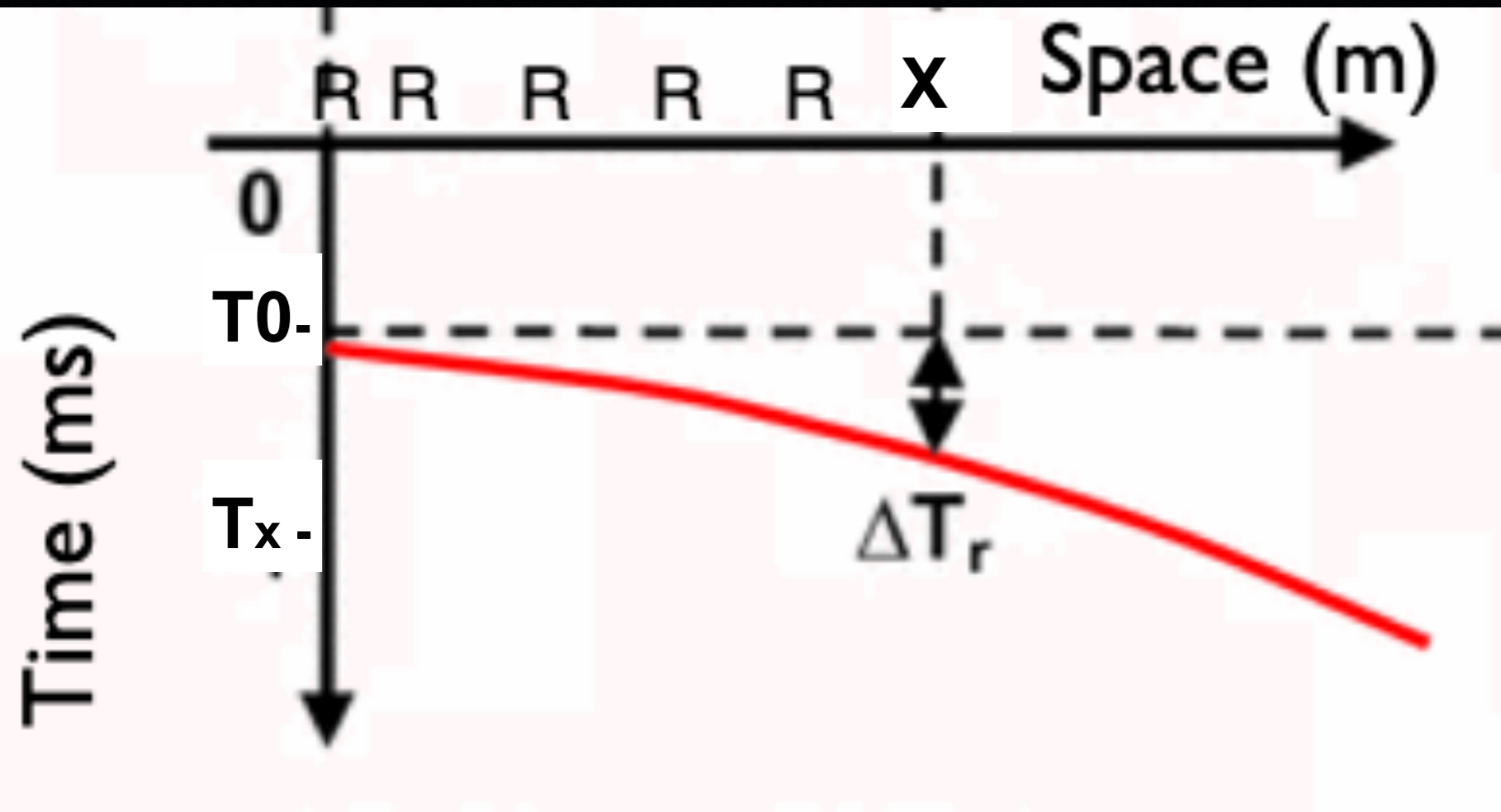
Hyperbola

$$T^2_x = T^2_0 + X^2 / V_1^2$$

spazio -tempo



EXTRA MATERIAL



2 equations 2 unknowns

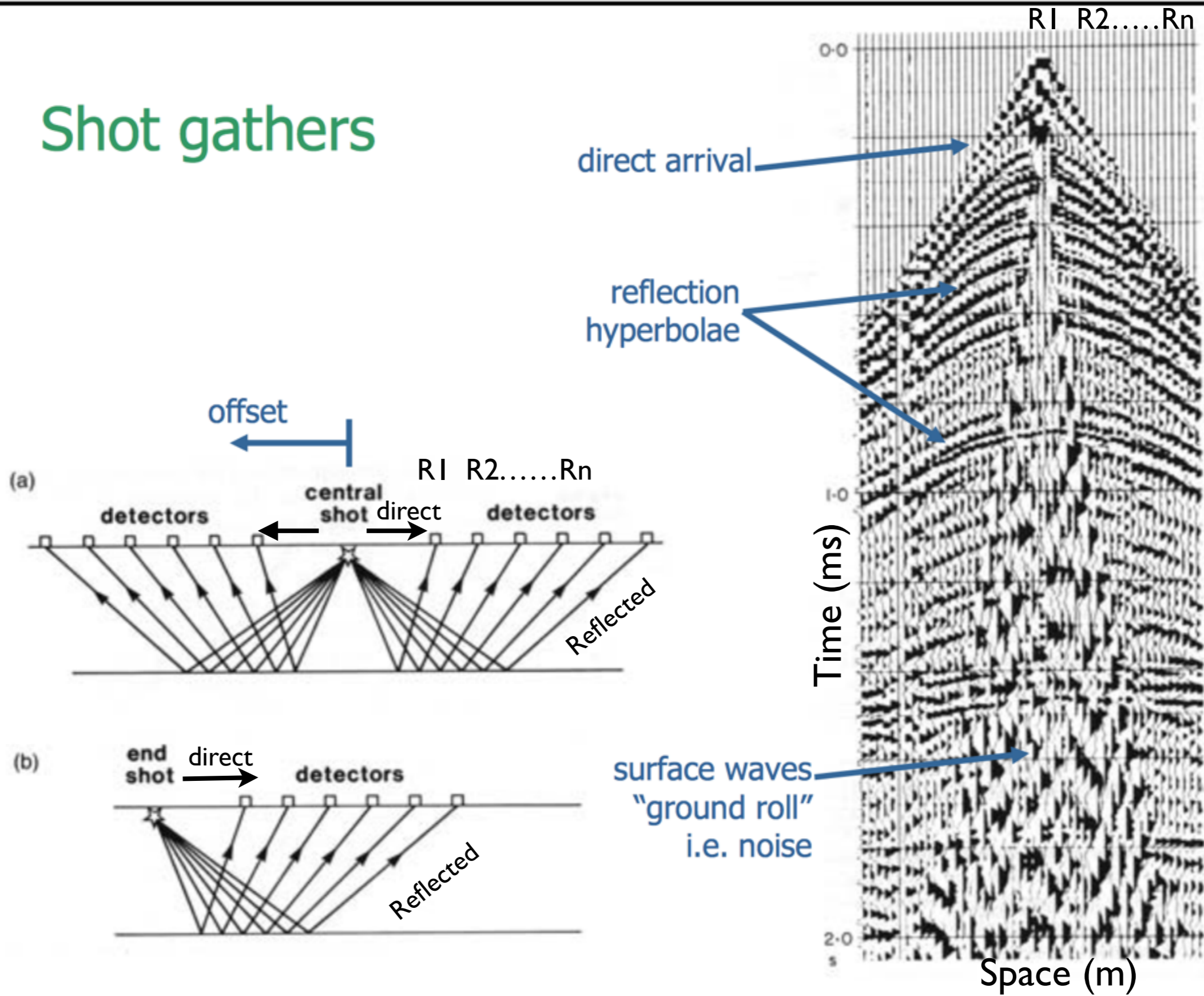
- Upper layer velocity V_1
- Thickness of upper layer h



$$T_0 = 2h/V_1$$

$$T_x^2 = T_0^2 + X^2 / V_1^2$$

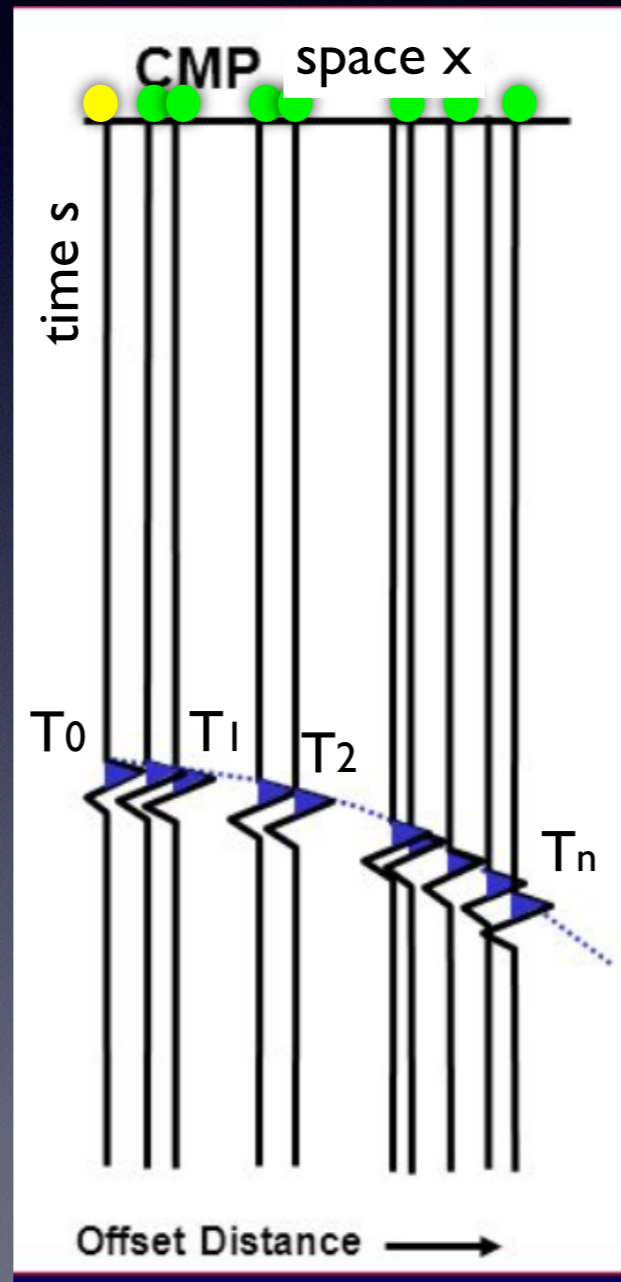
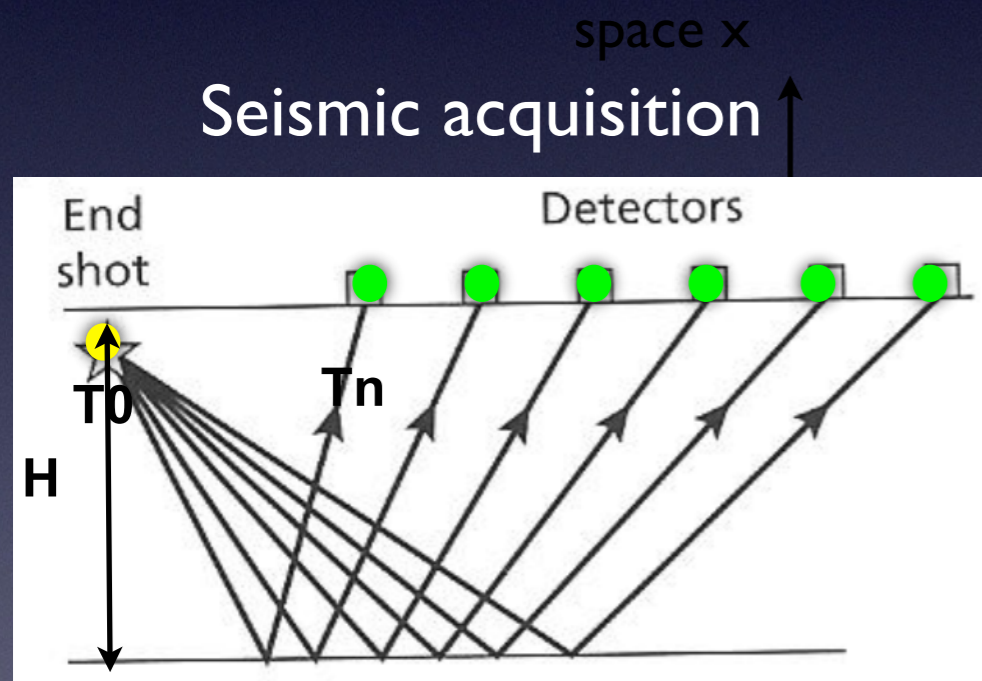
Shot gathers



Seismic methods

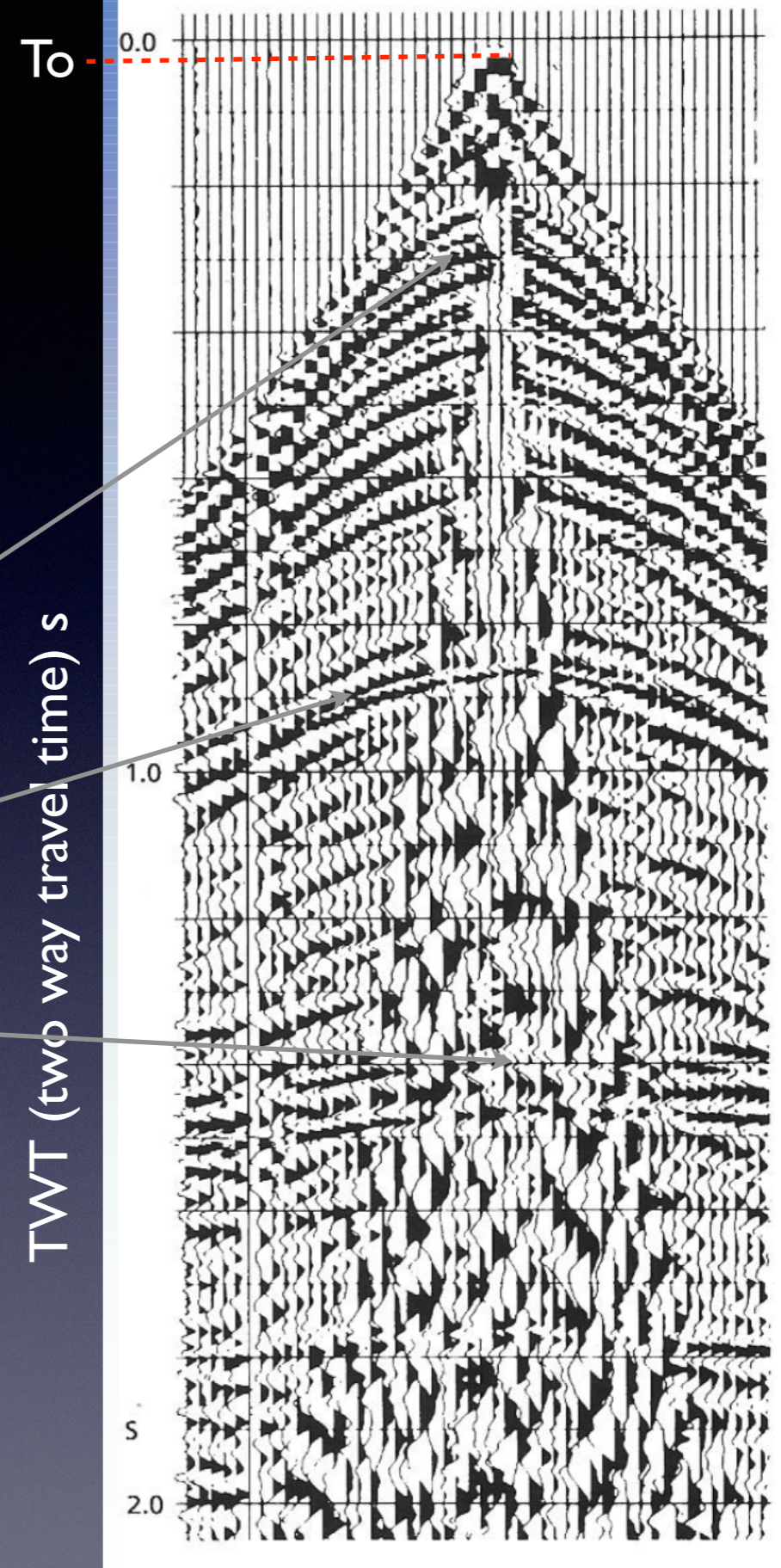
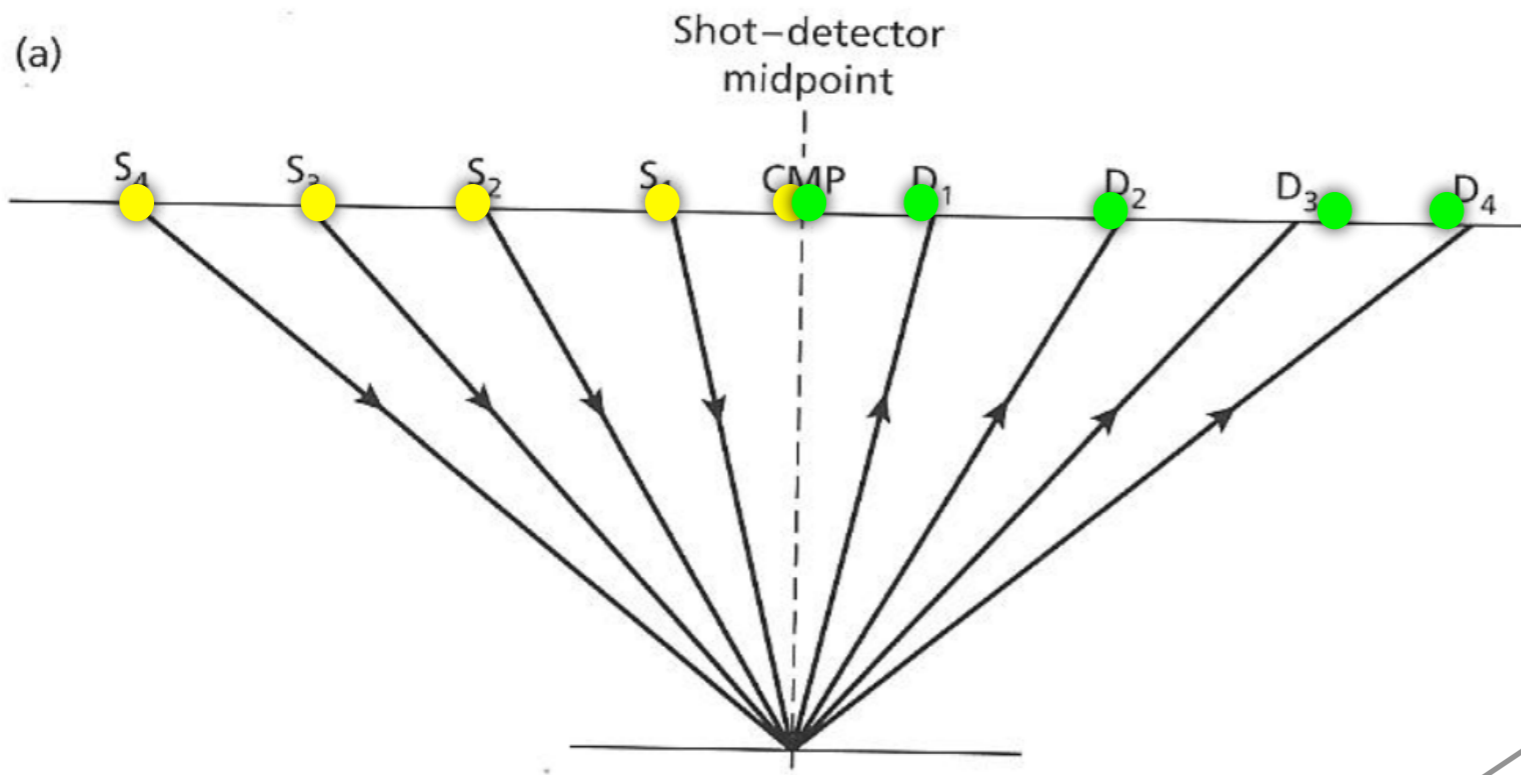
Reflections on Seismograms
are **REFLECTION HYPERBOLA**

Seismogram (space-time)



$$T^2_x = T^2_0 + X^2 / V_1^2$$

$$T_0 = 2H / V_1$$



Reflection Hyperbola

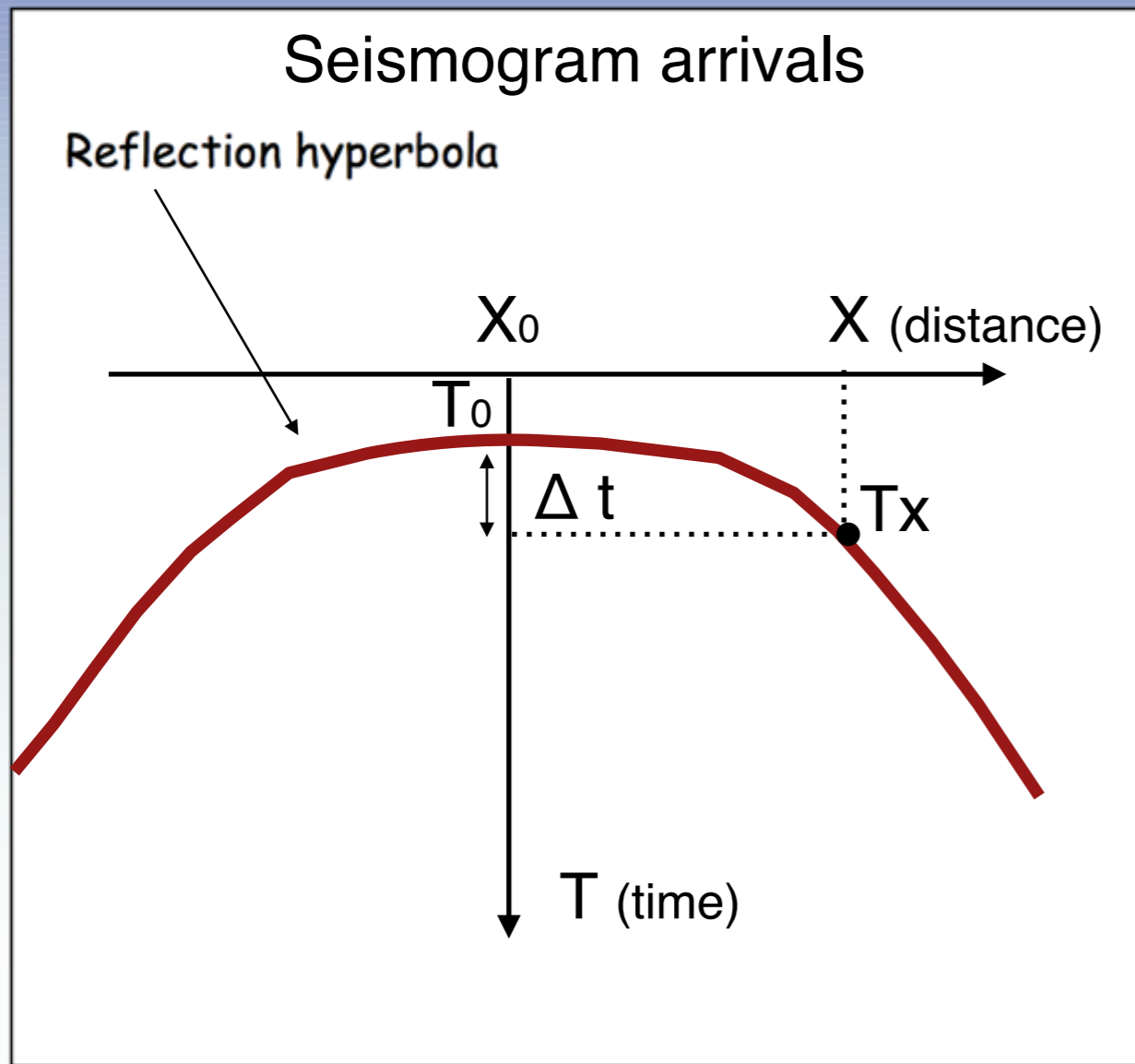
TWWT (two way travel time) s

EXTRA MATERIAL

$$T^2x = T^2_0 + x^2 / V_1^2$$

$$T_0 = 2h/V_1$$

The arrival times $t(x)$ of reflections from an interface at depth h as a function of offset x are given as

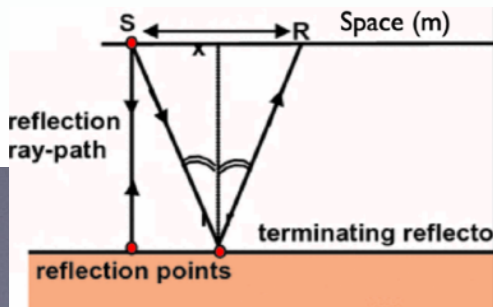


$$t(x) = \frac{1}{v} \sqrt{x^2 + 4h^2}$$

$$t^2 = \frac{4h^2}{v^2} + \frac{x^2}{v^2} = t_0^2 + \frac{x^2}{v^2}$$

$$\Delta T = t_x - t_0 \approx \frac{x^2}{2V^2 t_0}$$

Normal moveout (NMO)

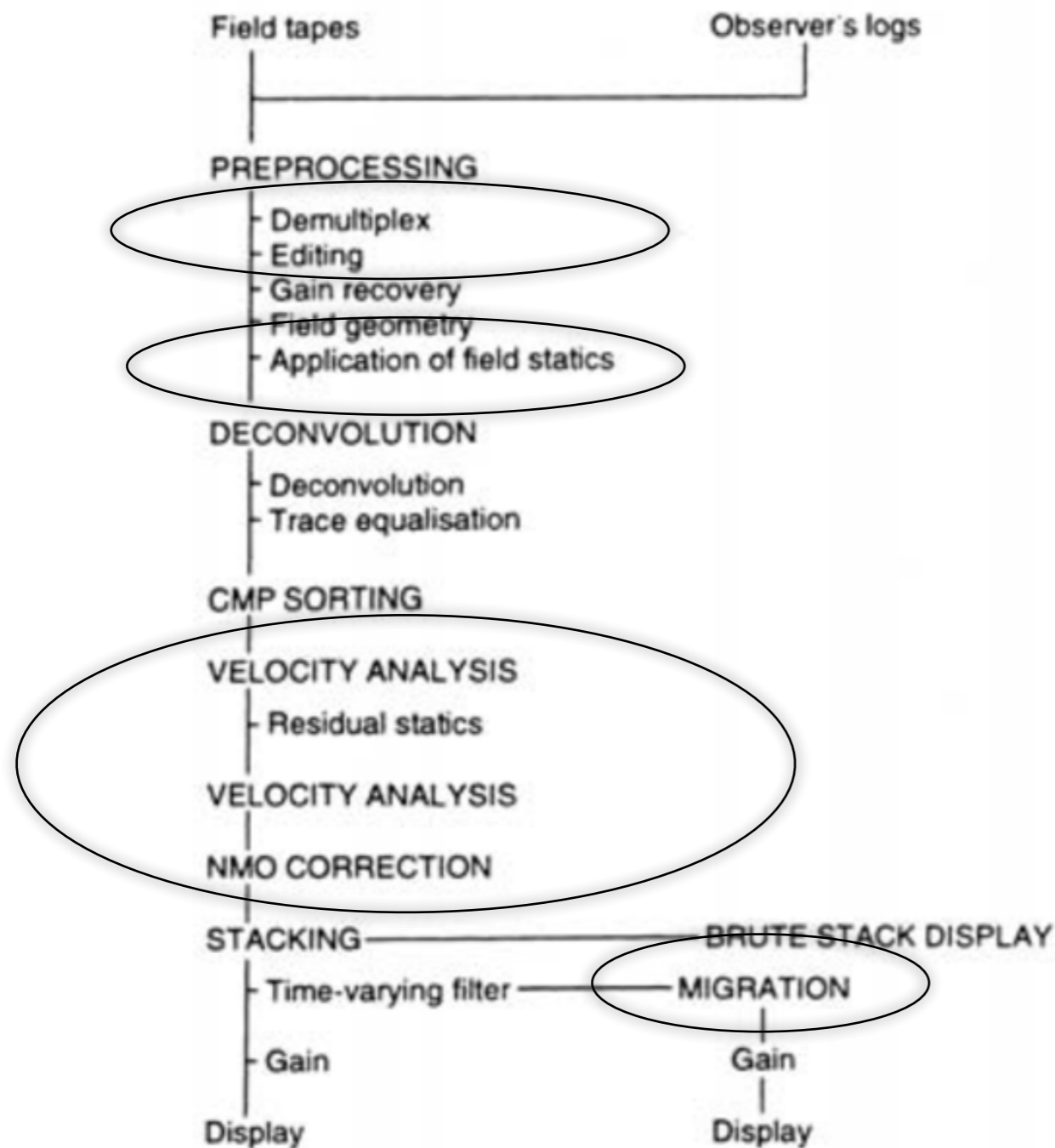


Easiest way to find V_1

sismica a riflessione - Processing complesso

Seismic reflection processing

Flow overview



- Statics correction
- Muting
- Velocity analysis (NMO)
- migration

These are the main steps in processing

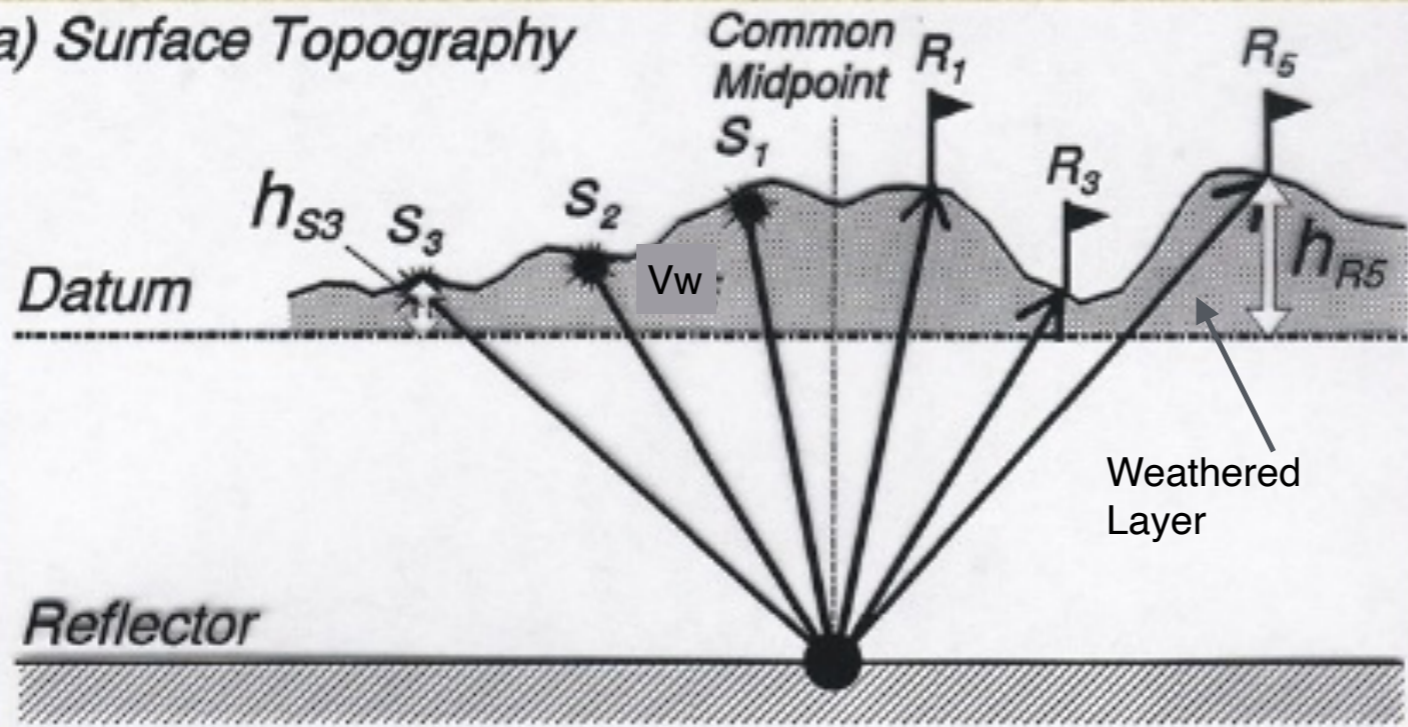
The order in which they are applied is variable

EXTRA MATERIAL

Static Corrections

(Topographic Correction)

a) Surface Topography

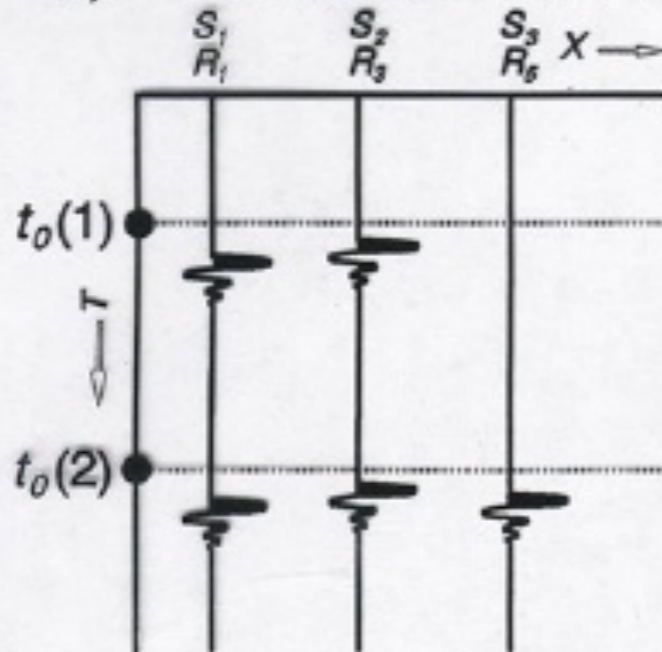


$$\text{Time corr} = hr / V_w$$

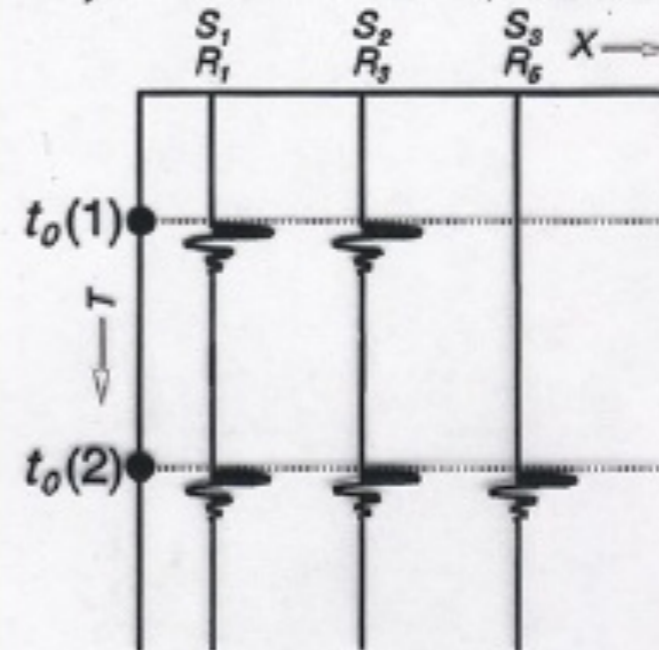
V_w Assumed velocity of the material above

hr Thickness of the weathered layer

b) Before Statics Corrections



c) After Statics Corrections



Static corrections

Correct for surface topography and the weathered surface layer

Surface topography

Time correction to each trace:

$$t_g = (E_g - E_d) / V$$

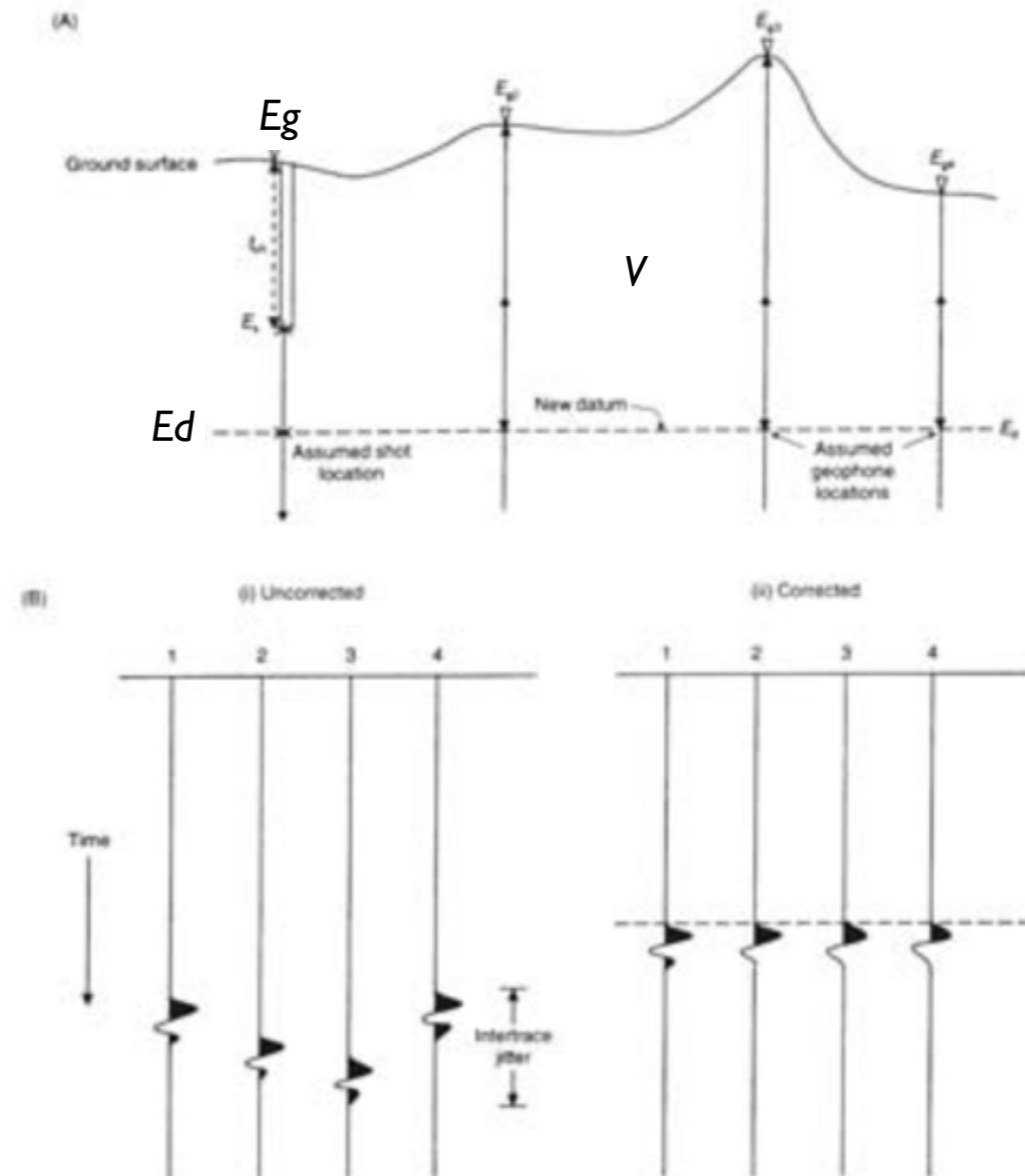
Source depth

$$t_s = (E_s - E_d) / V$$

total correction

$$t_e = t_s + t_g$$

Shift each trace by this amount to line up deeper reflectors



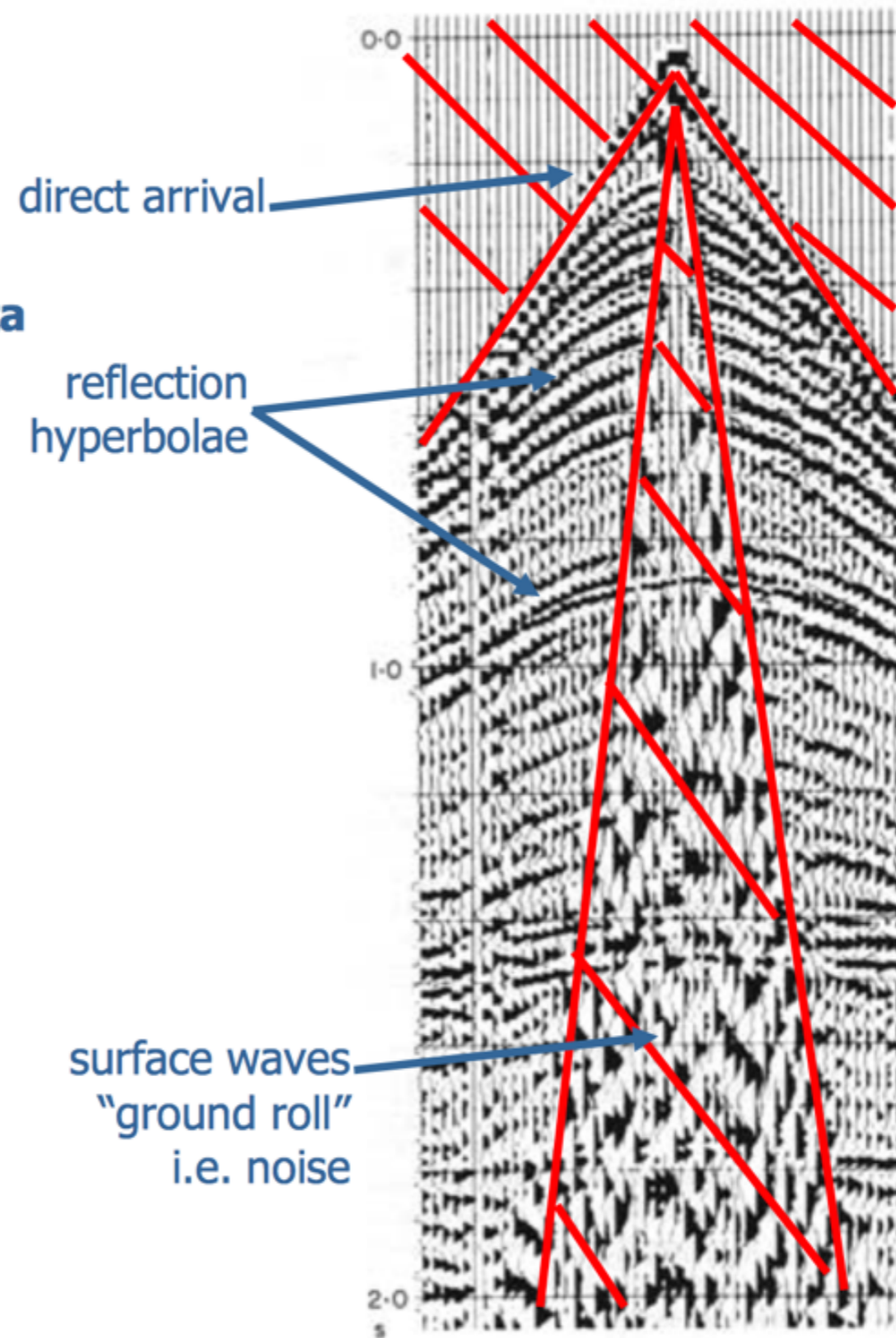
Editing and Muting = clean the raw data

EXTRA MATERIAL

Preprocessing Editing and muting

Manually cleaning up the data

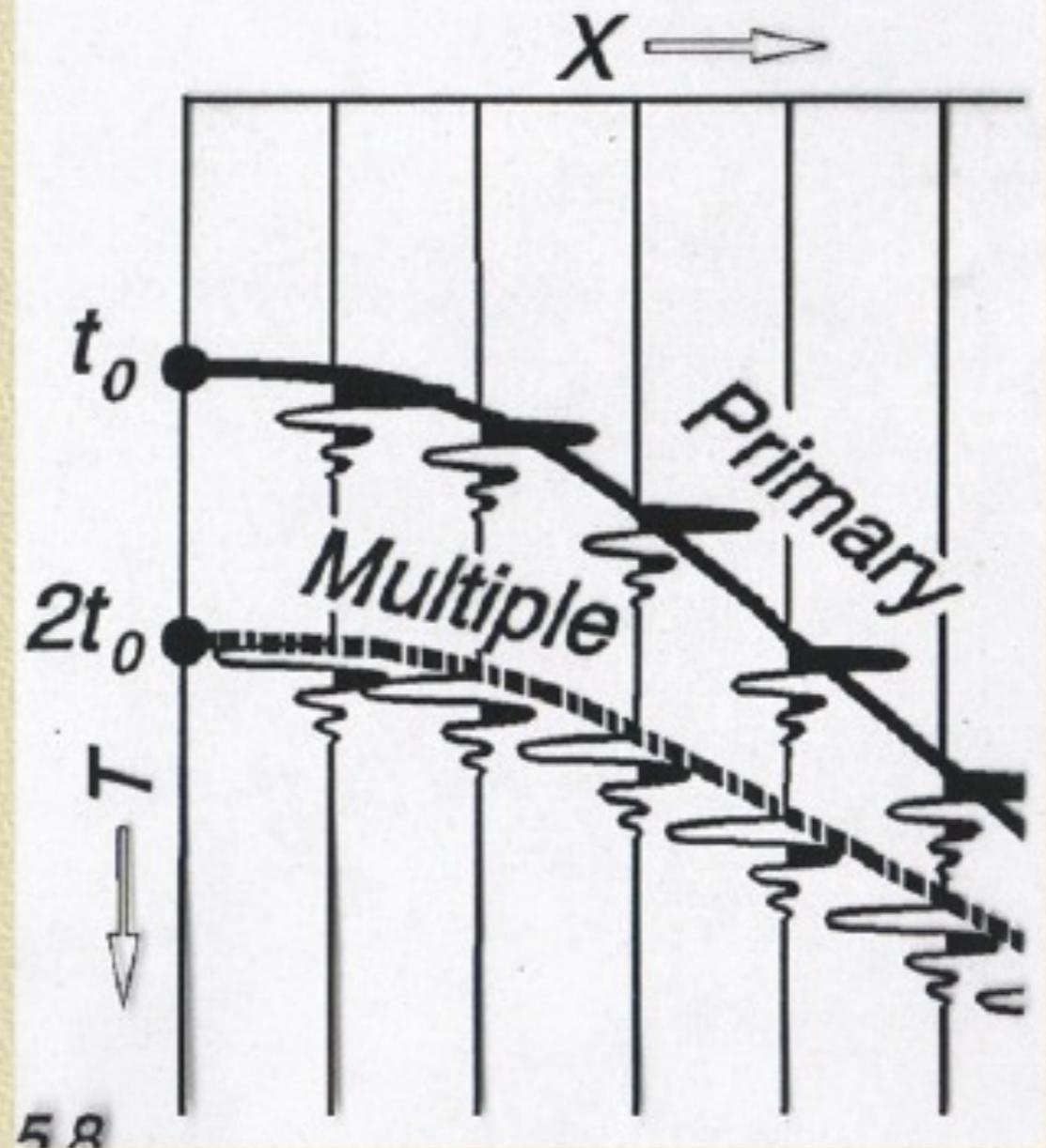
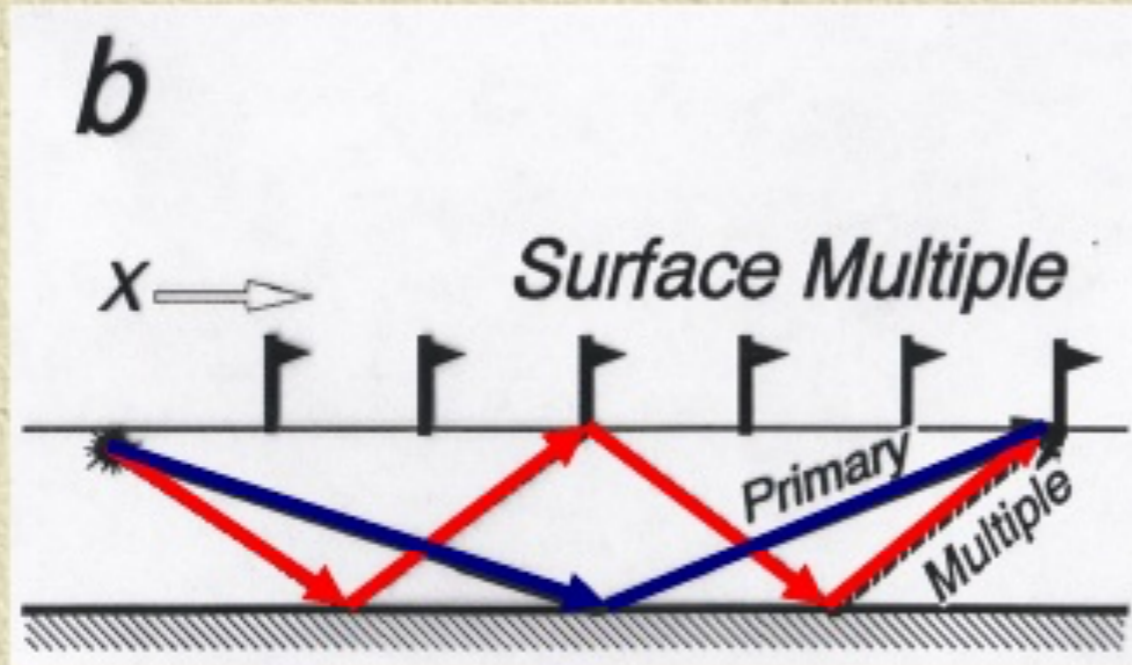
- Remove dead traces
- Remove noisy traces
- Switch polarity on reversed traces
- "Cut" out unwanted signal e.g. pre-arrival noise, direct arrival, ground roll



EXTRA MATERIAL

Multiples

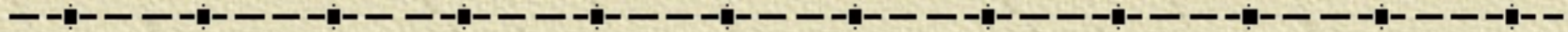
Muting



Reflected energy back up again following a reflection back down at the surface.

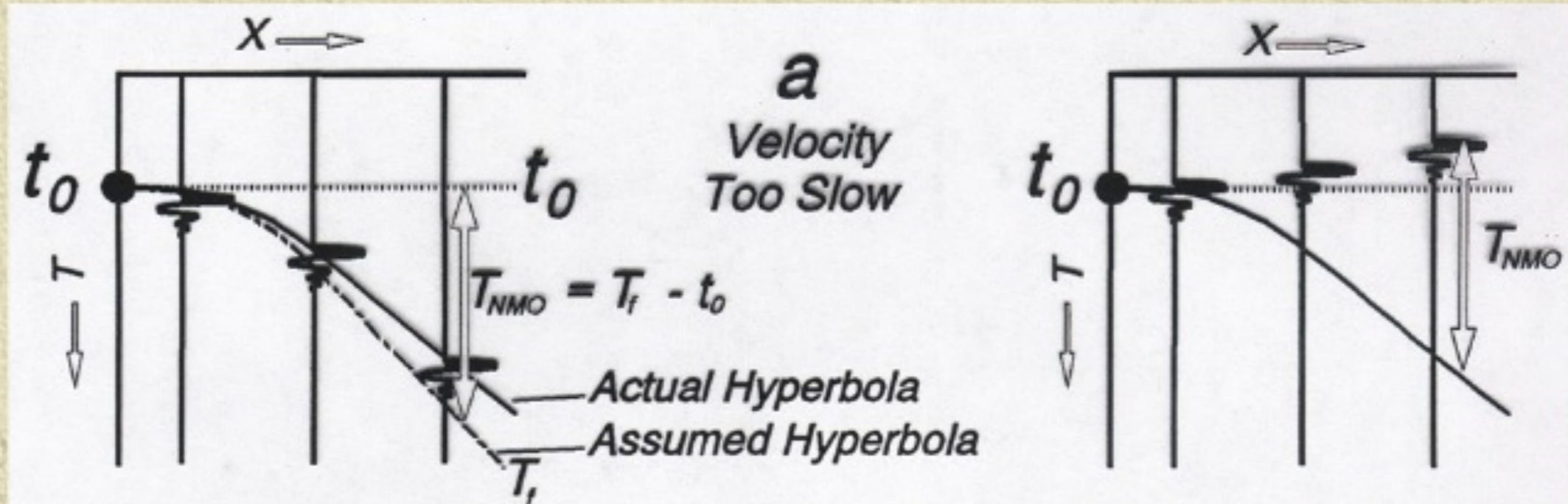
EXTRA MATERIAL

Velocity Analysis



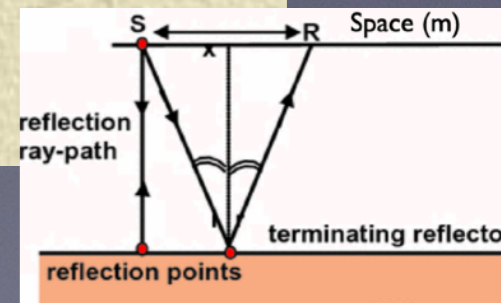
Before T_{NMO} Correction

After T_{NMO} Correction



Overcorrected by too slow velocity

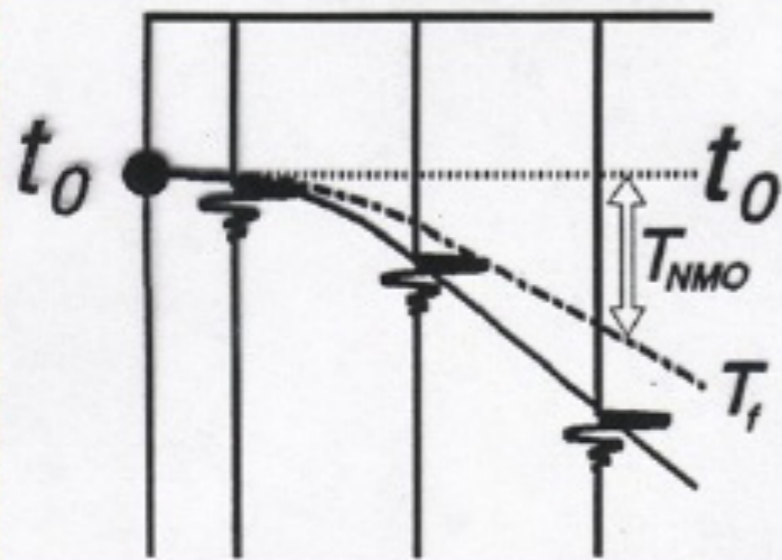
Normal MOVE OUT CORRECTION



EXTRA MATERIAL

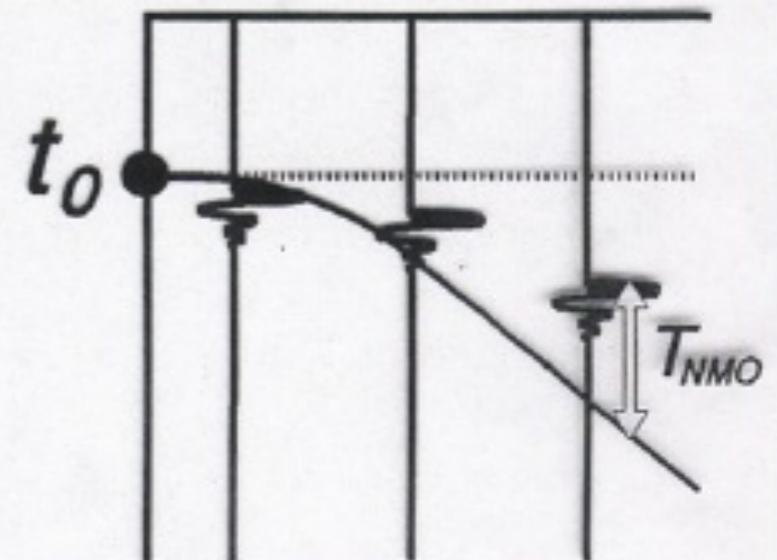
Velocity Analysis

Before T_{NMO} Correction



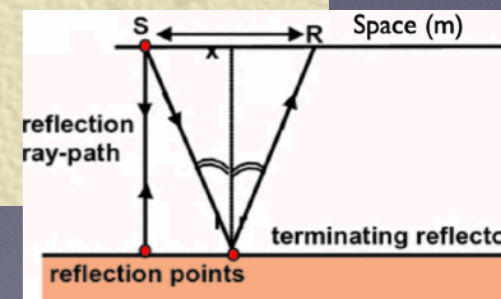
b
Velocity
Too Fast

After T_{NMO} Correction



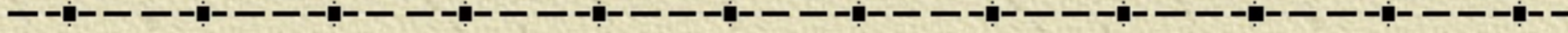
Under corrected by too fast velocity

Normal MOVE OUT CORRECTION



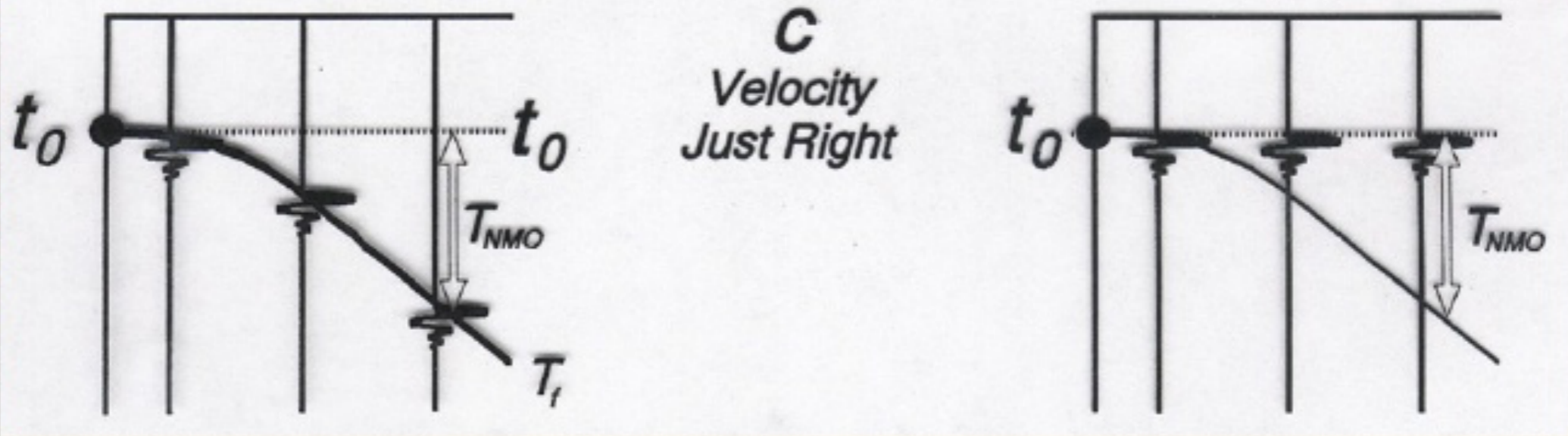
EXTRA MATERIAL

Velocity Analysis

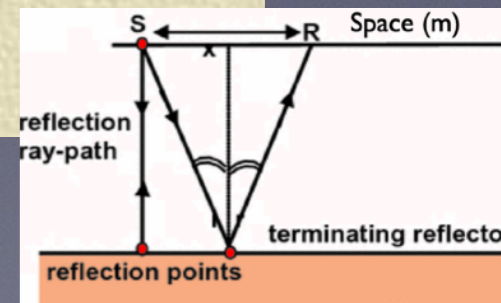


Before T_{NMO} Correction

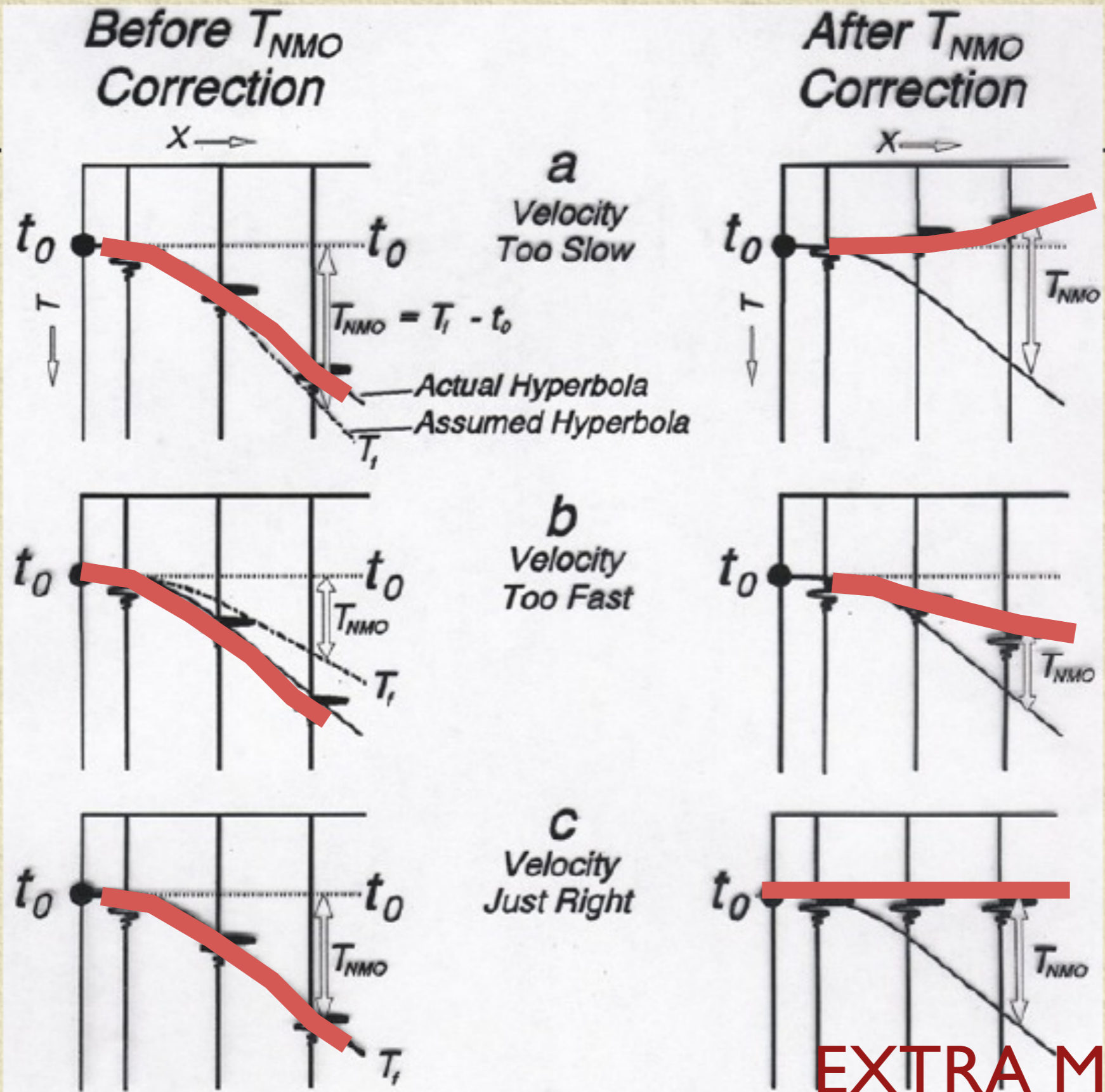
After T_{NMO} Correction



NMO - Normal Moveout Correction
Now Corrected



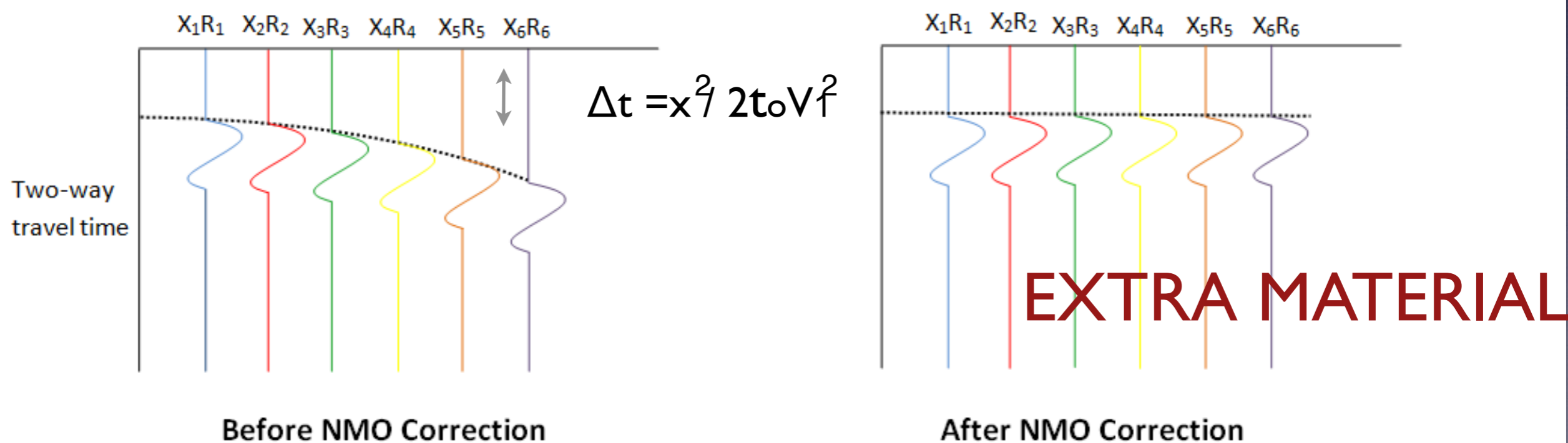
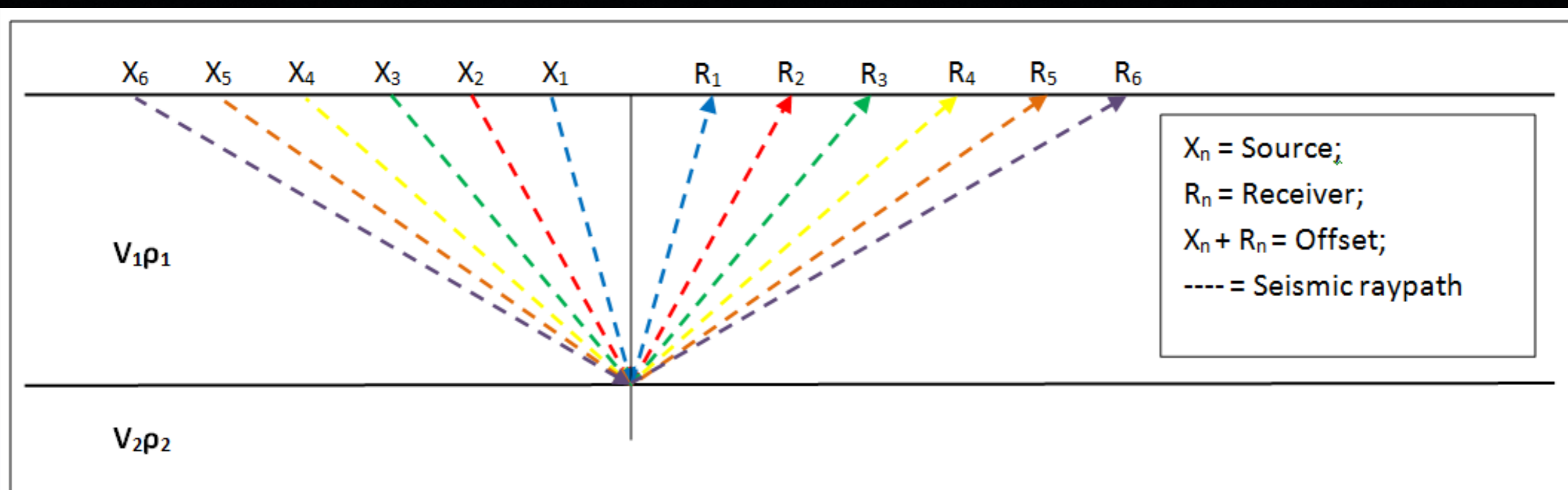
Normal MOVE OUT CORRECTION



EXTRA MATERIAL

Metodi Sismici

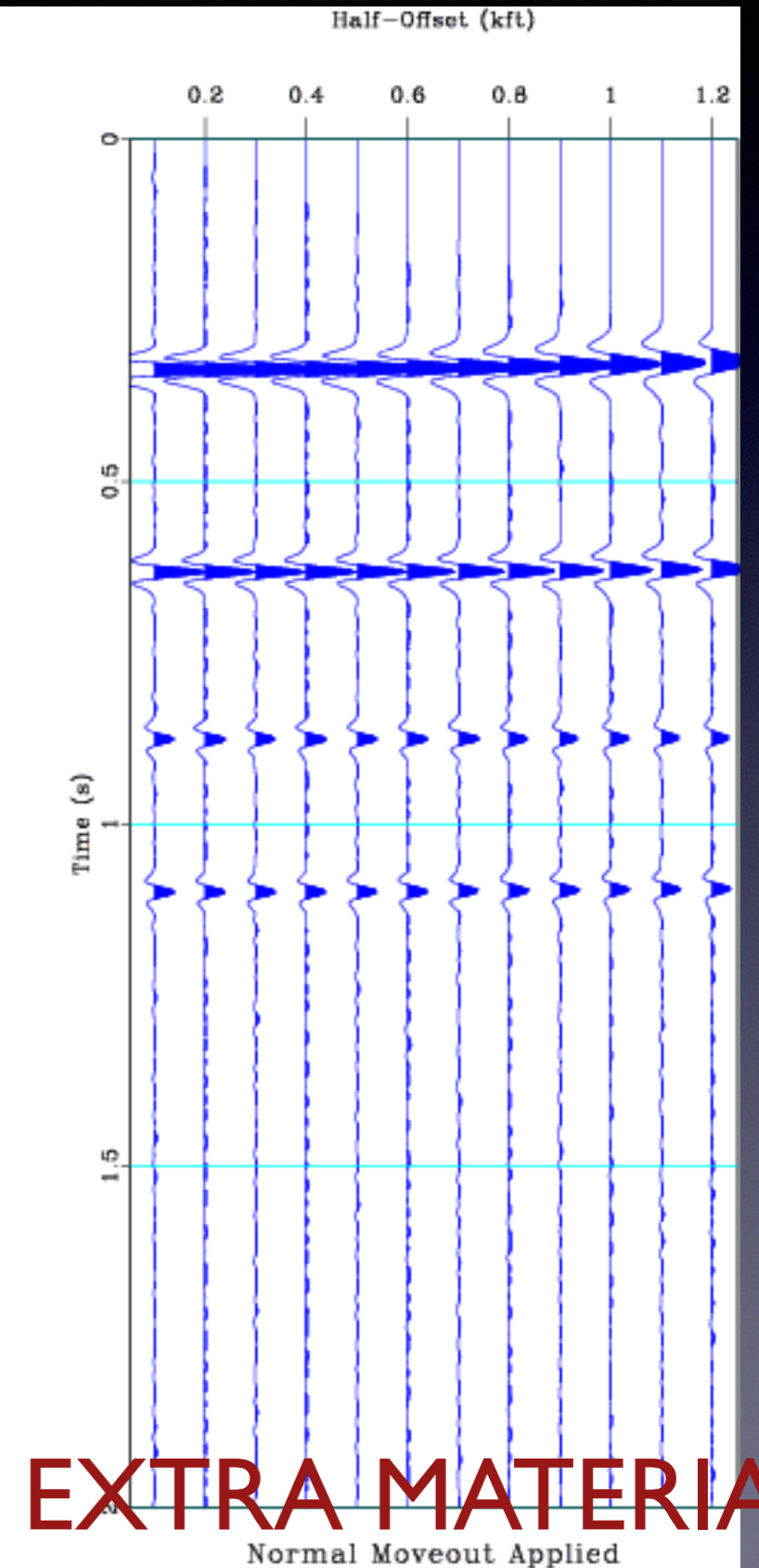
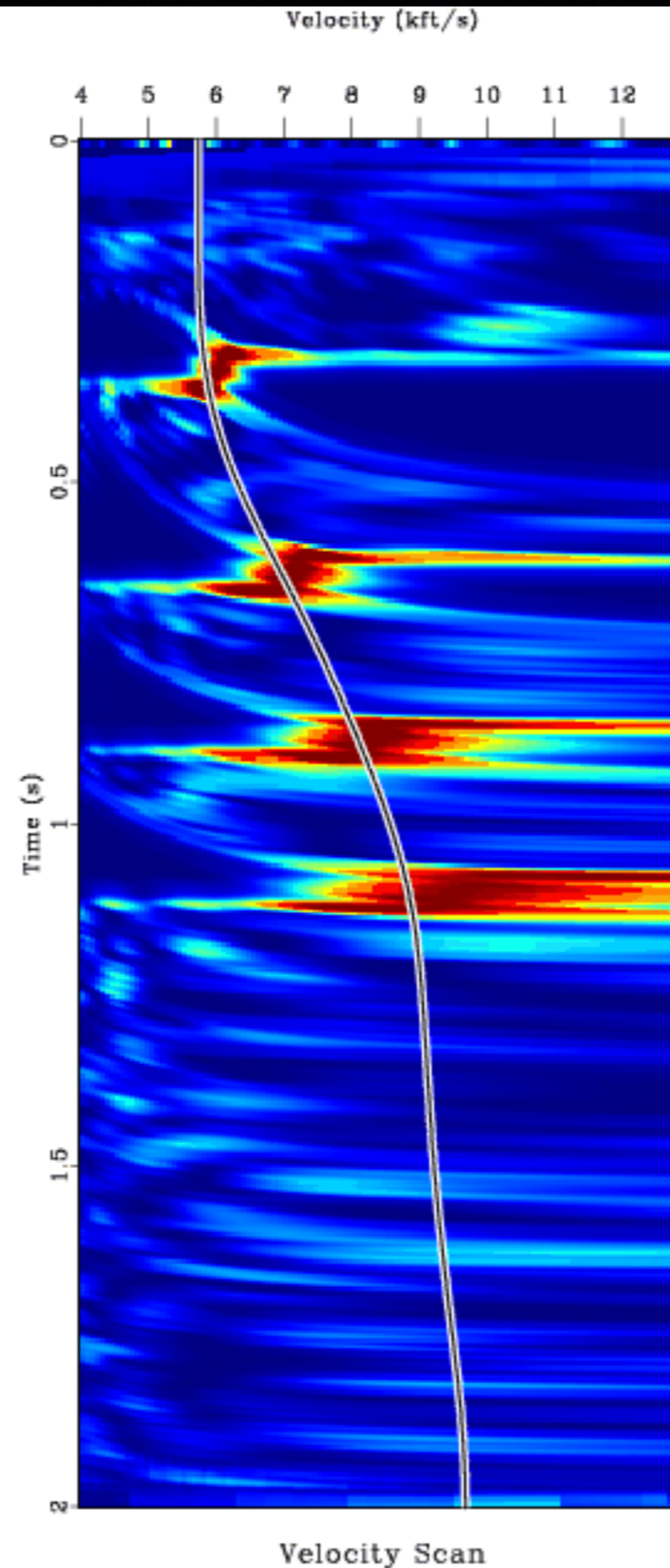
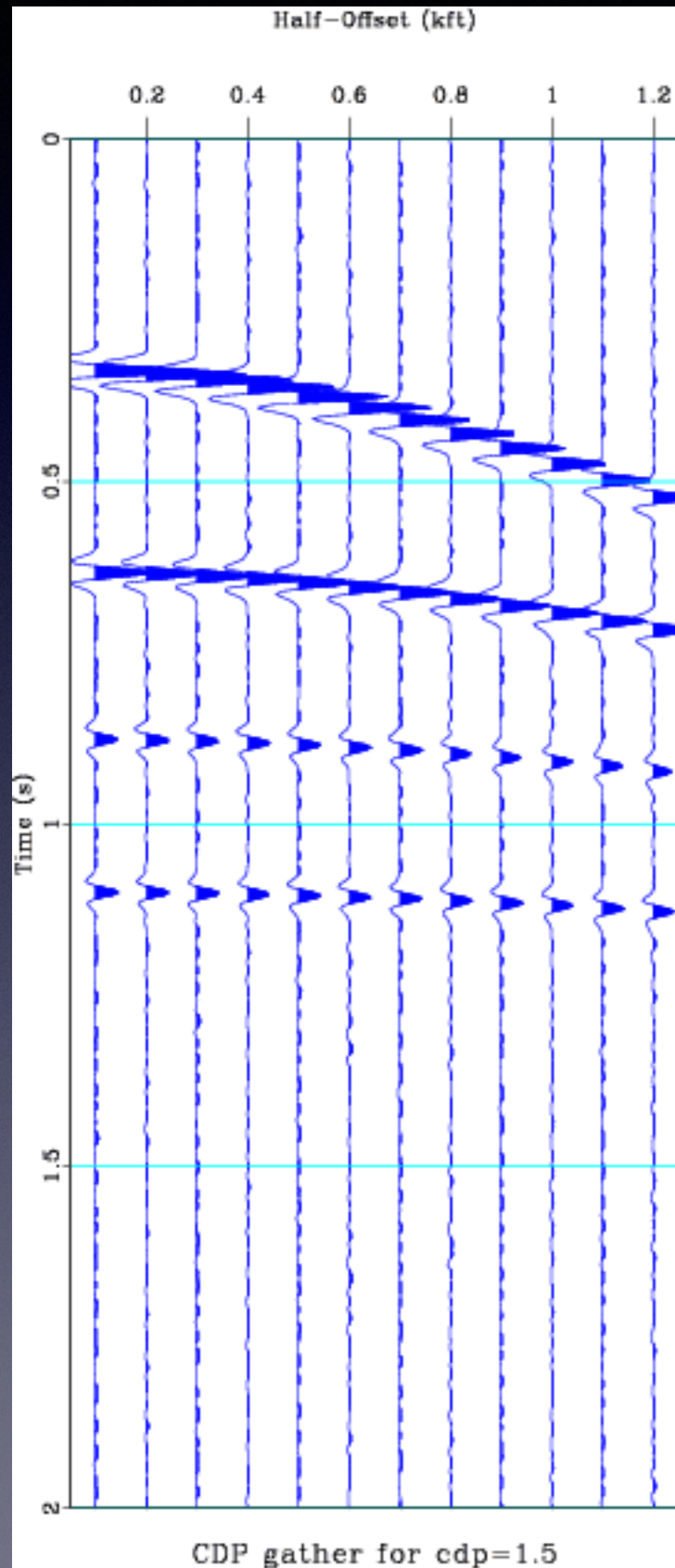
Es. Normal Move Out Correction



Metodi Sismici

Es. Normal Move Out -Velocity analysis

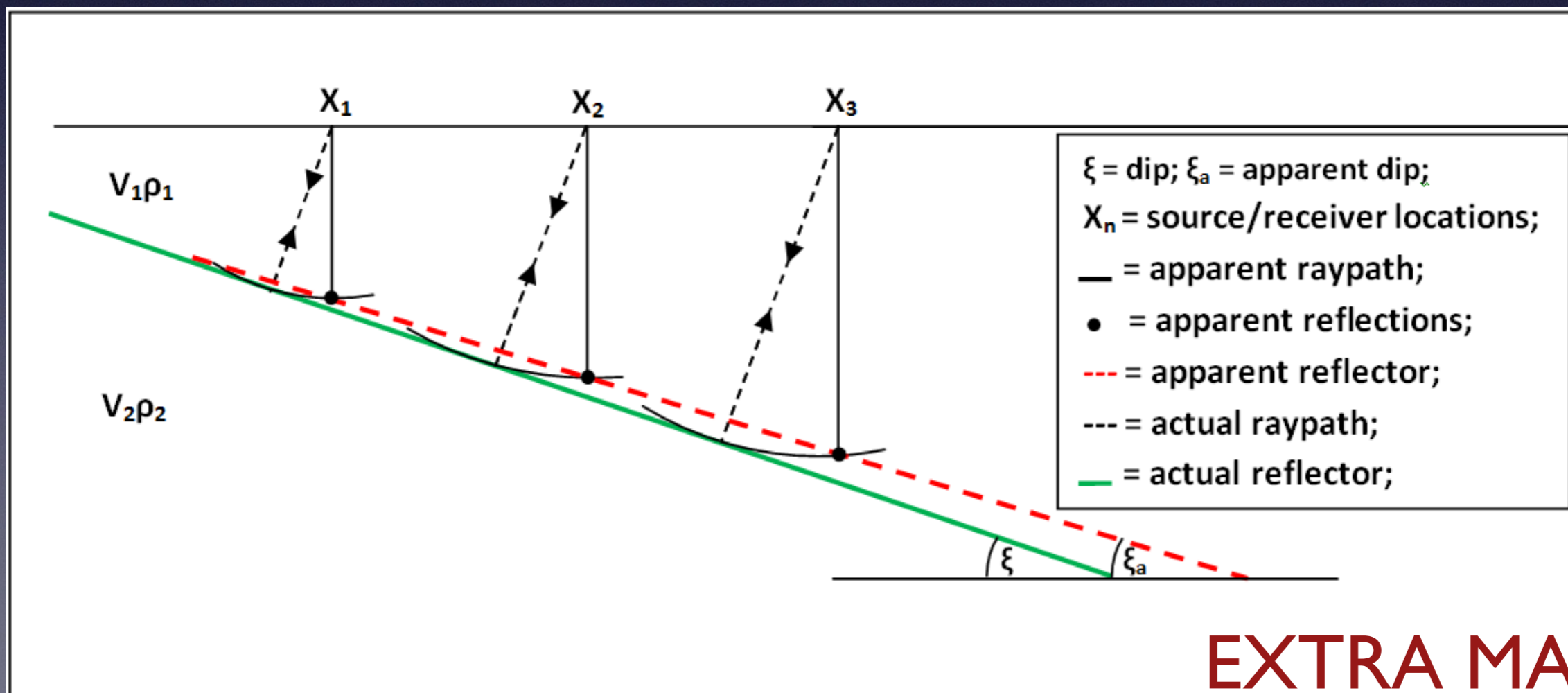
Multi-layers system



Migration

FROM TIME DOMAIN to SPACE DOMAIN

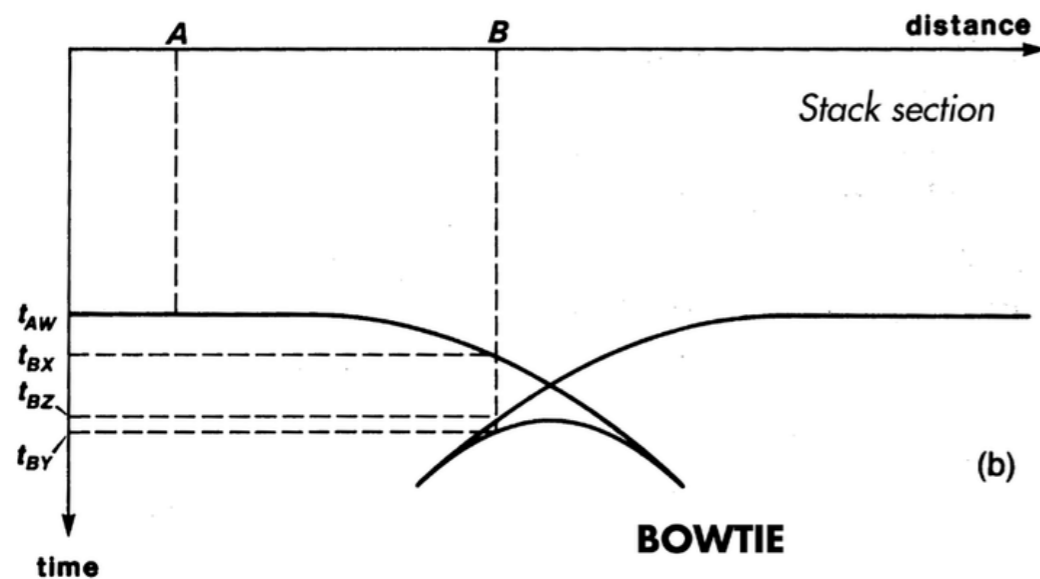
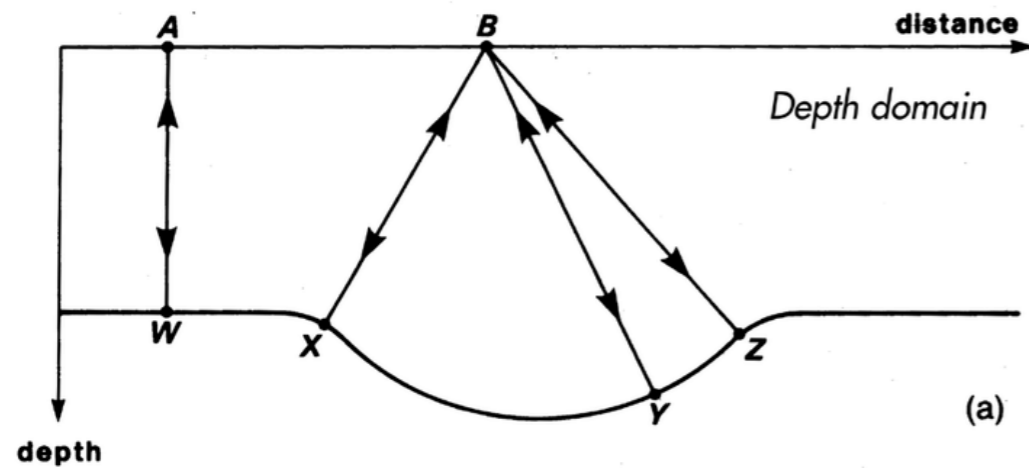
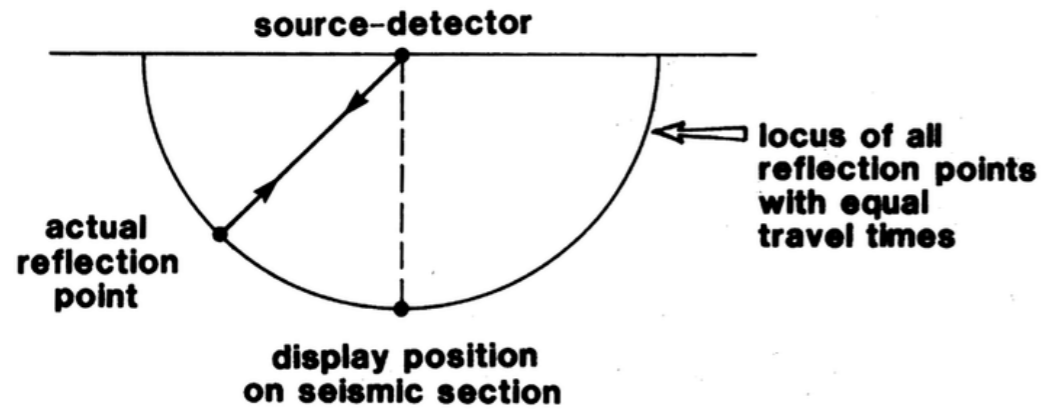
Seismic migration is the process by which seismic events are geometrically re-located in either space or time to the location the event occurred in the subsurface rather than the location that it was recorded at the surface, thereby creating a more accurate image of the subsurface.



Spheric wavefront

EXTRA MATERIAL

Migration



FROM TIME DOMAIN
to
SPACE DOMAIN

es.

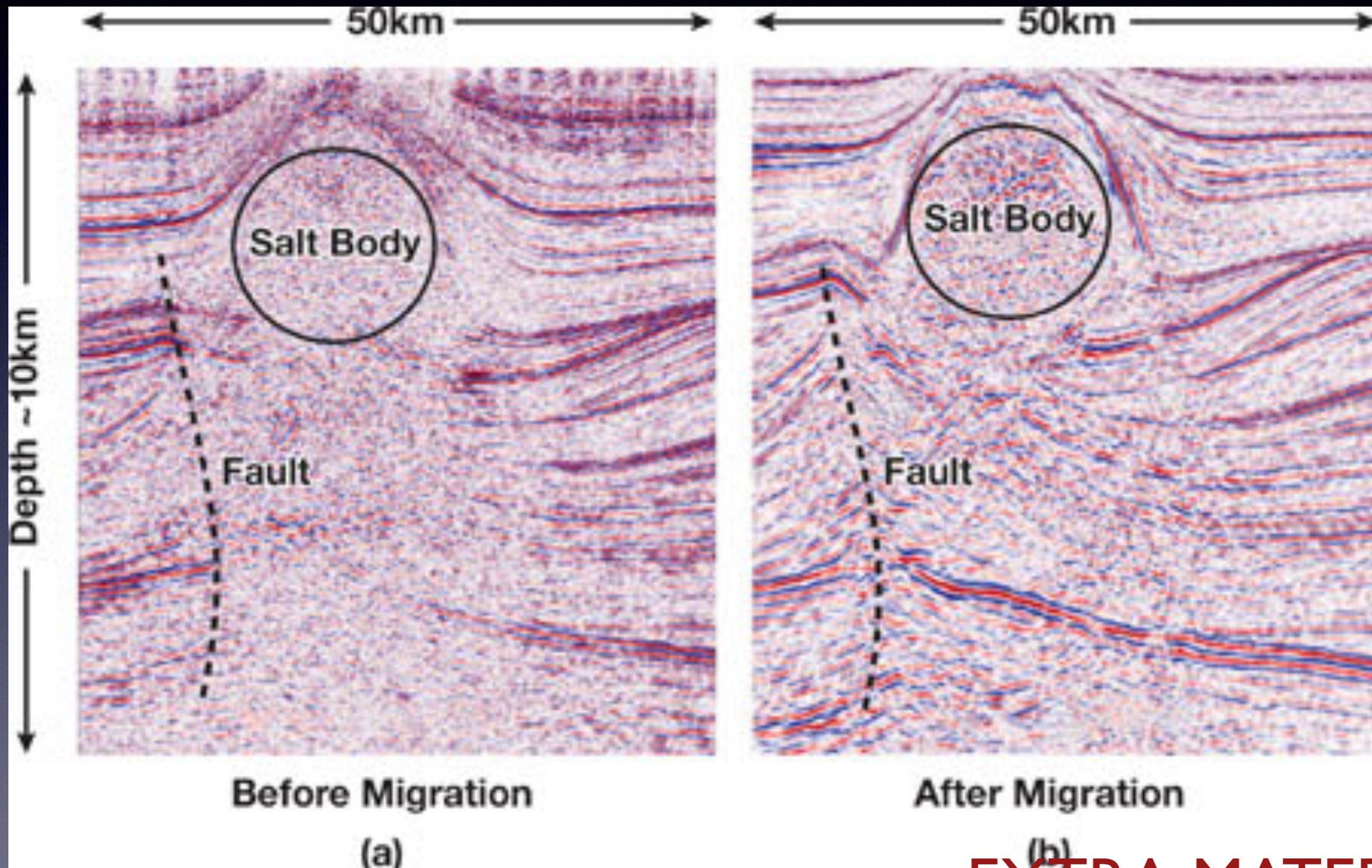
Kirchhoff migration

EXTRA MATERIAL

~30% of the world's CPU time is spent on seismic reflection processing (from stanford.pangea)

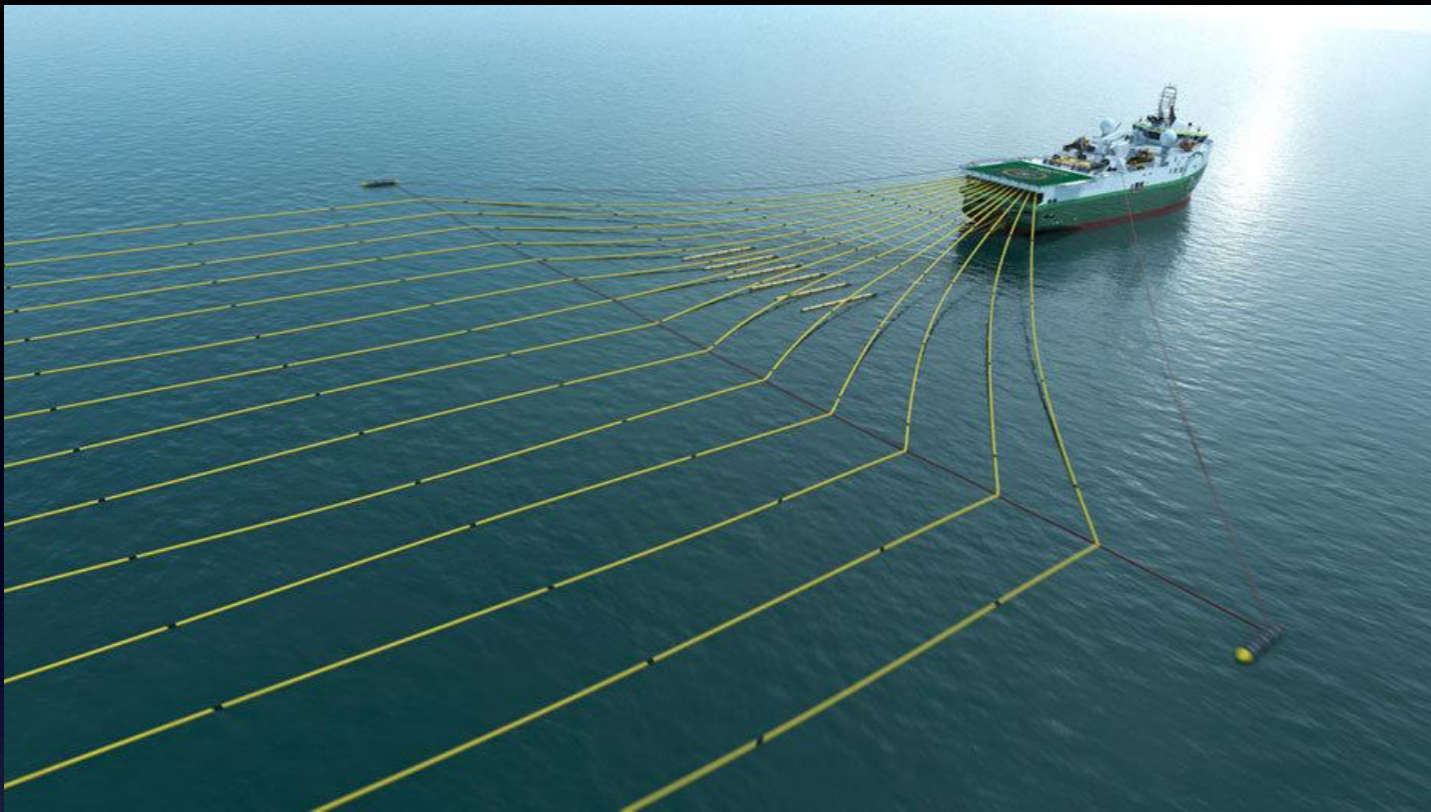
Metodi Sismici

*Migrazione: Passare da DOMINIO TEMPO a DOMINIO PROFONDITA'
(note le velocità)*



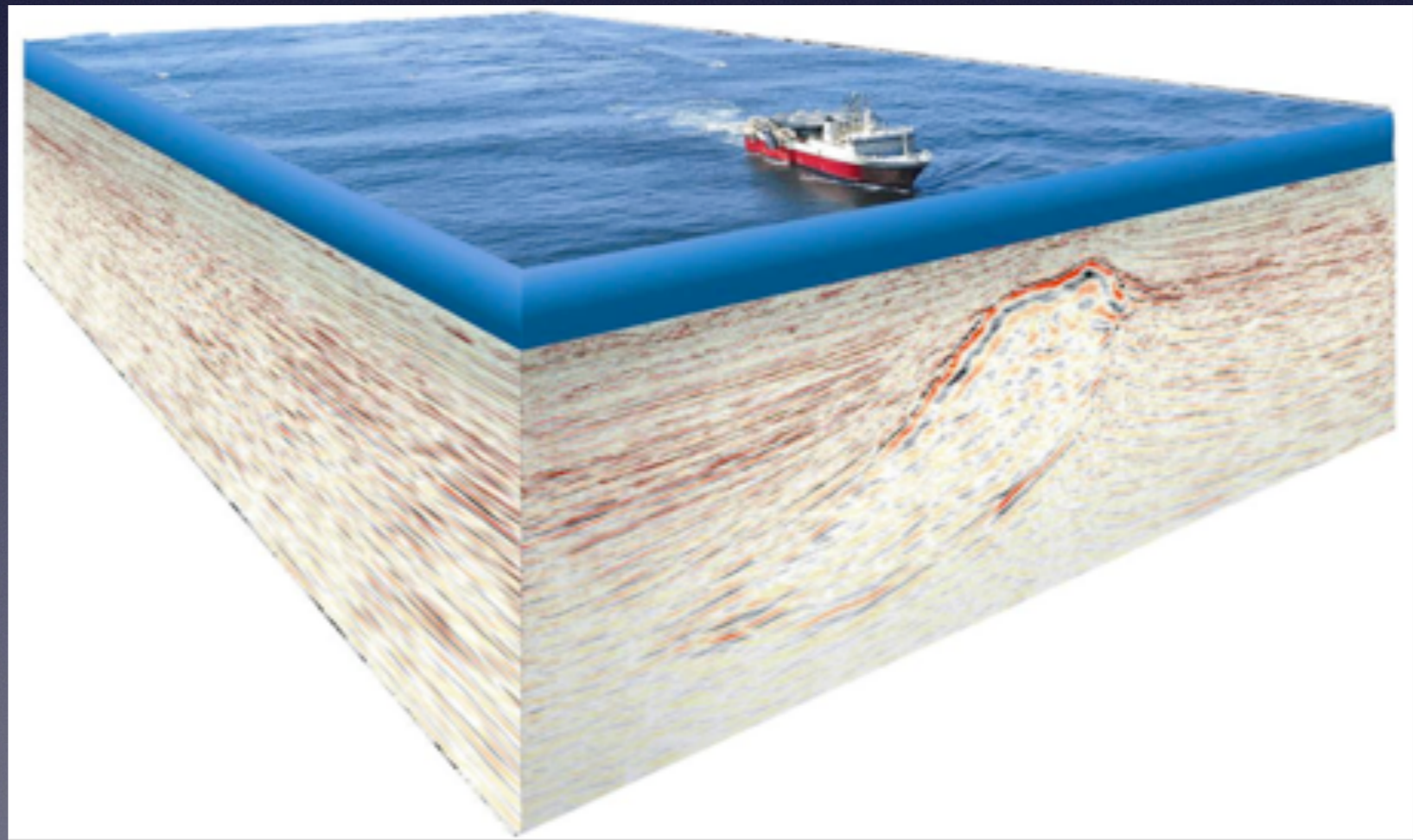
EXTRA MATERIAL

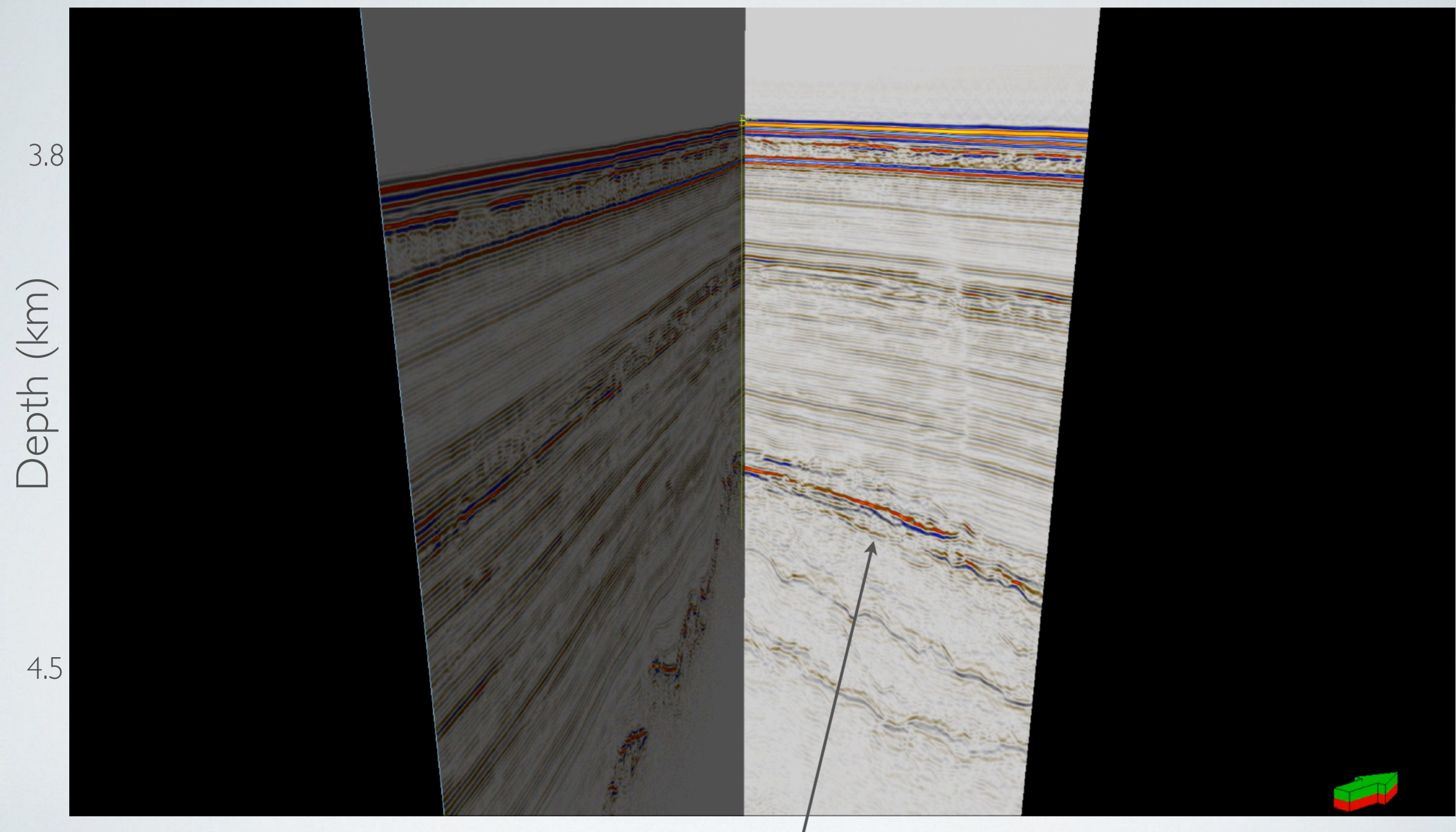
Seismic methods



Reflection seismic

seismic imaging

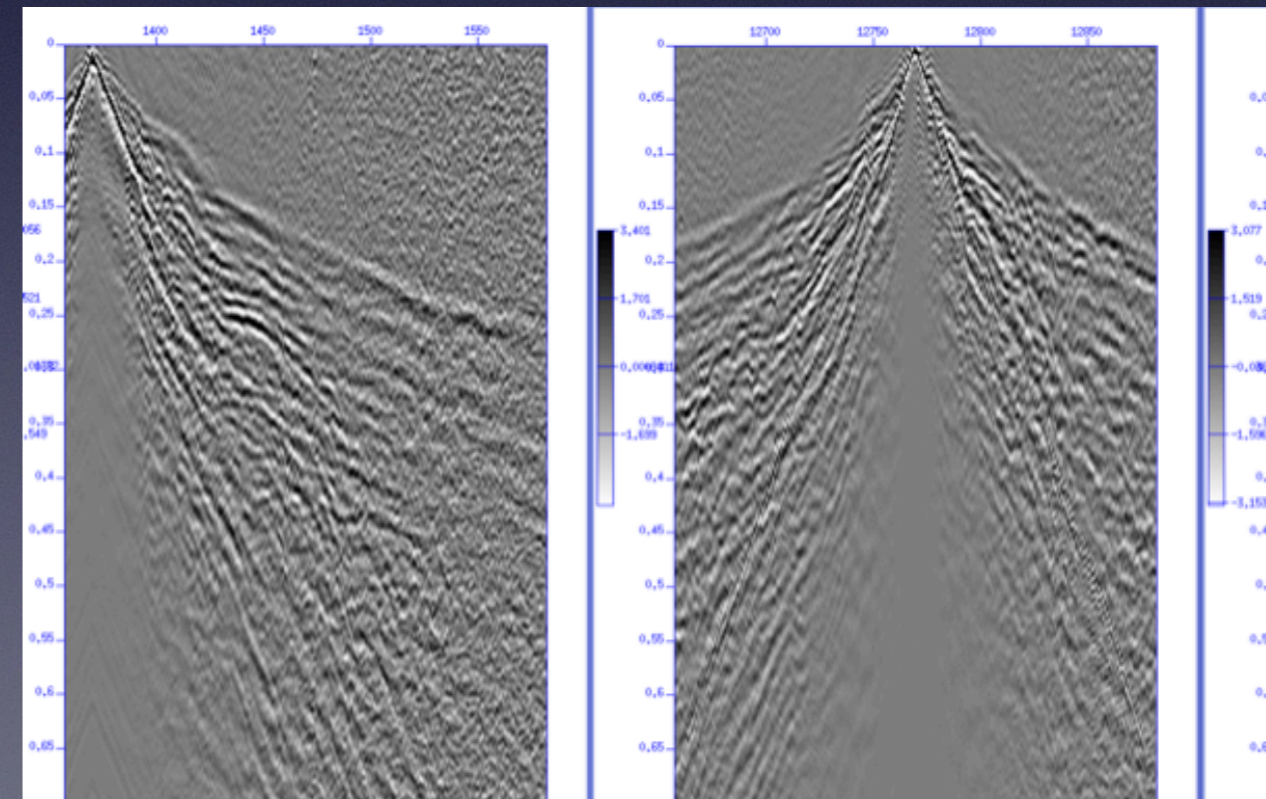
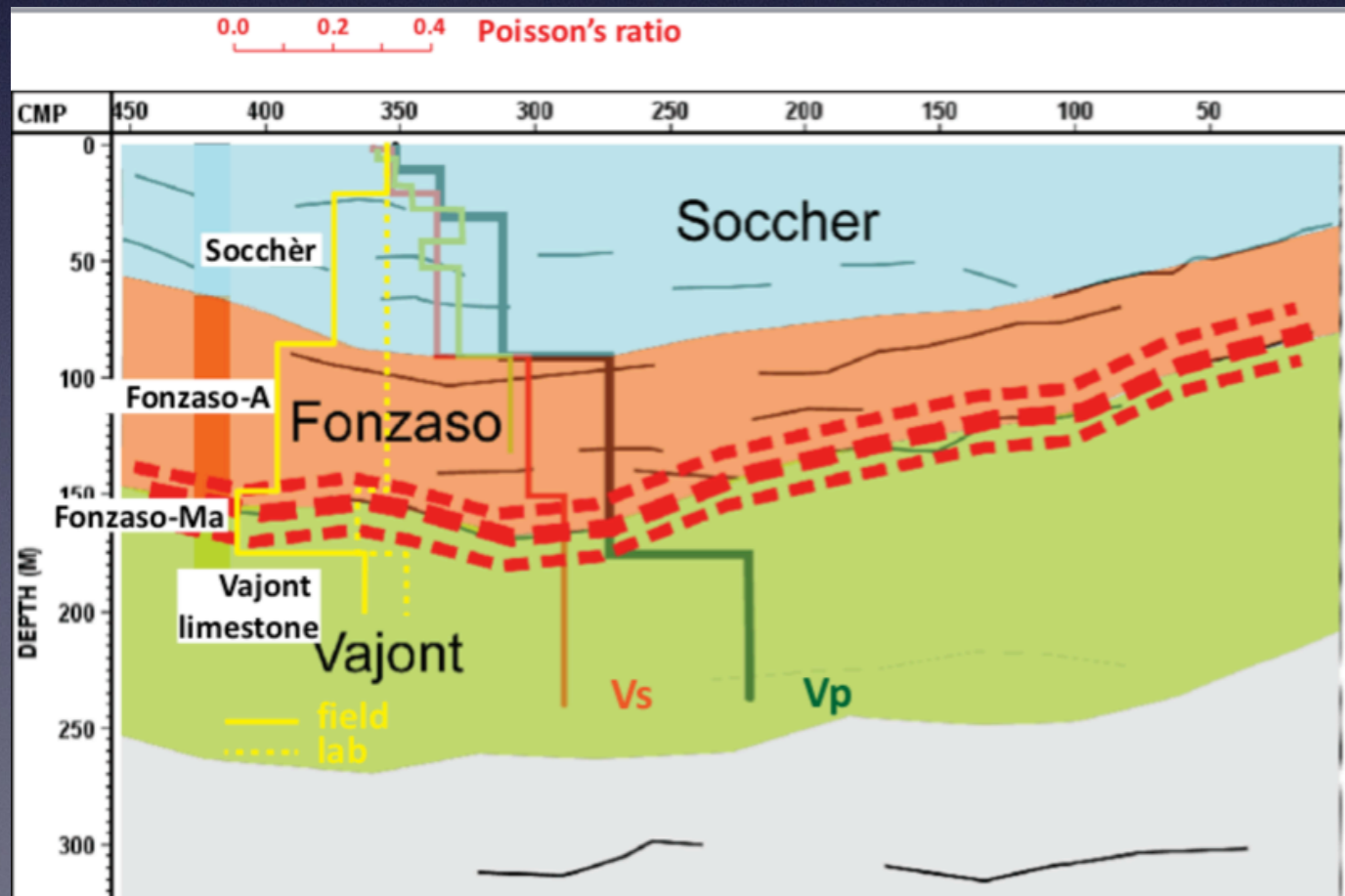
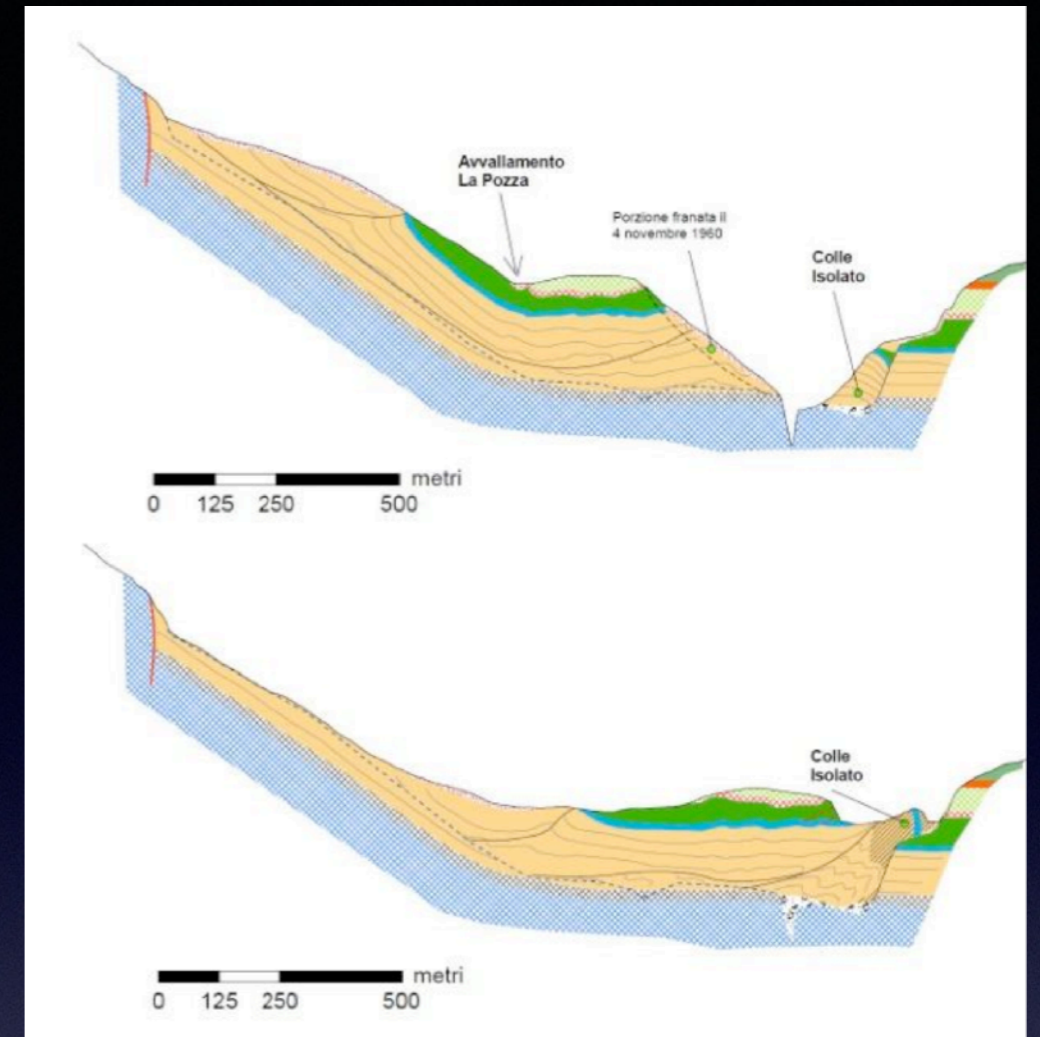




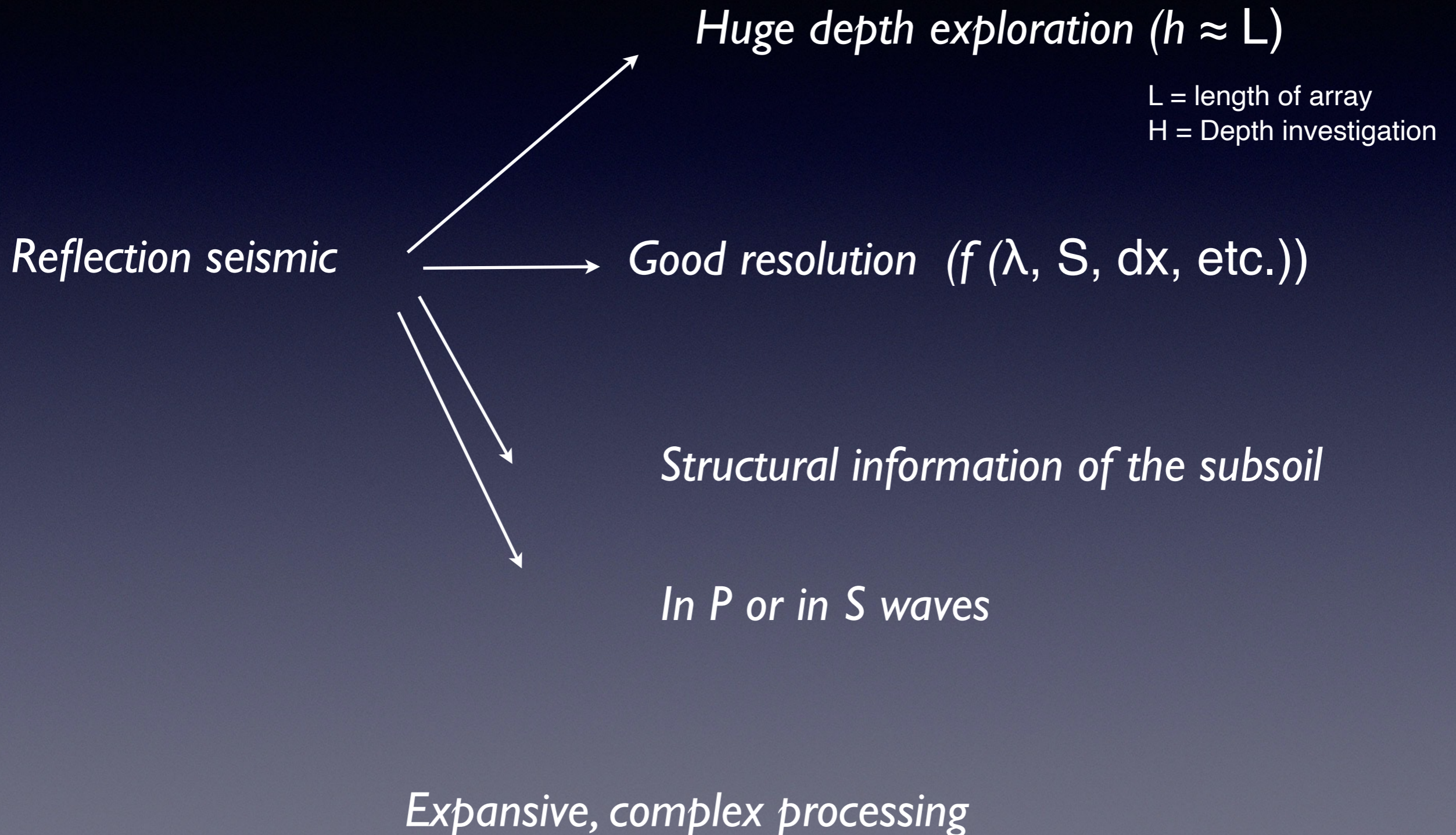
Rock Basement

Example of engineering application

Vajont landslide seismic reflection



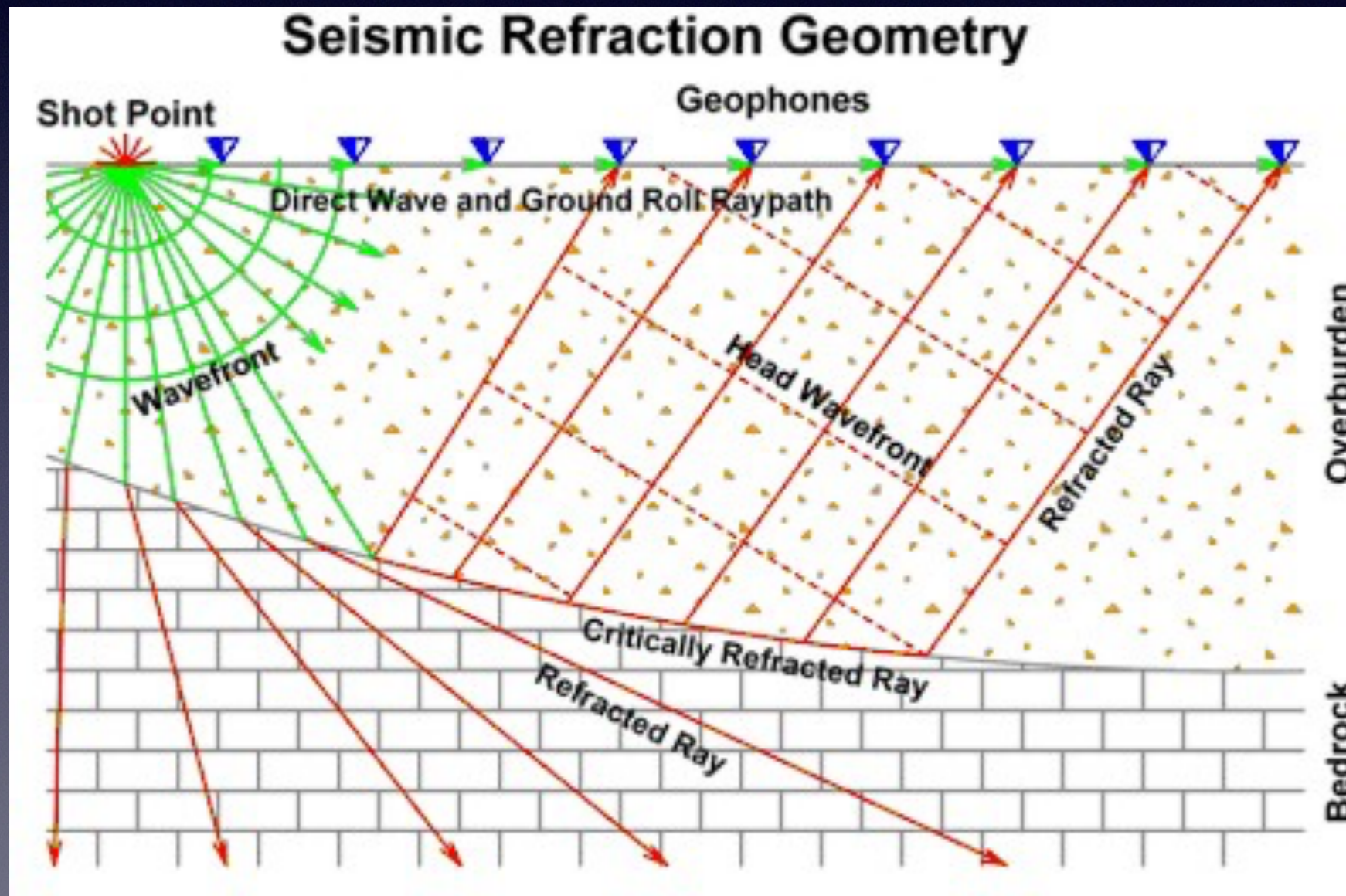
Seismic Methods



For the engineering purpose, most diffused is the:

REFRACTION seismic

Studying *refracted waves* to characterise velocity and depth of buried layers

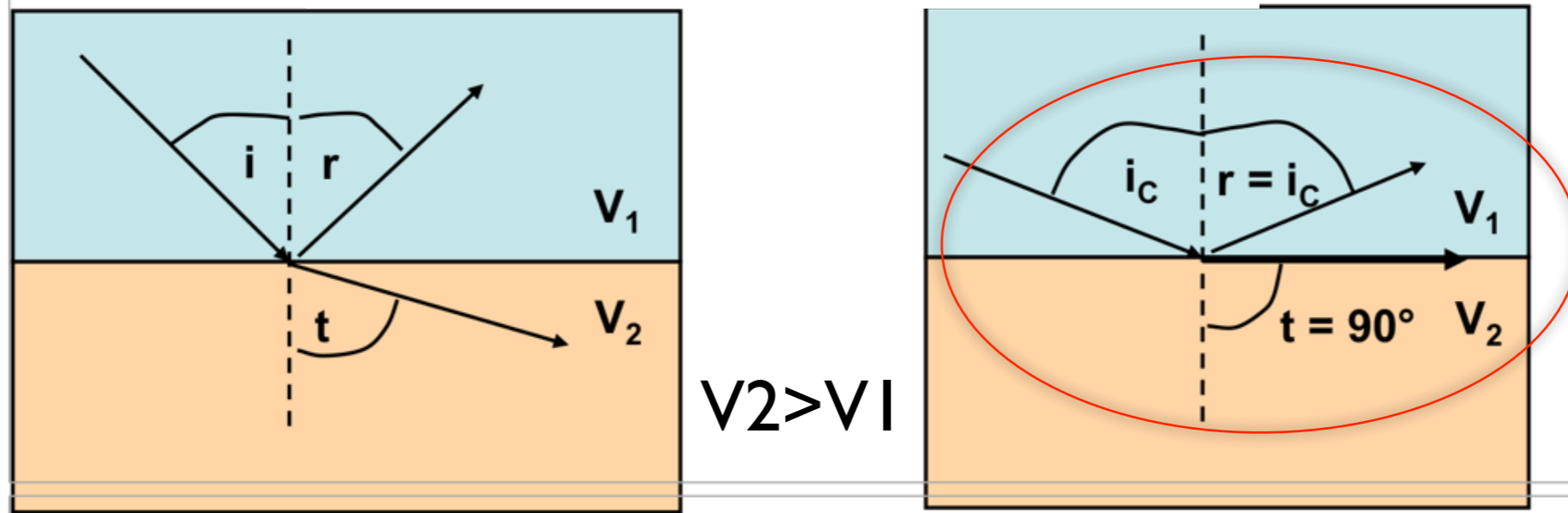


Critically refracted waves

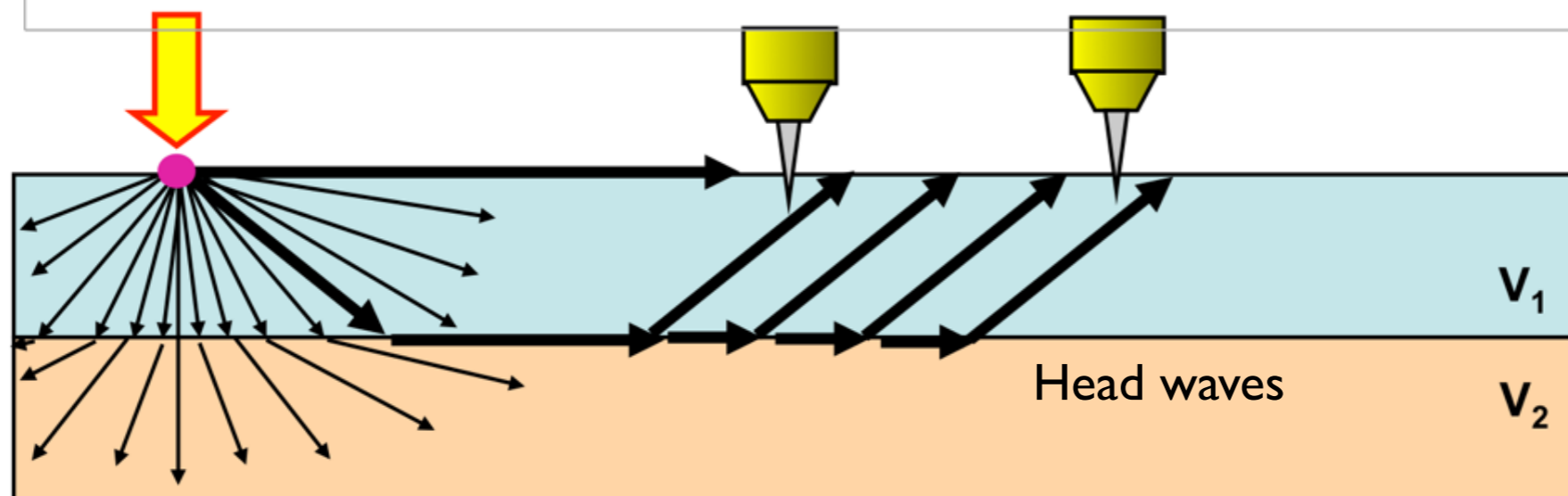
Head-waves

REFRACTION

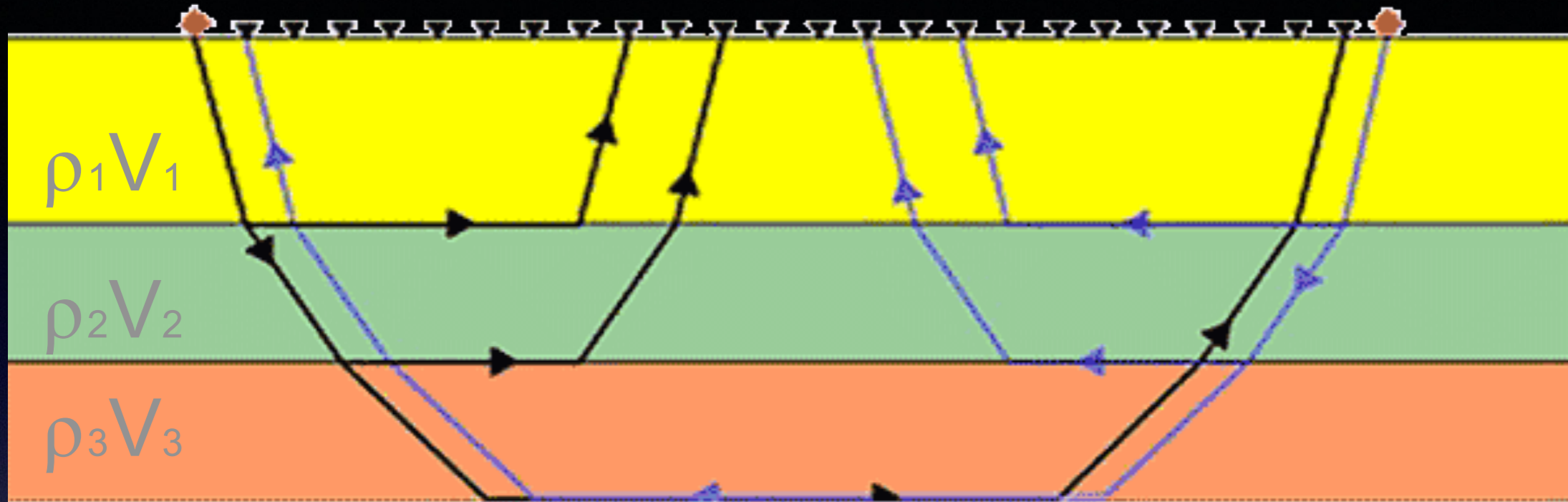
Snell Law for critical reflection



Time arrival study in function of distance of travel paths



Refraction Seismic methods



Impedance Contrast = $\frac{\rho_2 V_2}{\rho_1 V_1} > 1$ \rightarrow REFRACTION

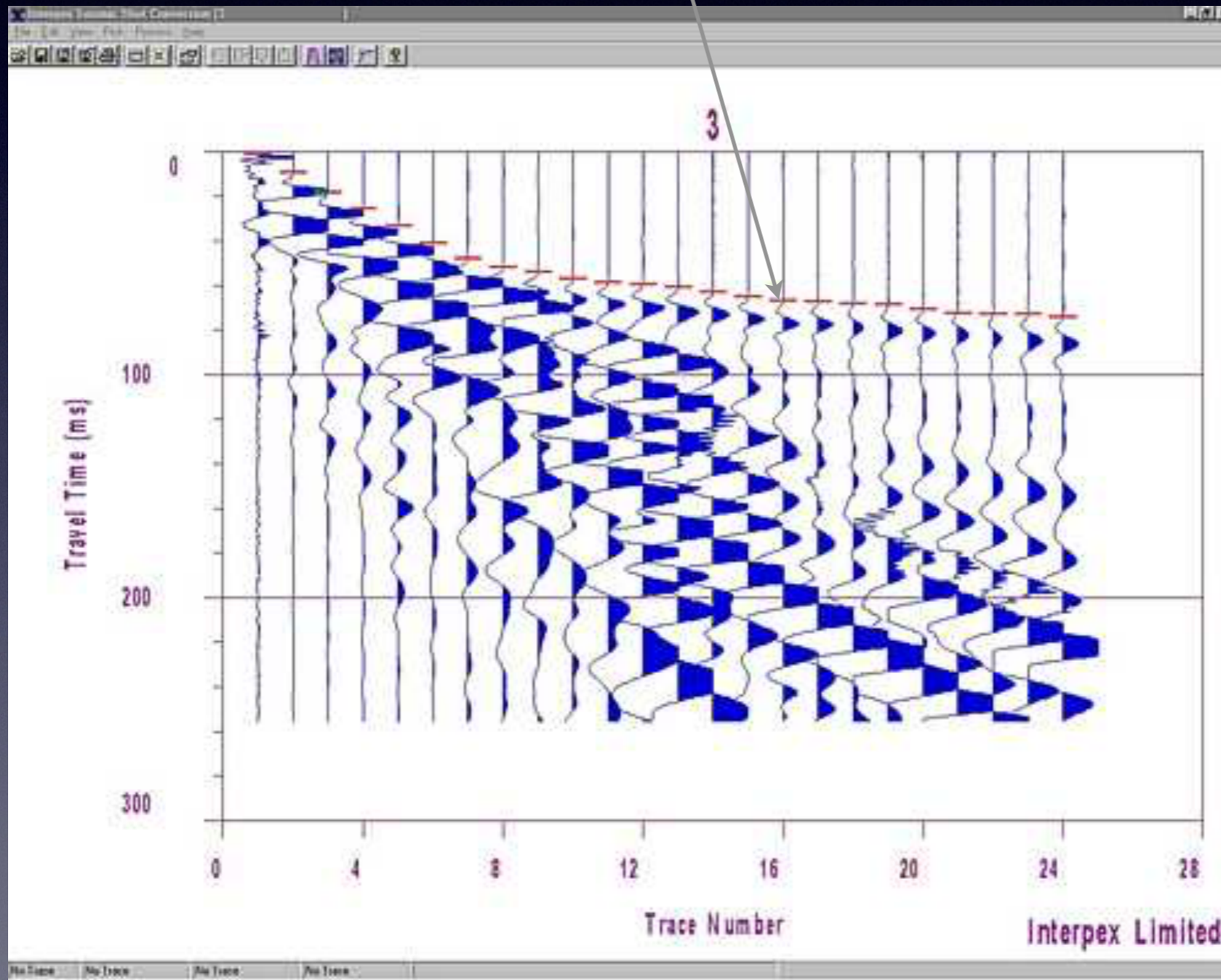
If $V_2 < V_1$ NO REFRACTION !

\rightarrow Blind to inversion velocity in depth

Refraction seismic

Measuring the time arrival of the generated seismic waves....

first break Picking



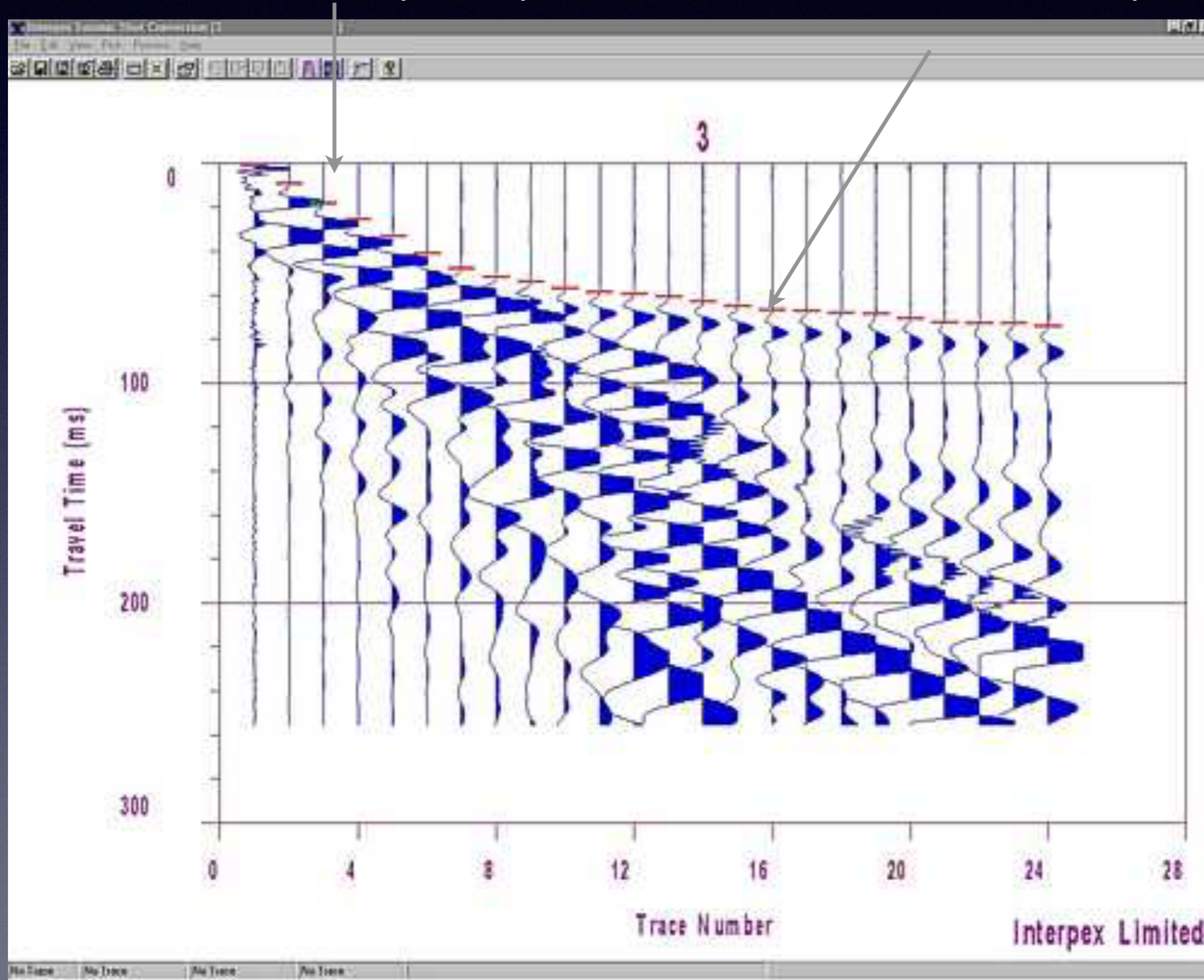
Refraction seismic

Measuring the time arrival of the generated seismic waves....

first break Picking

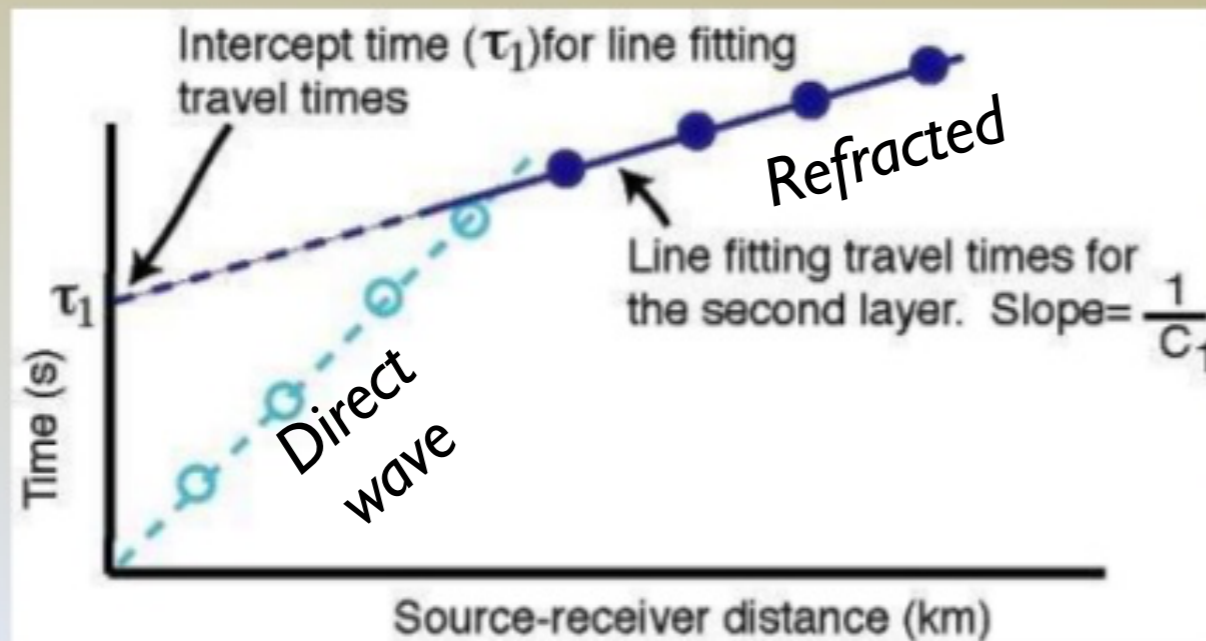
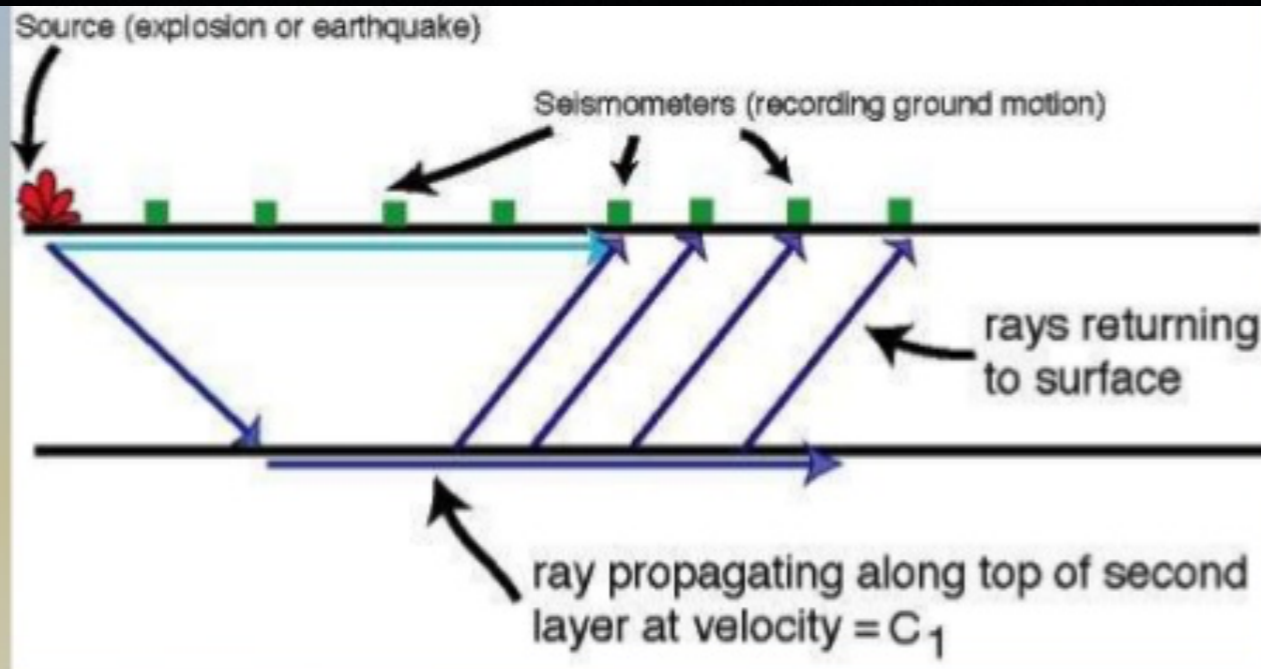
Direct wave (slow)

Refracted wave (fast)



2 straight lines are identified (In the case of 2 layers)

REFRACTION



Measuring time arrival

Direct and refracted Waves

$$\text{Slope of the dromocrhone} = \frac{1}{V}$$

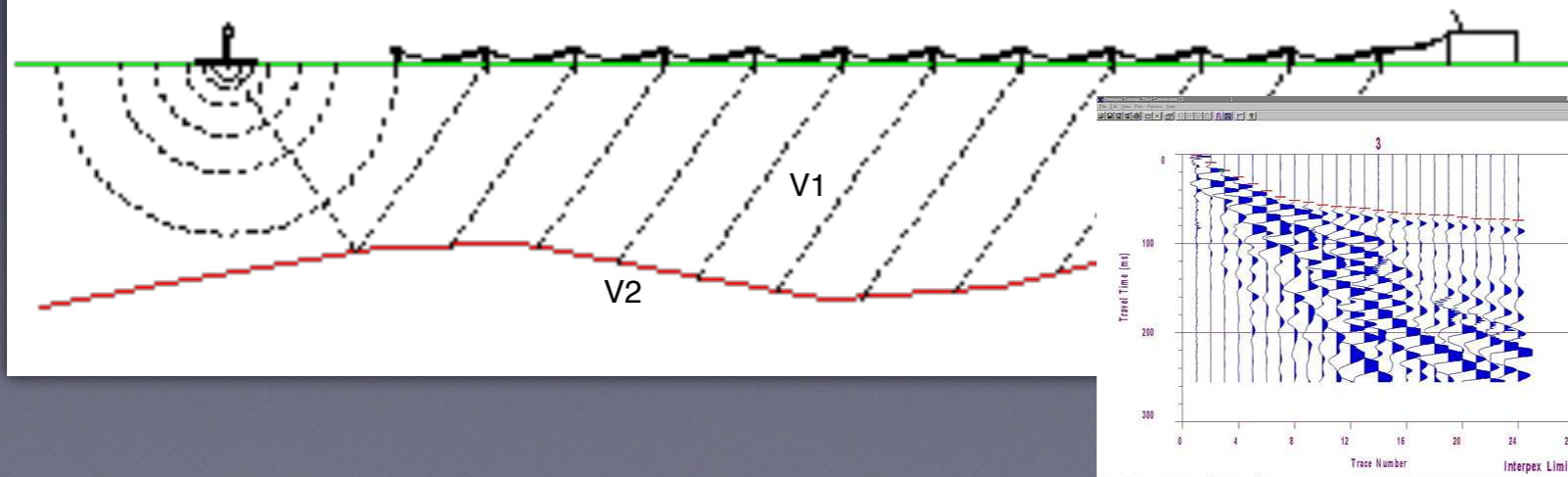
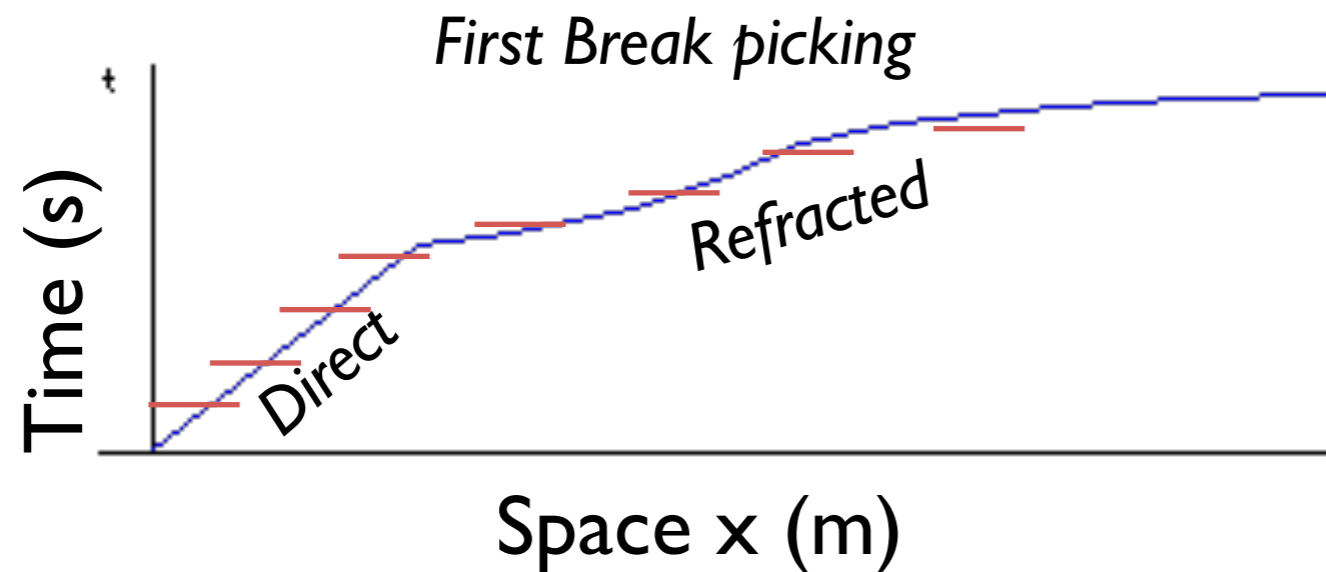
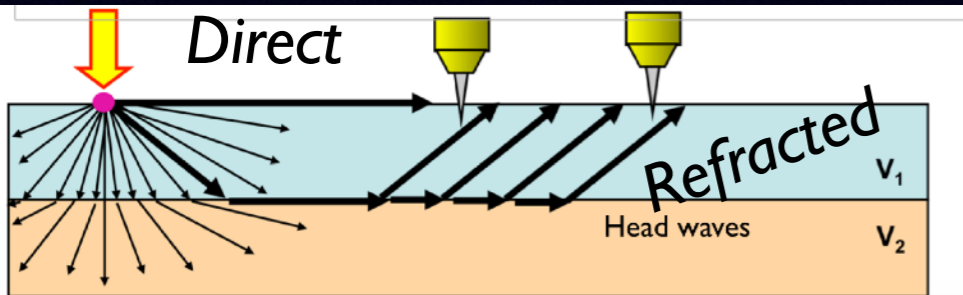
Straight line $\Rightarrow ax+by+c=0$

$$y = mx + q \quad m = \text{angular coef. (Slope)} = -\frac{a}{b}$$

Refraction Seismic

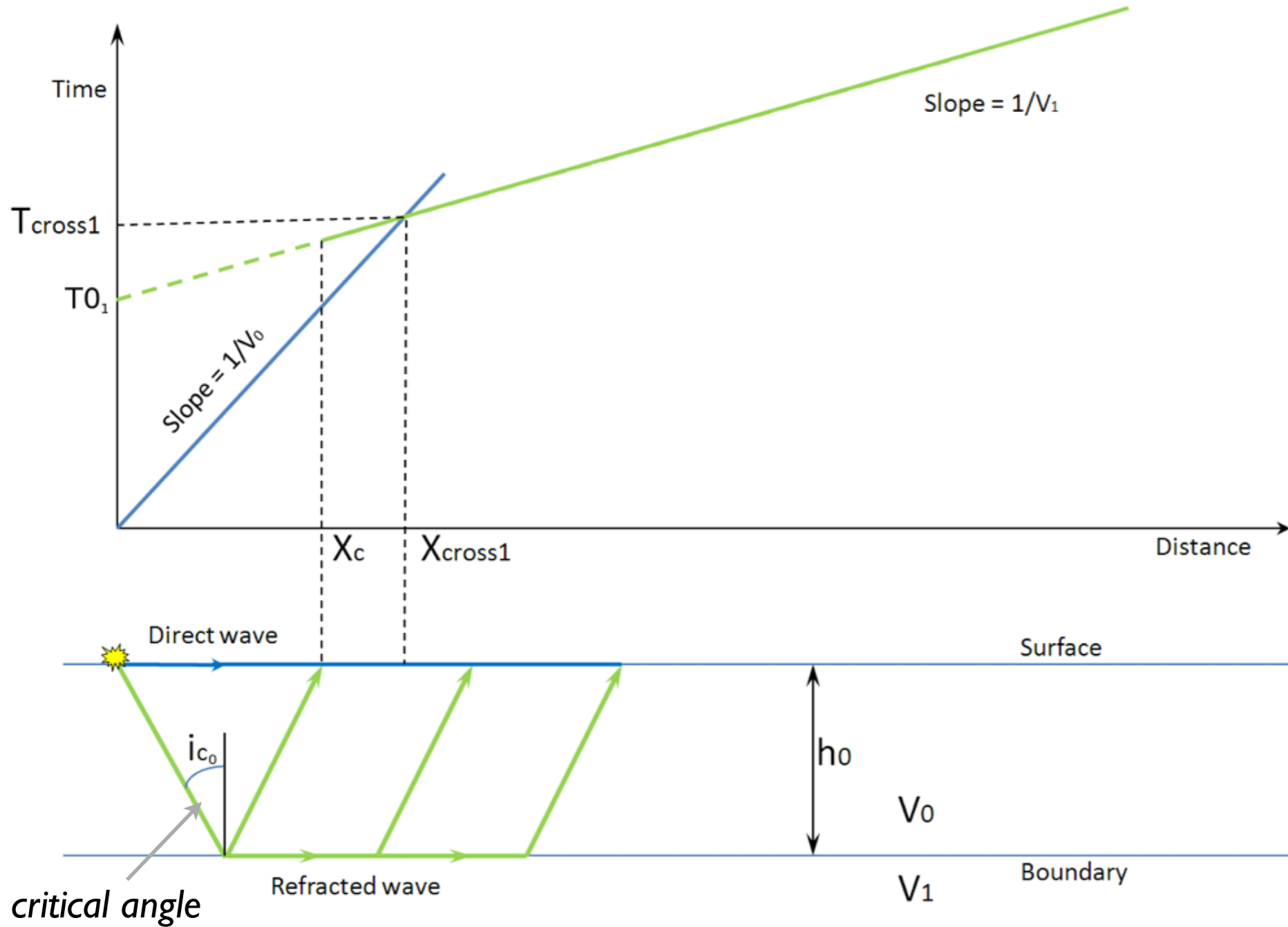
Time arrivals first break Picking

In a space-time diagram (dromochrone)



Dromochrone =
Travel-Time curves

REFRACTION SEISMIC

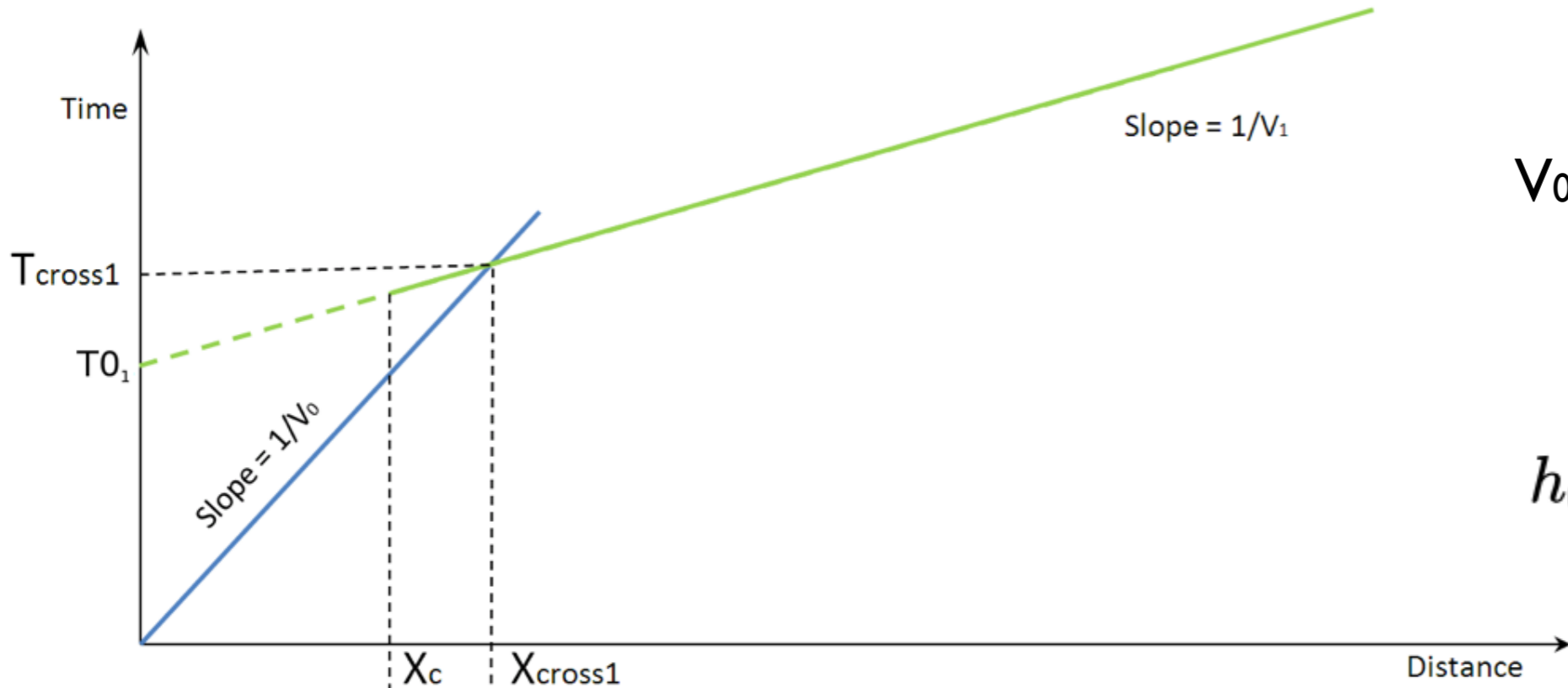


1) Slope of the dromochrone

2) X_{cross}
Crossover
point distance

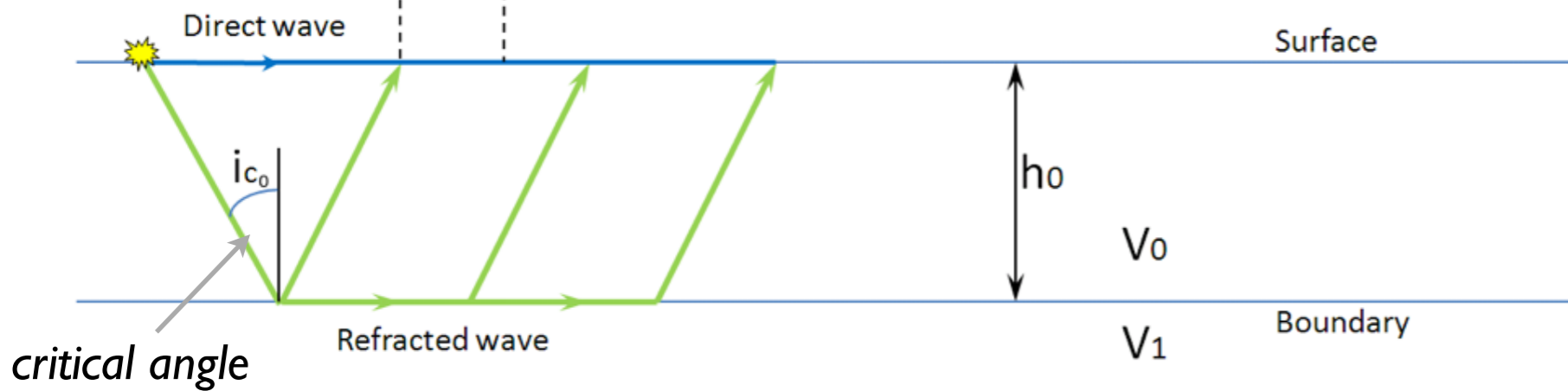
3) T_0
Intercept time

REFRACTION SEISMIC



V_0 and V_1 from the slope

$$h_0 = \frac{X_{cross1}}{2} \sqrt{\frac{V_1 - V_0}{V_1 + V_0}}$$

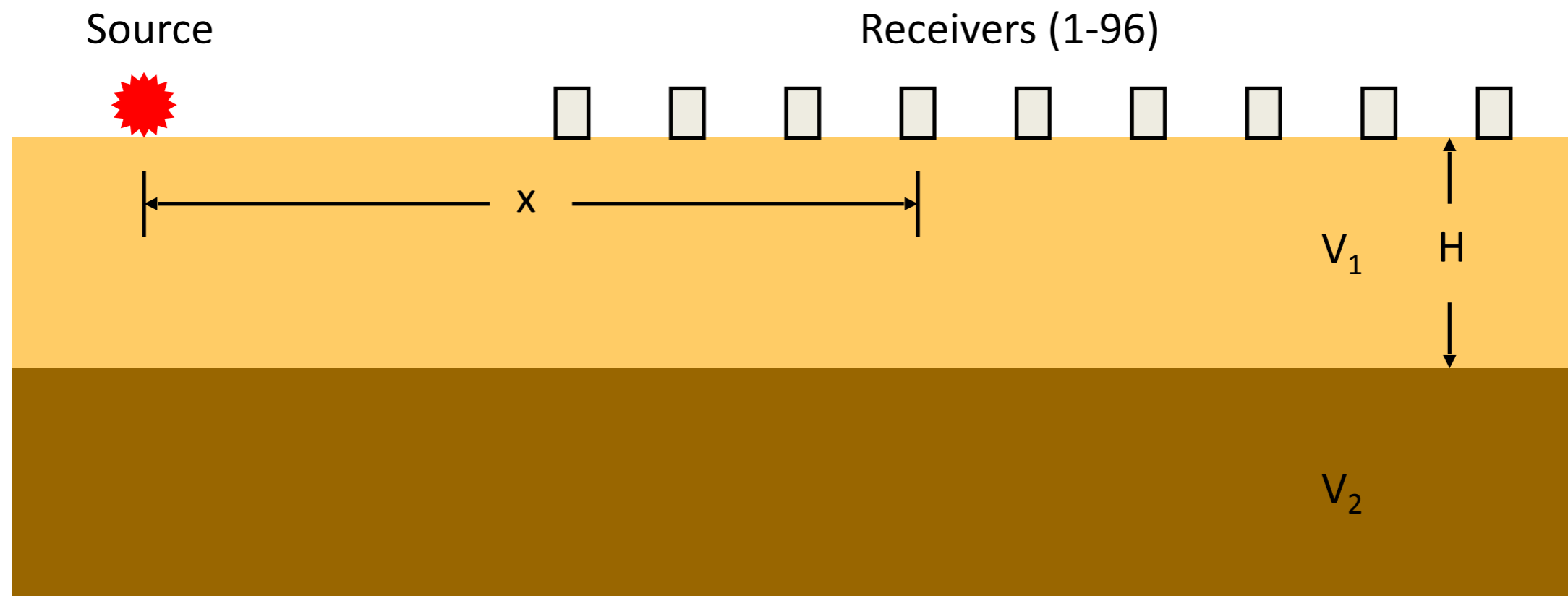


$$h_0 = \frac{1}{2} T_0 \frac{v_1 v_2}{\sqrt{v_2^2 - v_1^2}}$$

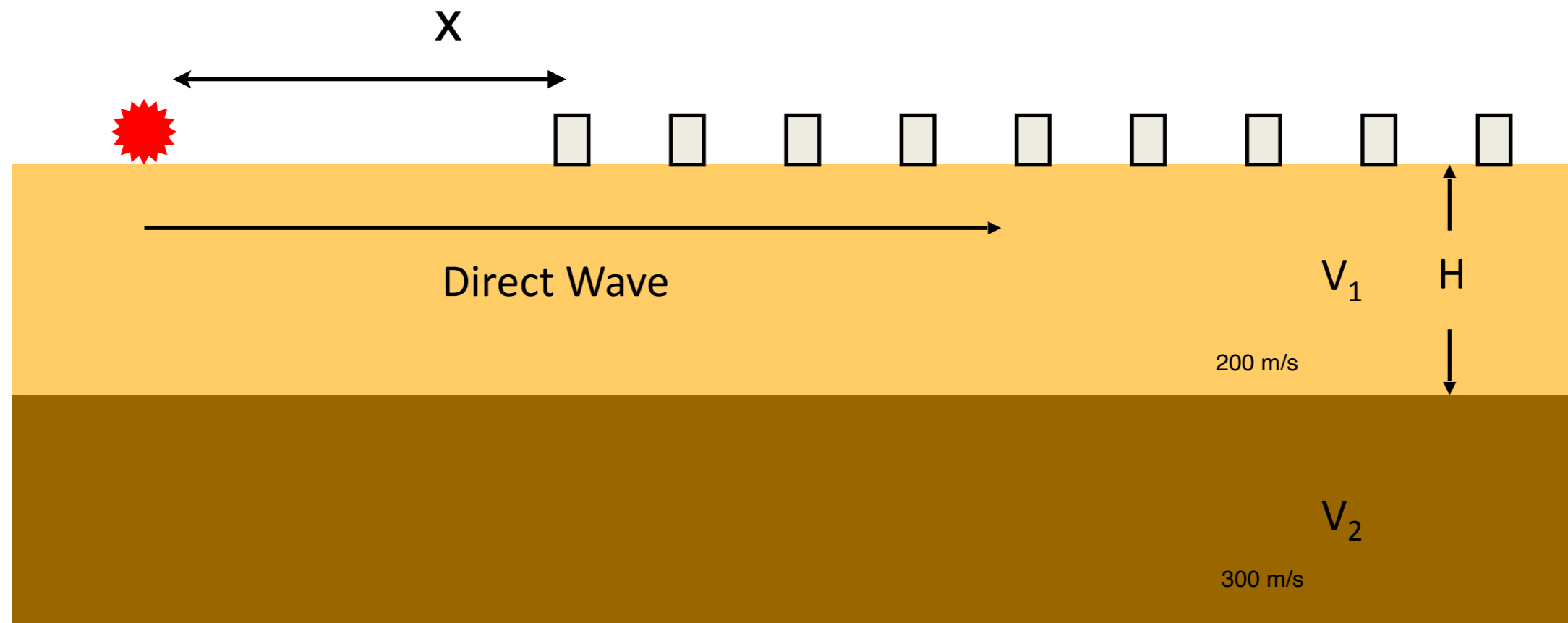
T_0 intercept time

Velocity and thickness of the layers !

Acquisition



Seismic Refraction

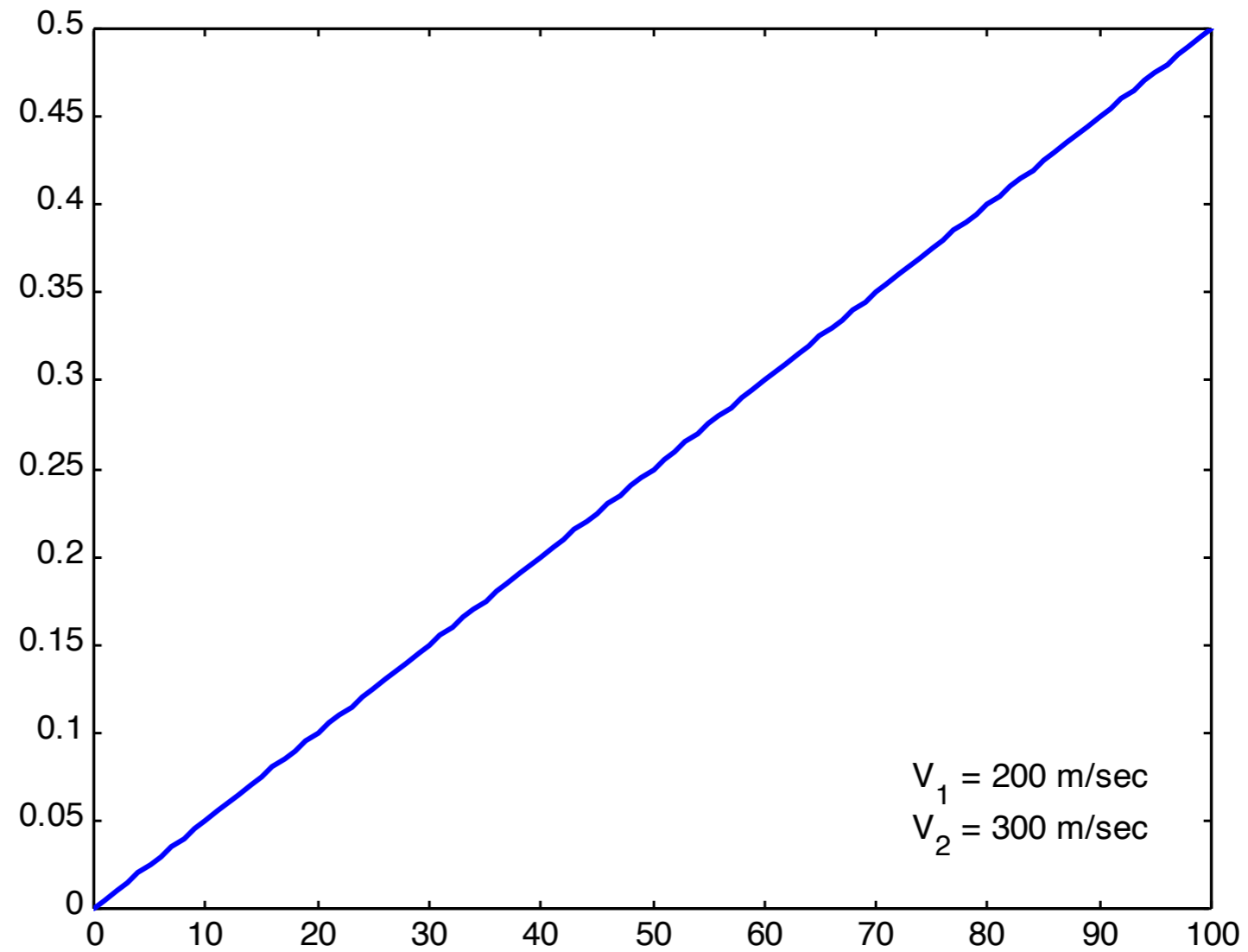


$$t_{direct} = \frac{x}{V_1}$$

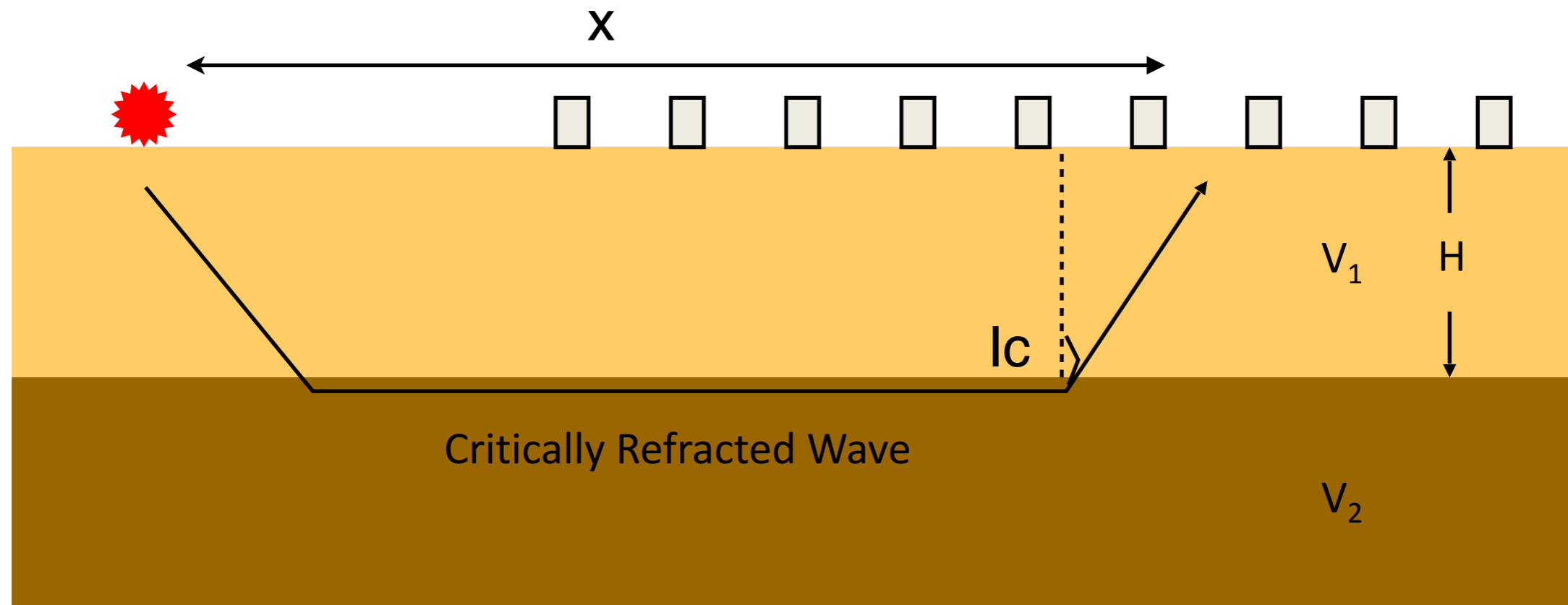


Seismic Refraction

$$t_{direct} = \frac{x}{V_1}$$



Seismic Refraction



$$t_{\text{refract}} = \frac{2H}{V_1 \cos i_c} + \frac{x - 2H \tan i_c}{V_2}$$

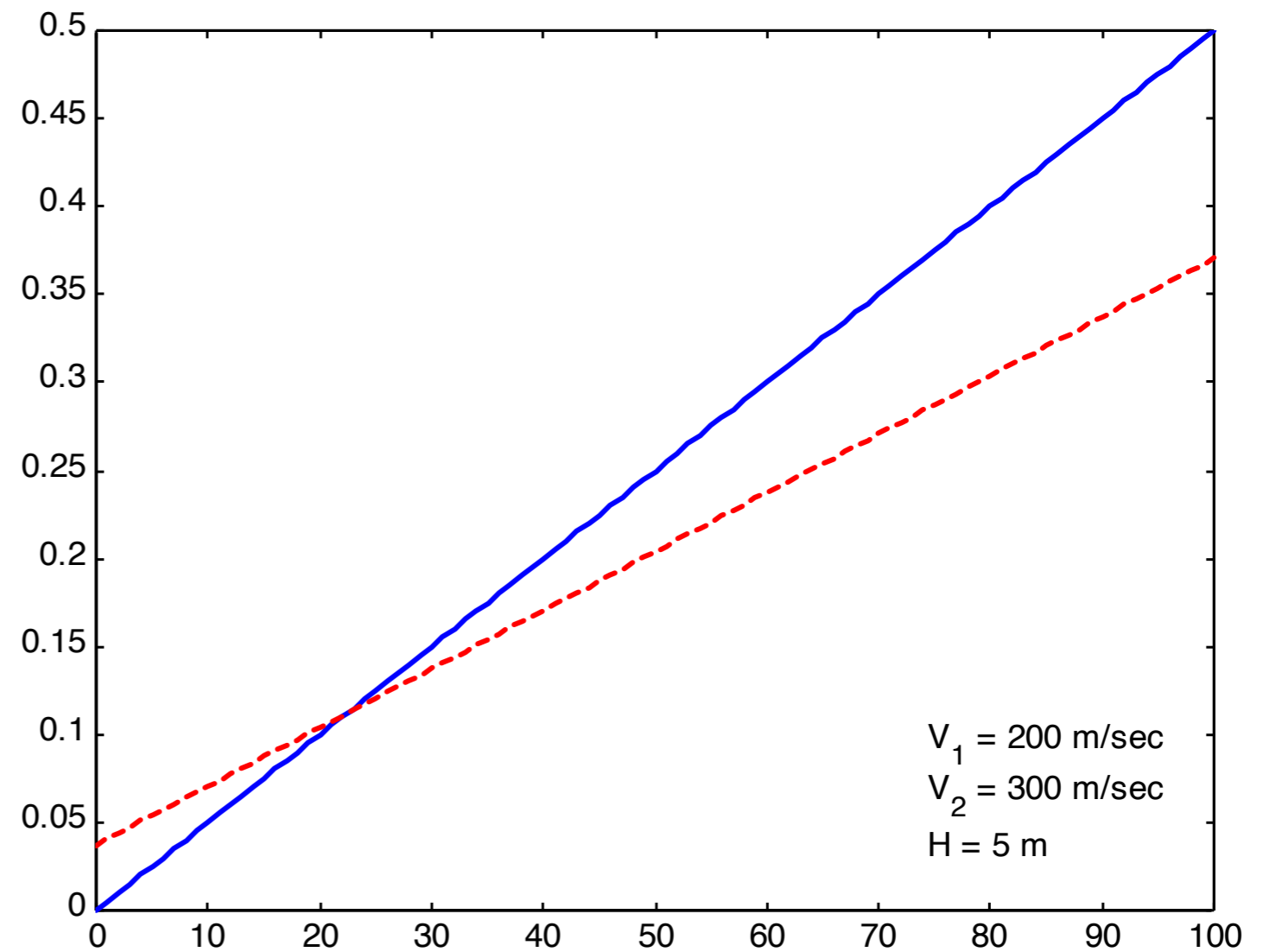
$$= \frac{x}{V_2} + 2H \sqrt{\frac{1}{V_1^2} - \frac{1}{V_2^2}}$$



Seismic Refraction

$$t_{\text{refract}} = \frac{2H}{V_1 \cos i_c} + \frac{x - 2H \tan i_c}{V_2}$$

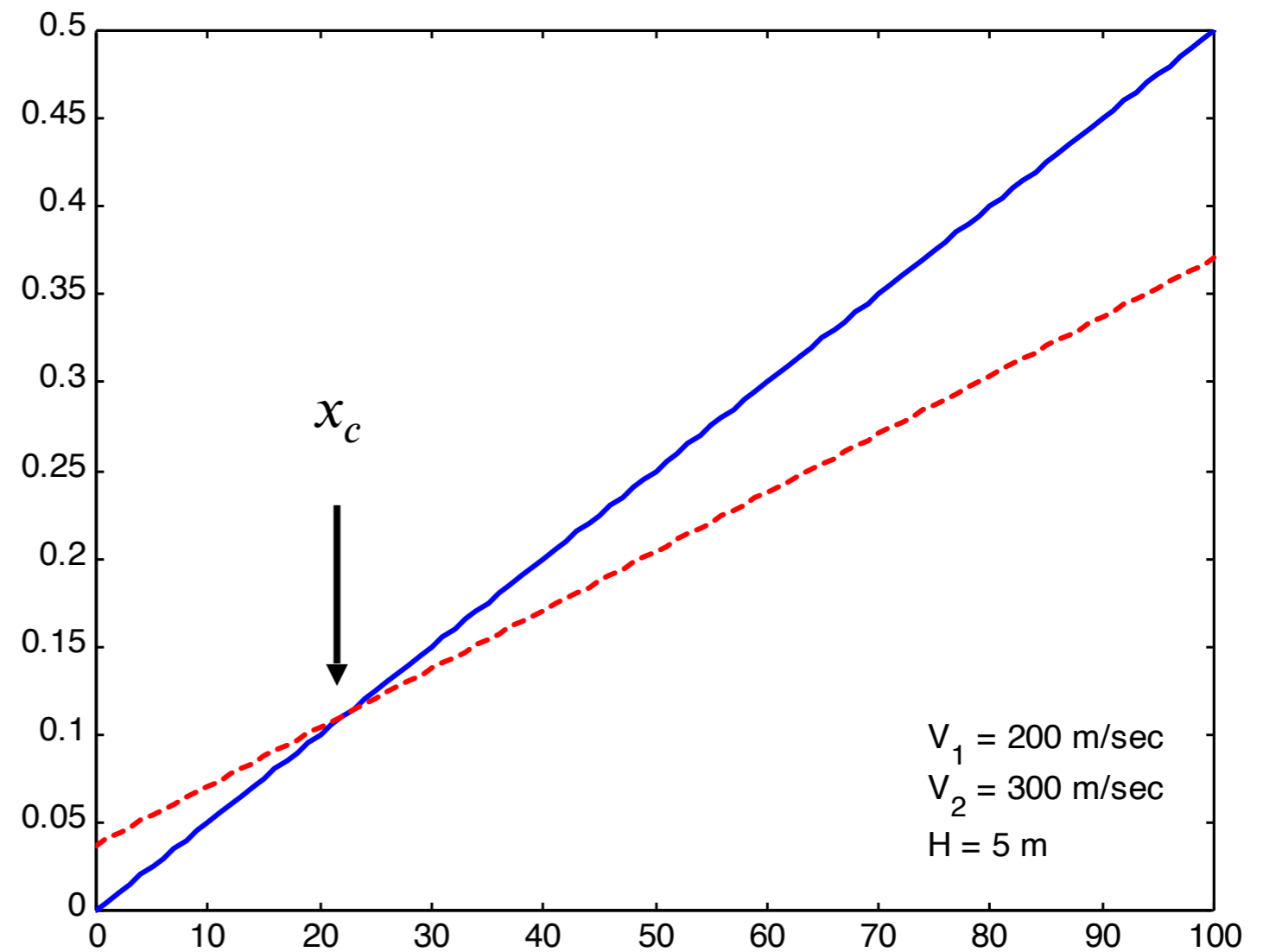
$$= \frac{x}{V_2} + 2H \sqrt{\frac{1}{V_1^2} - \frac{1}{V_2^2}}$$



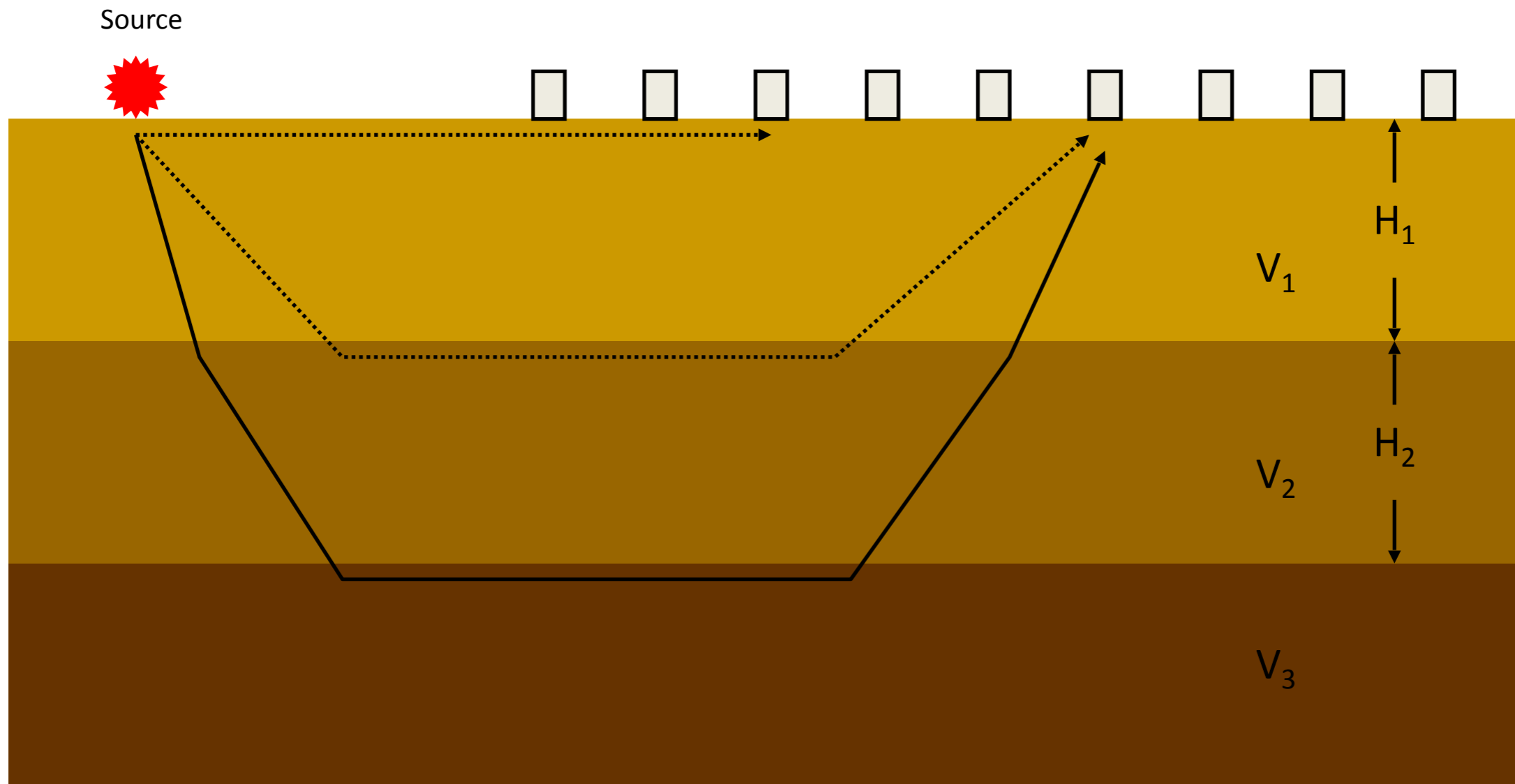
Seismic Refraction

$$x_c = 2H \sqrt{\frac{V_2 + V_1}{V_2 - V_1}}$$

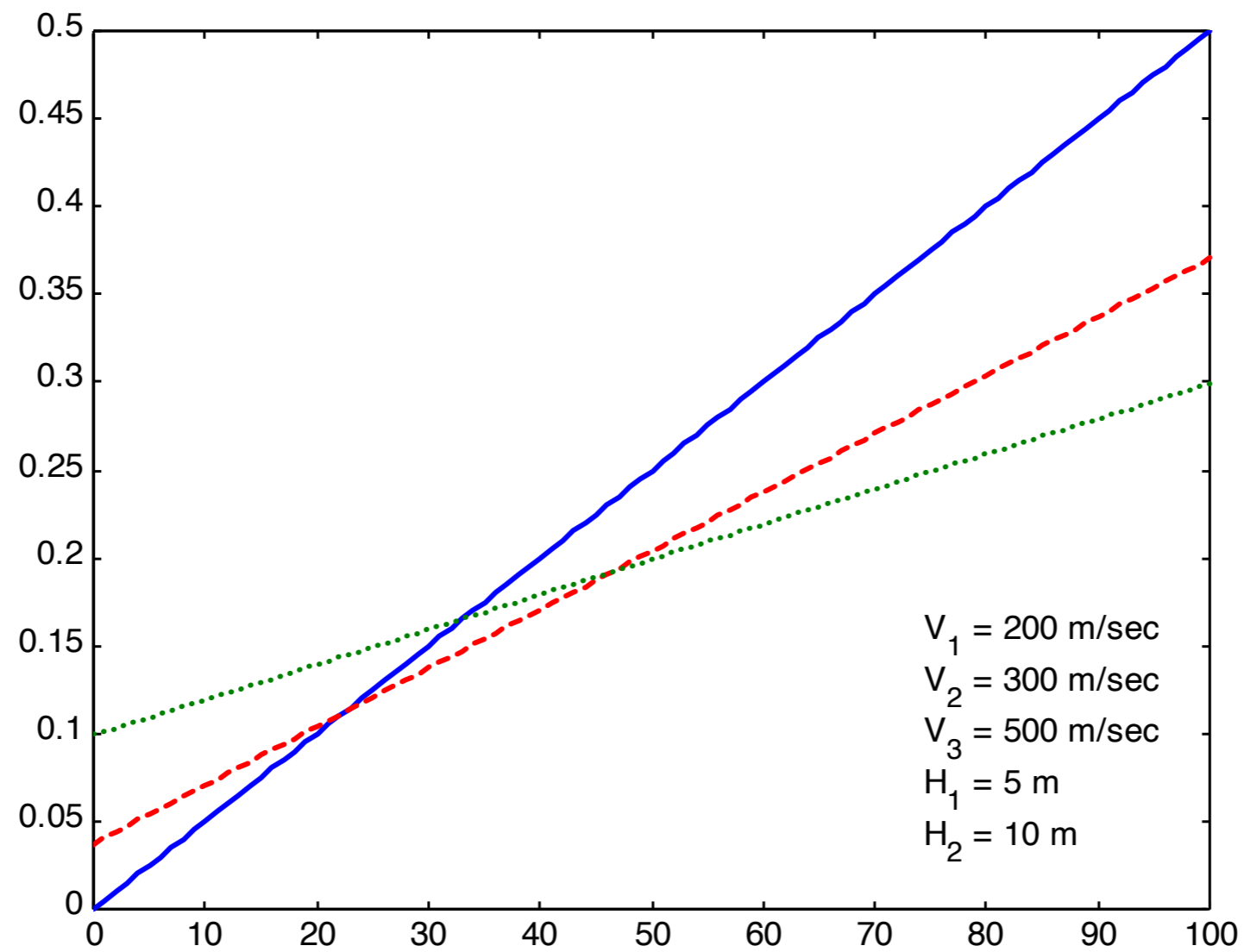
$$H = \frac{x_c}{2} \sqrt{\frac{V_2 - V_1}{V_2 + V_1}}$$



Seismic Refraction

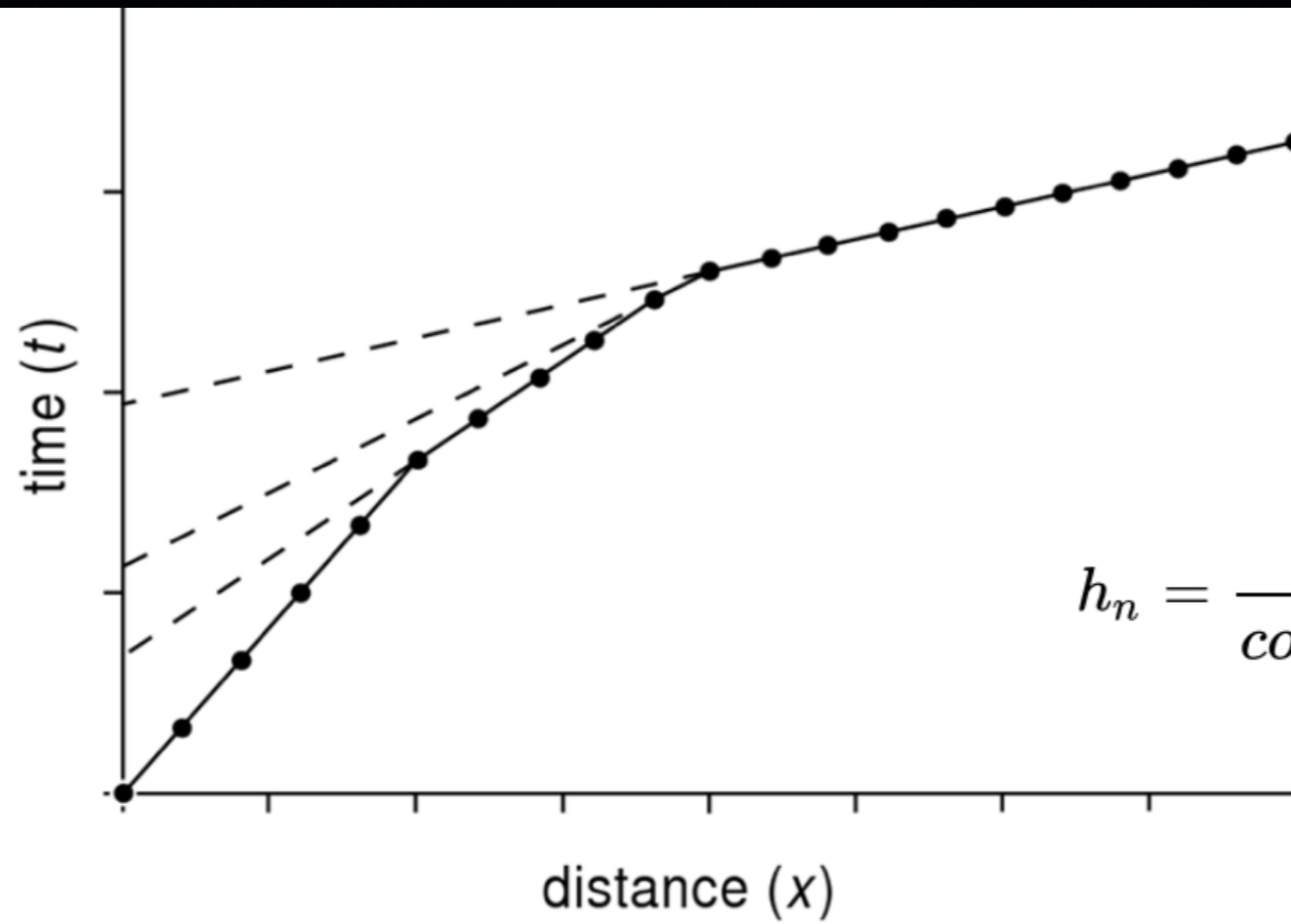


Seismic Refraction



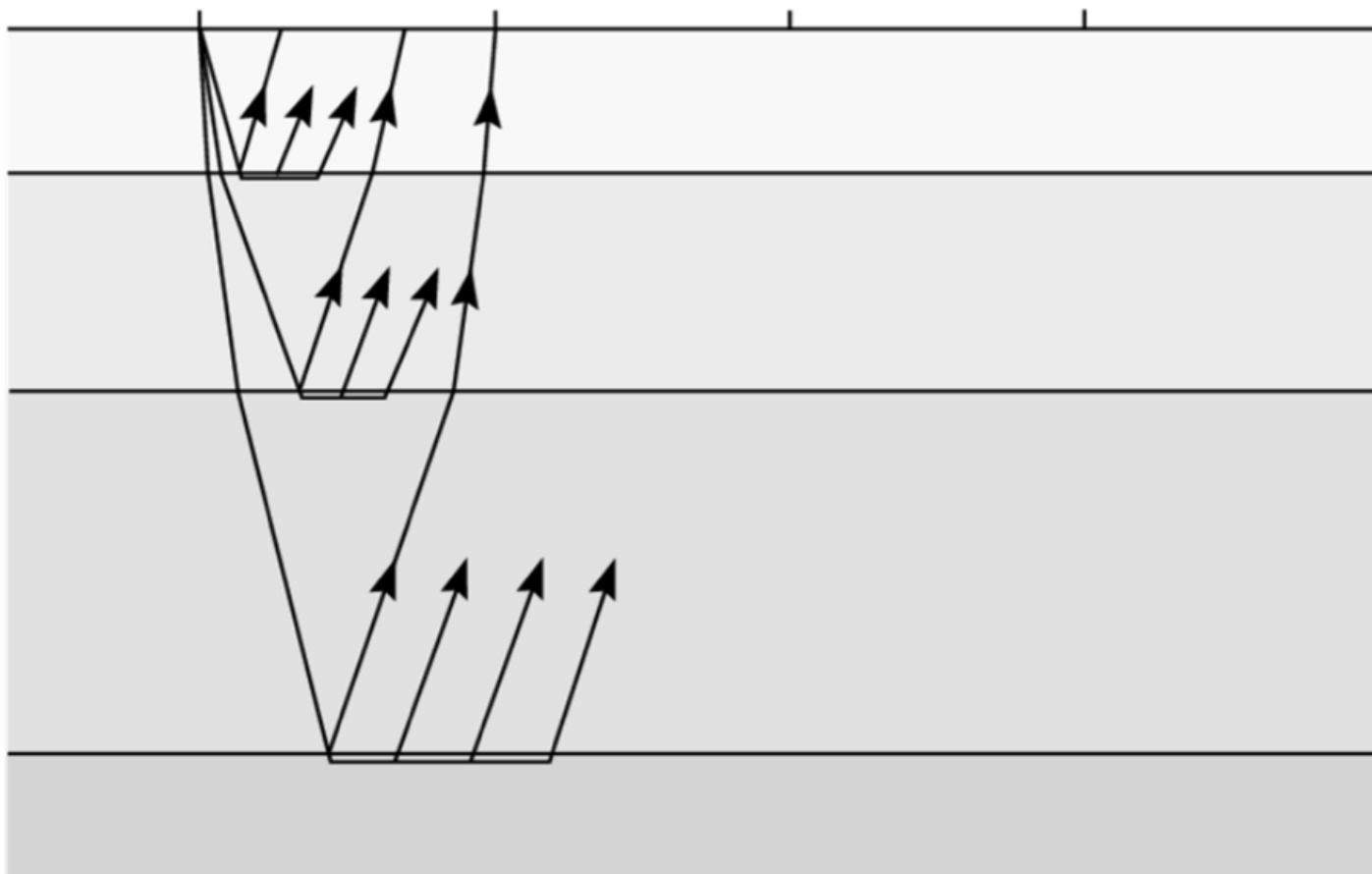
REFRACTION SEISMIC

Multiple Layers



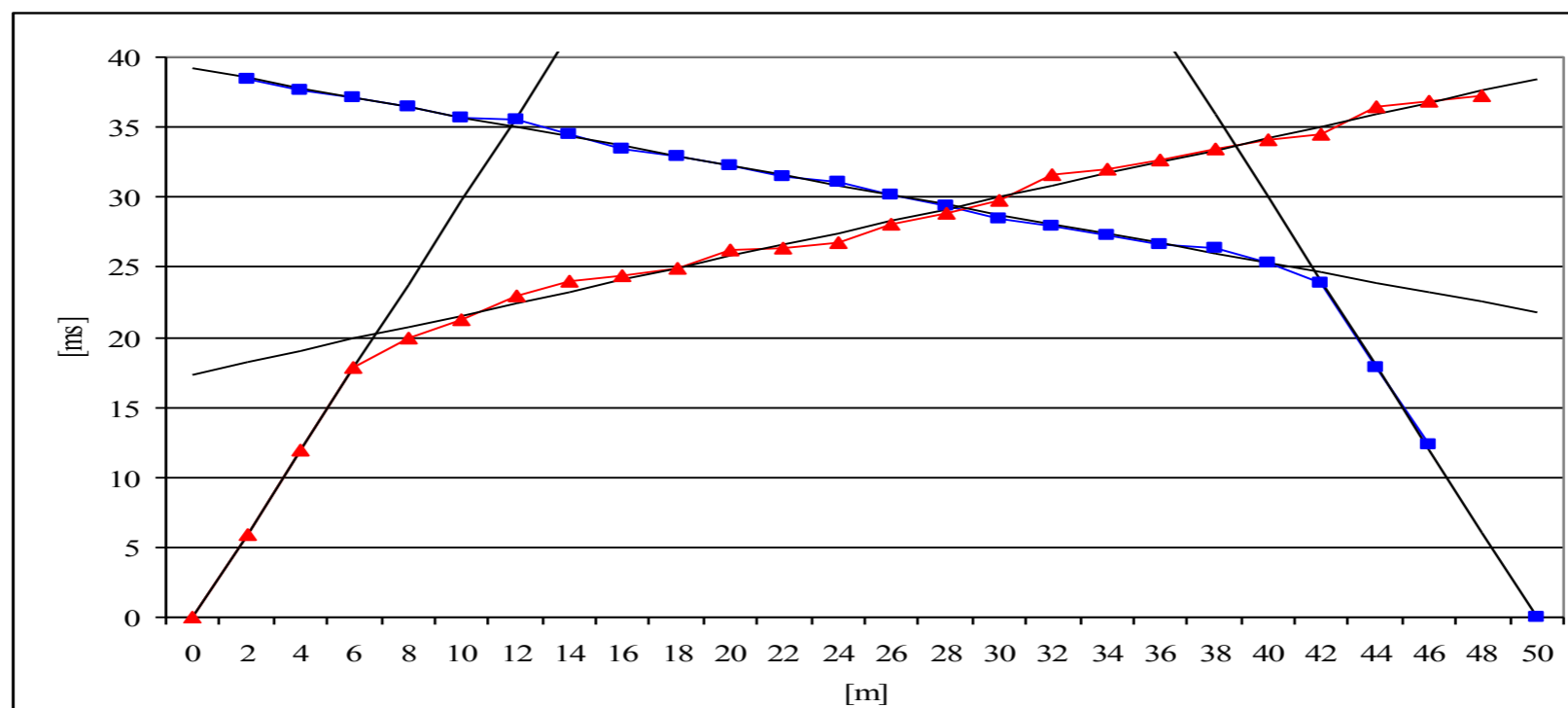
$$h_n = \frac{V_n}{\cos(i_n)} \left(\frac{T0_{n+1}}{2} - \sum_{j=0}^{n-1} h_j \sqrt{\frac{1}{V_j^2} - \frac{1}{V_{j+1}^2}} \right)$$

T0n = n intercept time



Non planar Deepening refractor 2D section

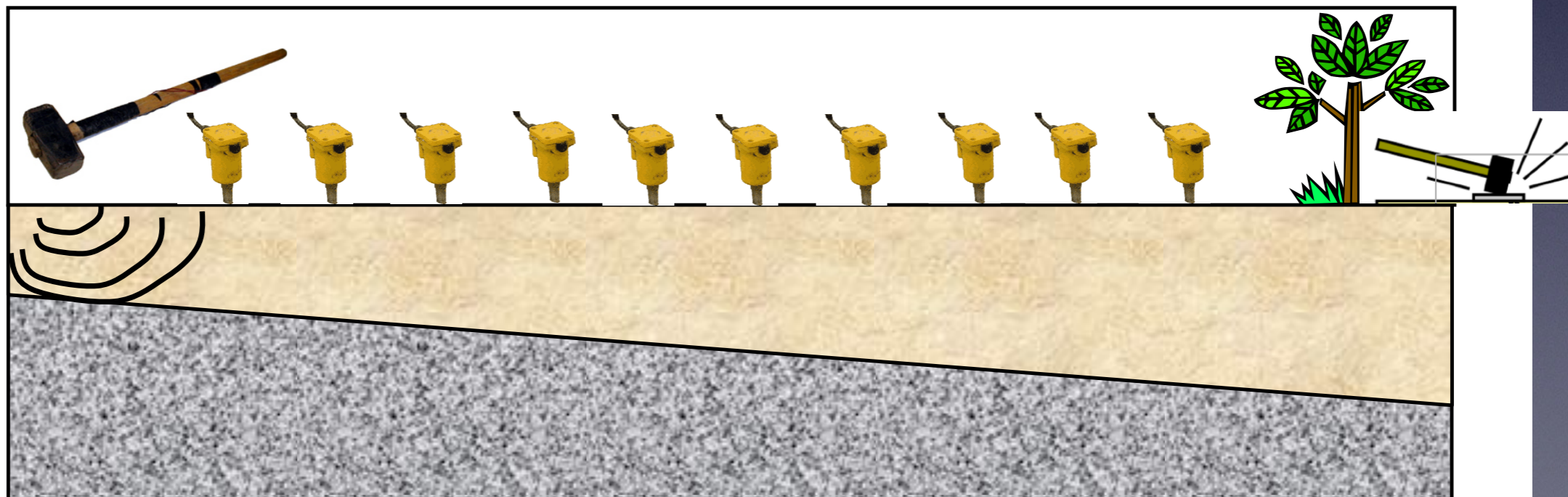
Subsoil 2D geometry



≠ Xcross

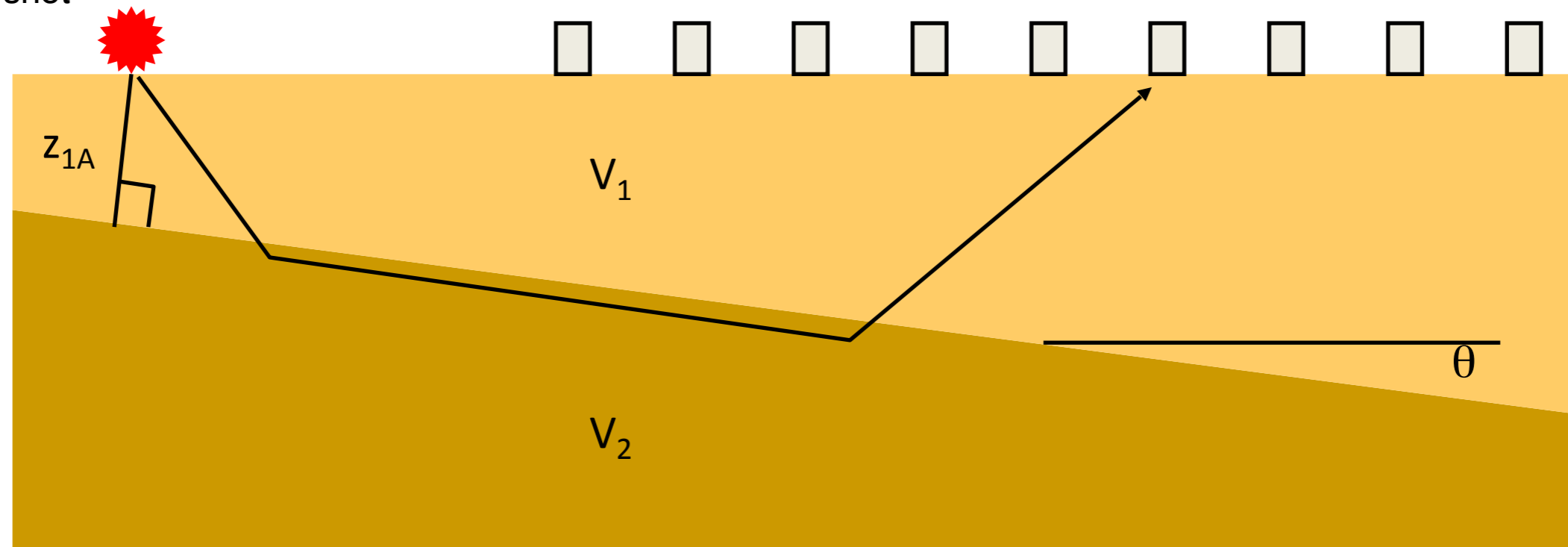
≠ T0

≠ H

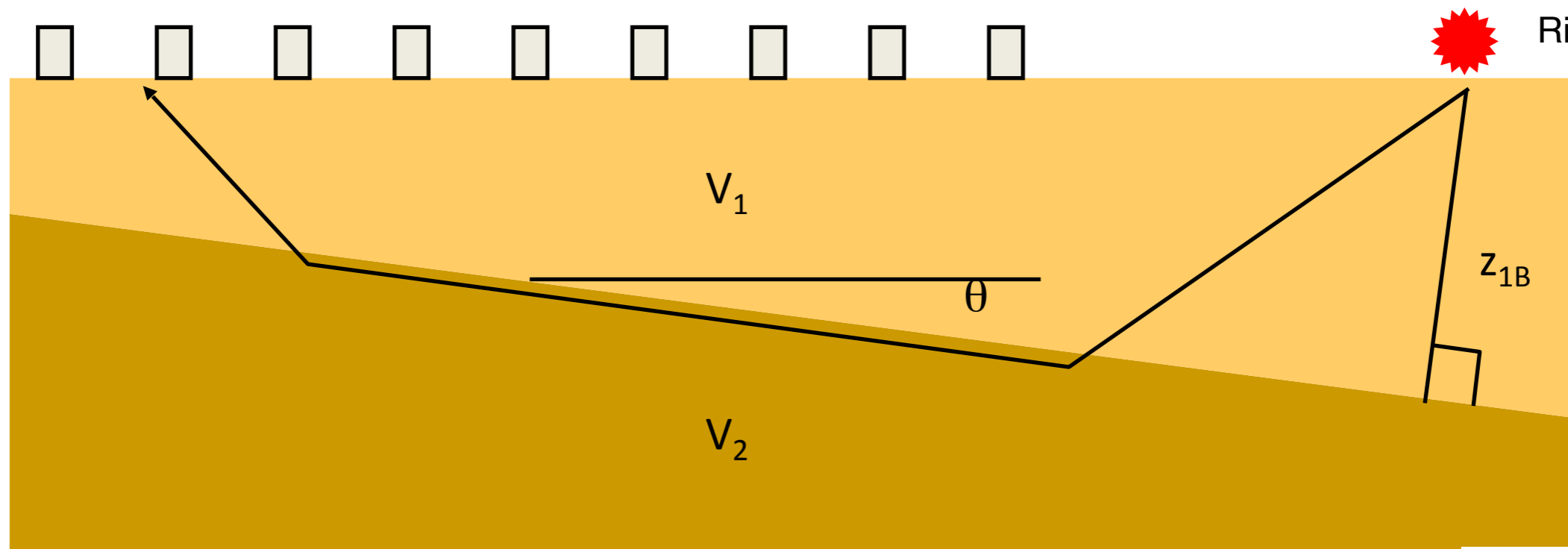


Seismic Refraction

Left shot



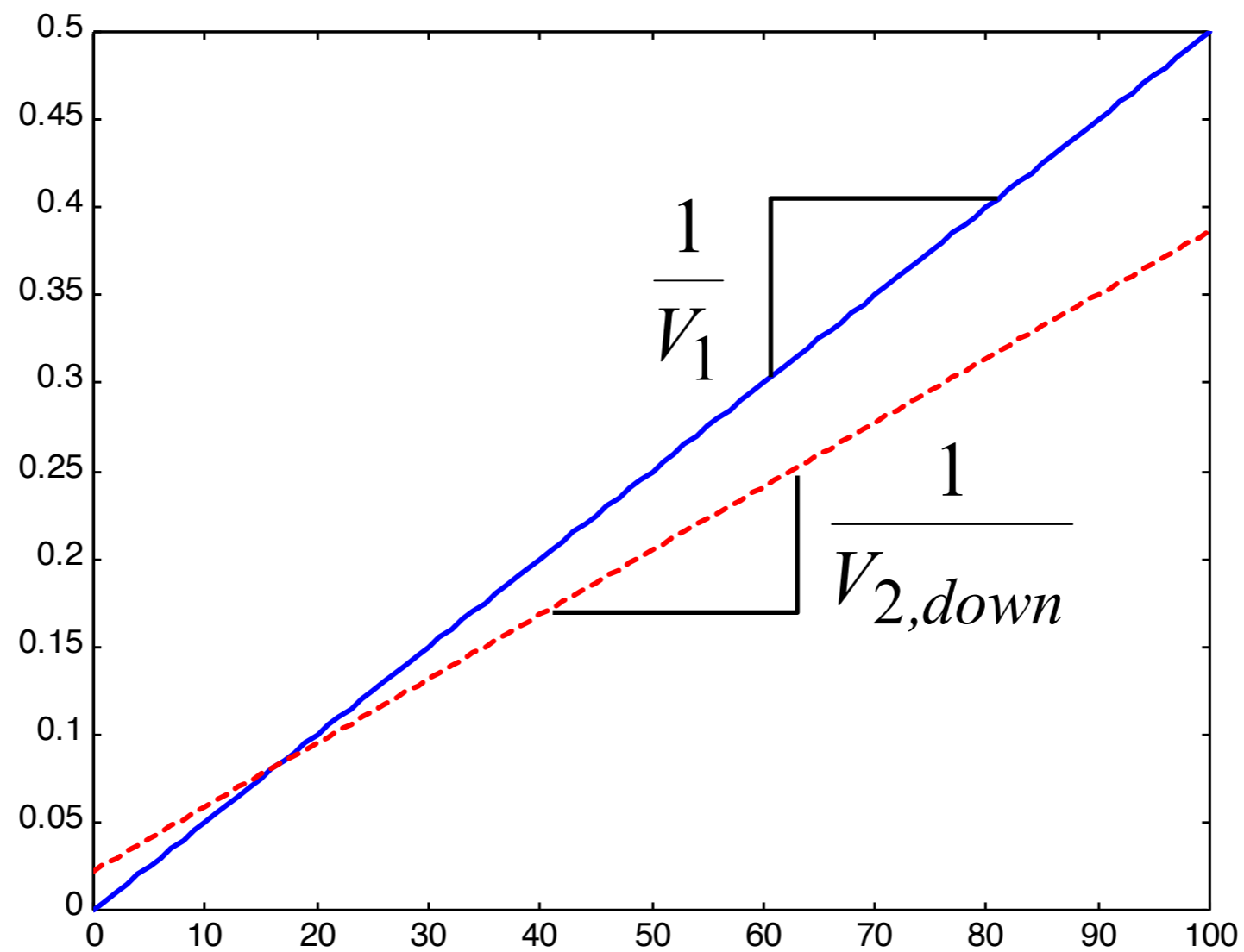
Deepening angle



Right shot



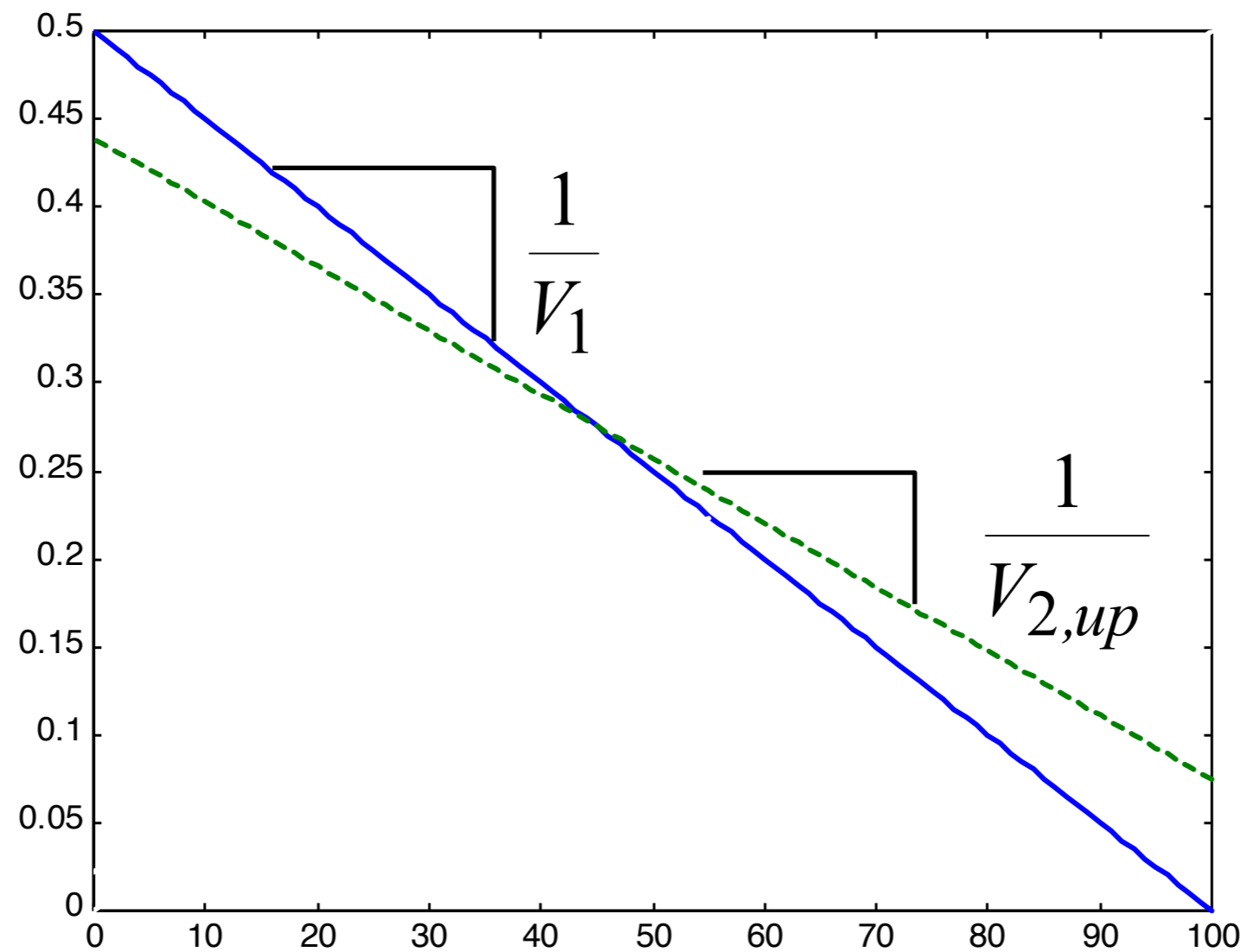
Seismic Refraction



Left shot

Right shot

Seismic Refraction



Right shot

$$\left. \begin{aligned} i_c + \theta &= \sin^{-1} \left(\frac{V_1}{V_{2,down}} \right) \\ i_c - \theta &= \sin^{-1} \left(\frac{V_1}{V_{2,up}} \right) \\ \sin i_c &= \frac{V_1}{V_2} \end{aligned} \right\}$$

Two Equations – Two Unknowns



Seismic Refraction

Source

24 receivers @ 3-m spacing

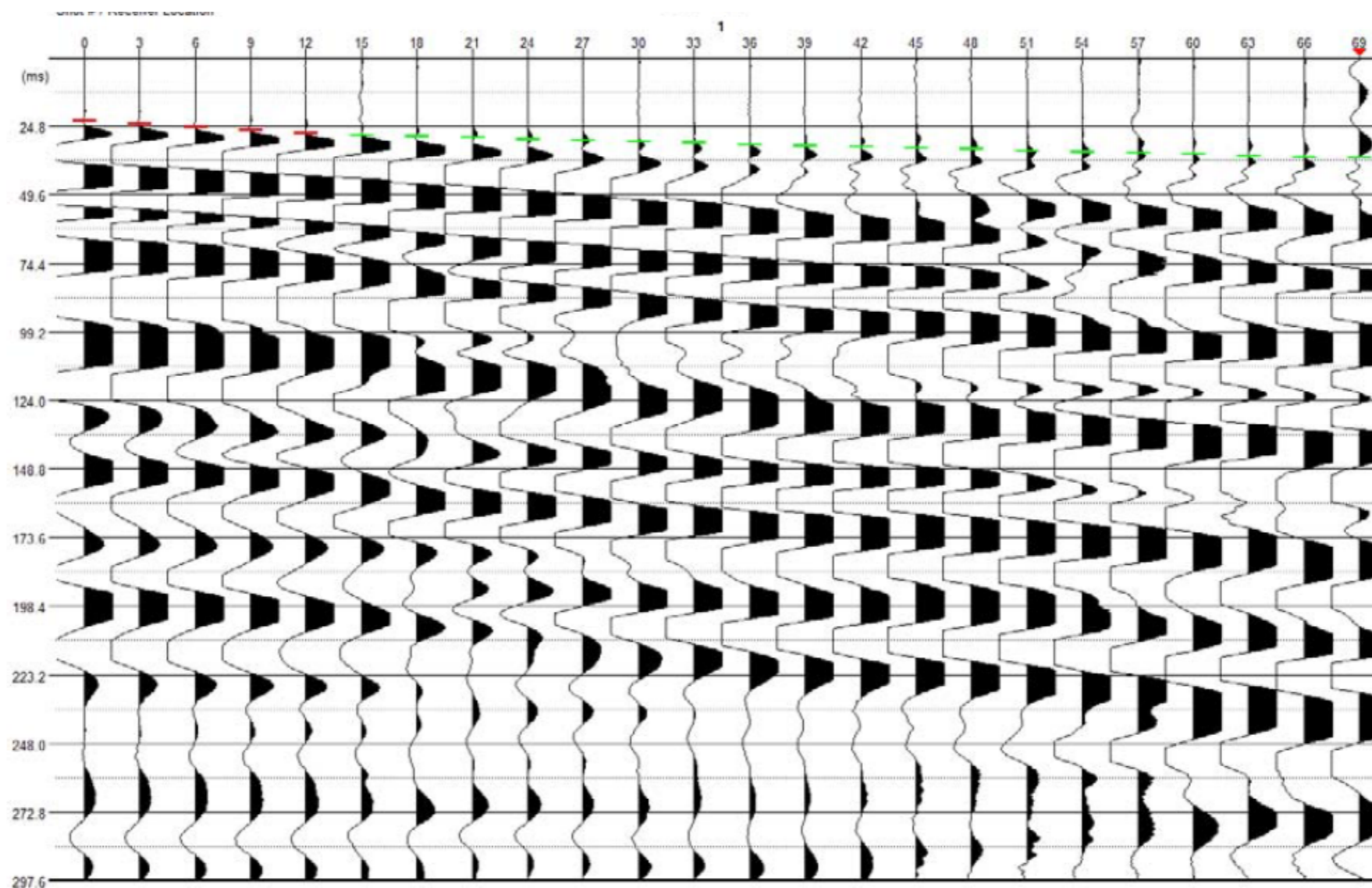
24 receivers @ 3-m spacing

X



Shot 1

Shot 2



Seismic Refraction

Source

24 receivers @ 3-m spacing

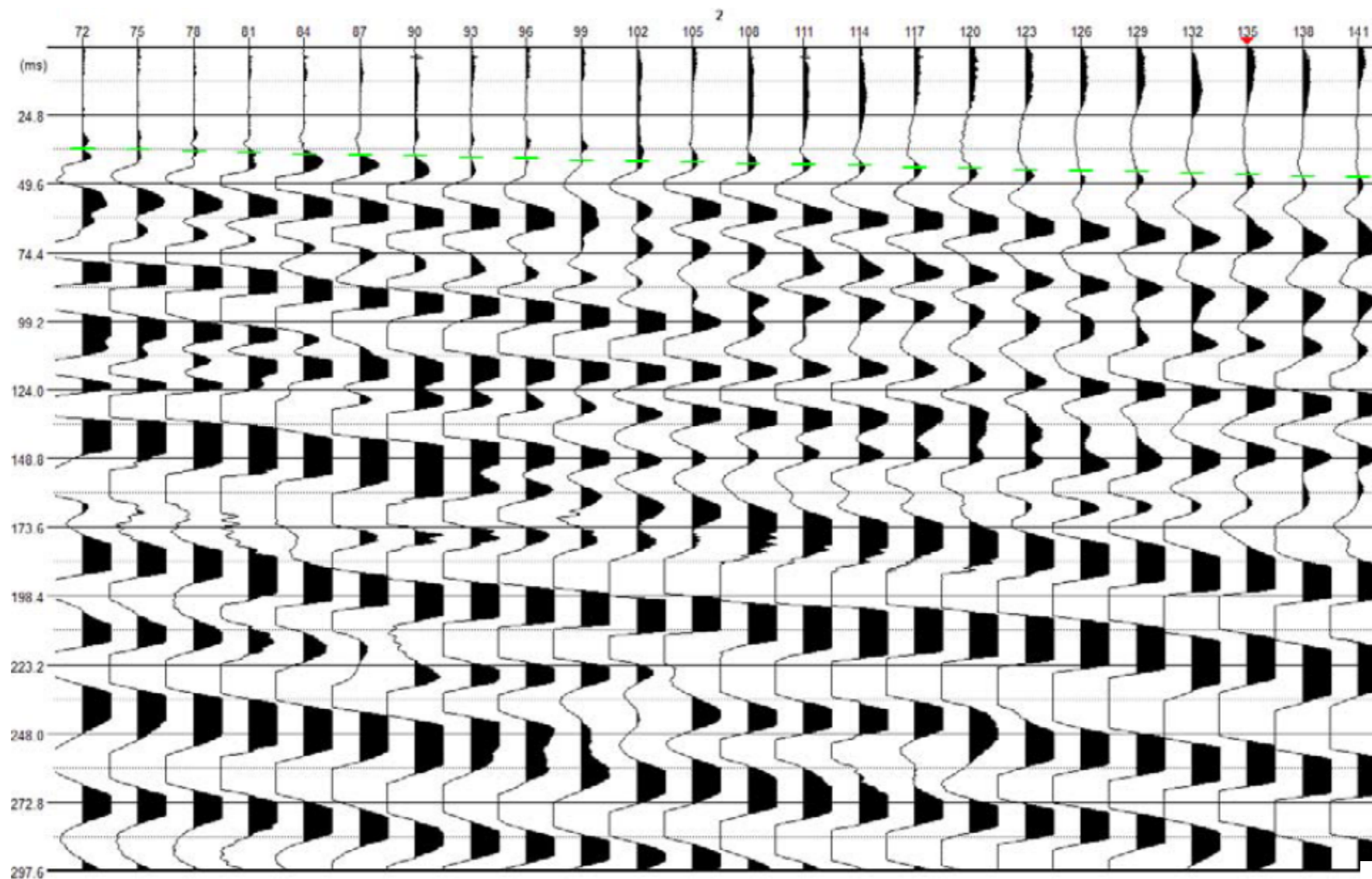
24 receivers @ 3-m spacing

X



Shot 1

Shot 2



Seismic Refraction

Source

24 receivers @ 3-m spacing

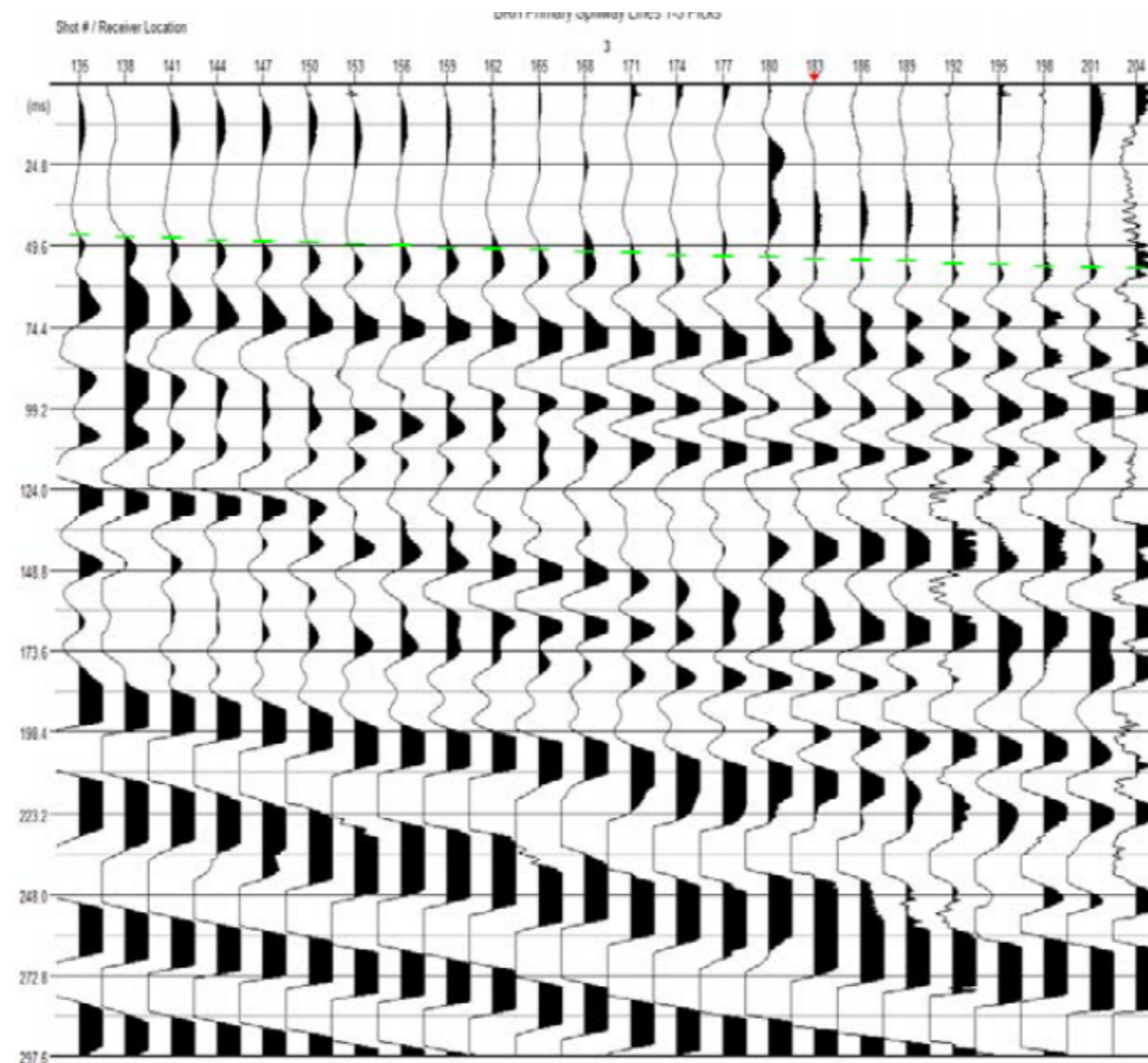
24 receivers @ 3-m spacing

X

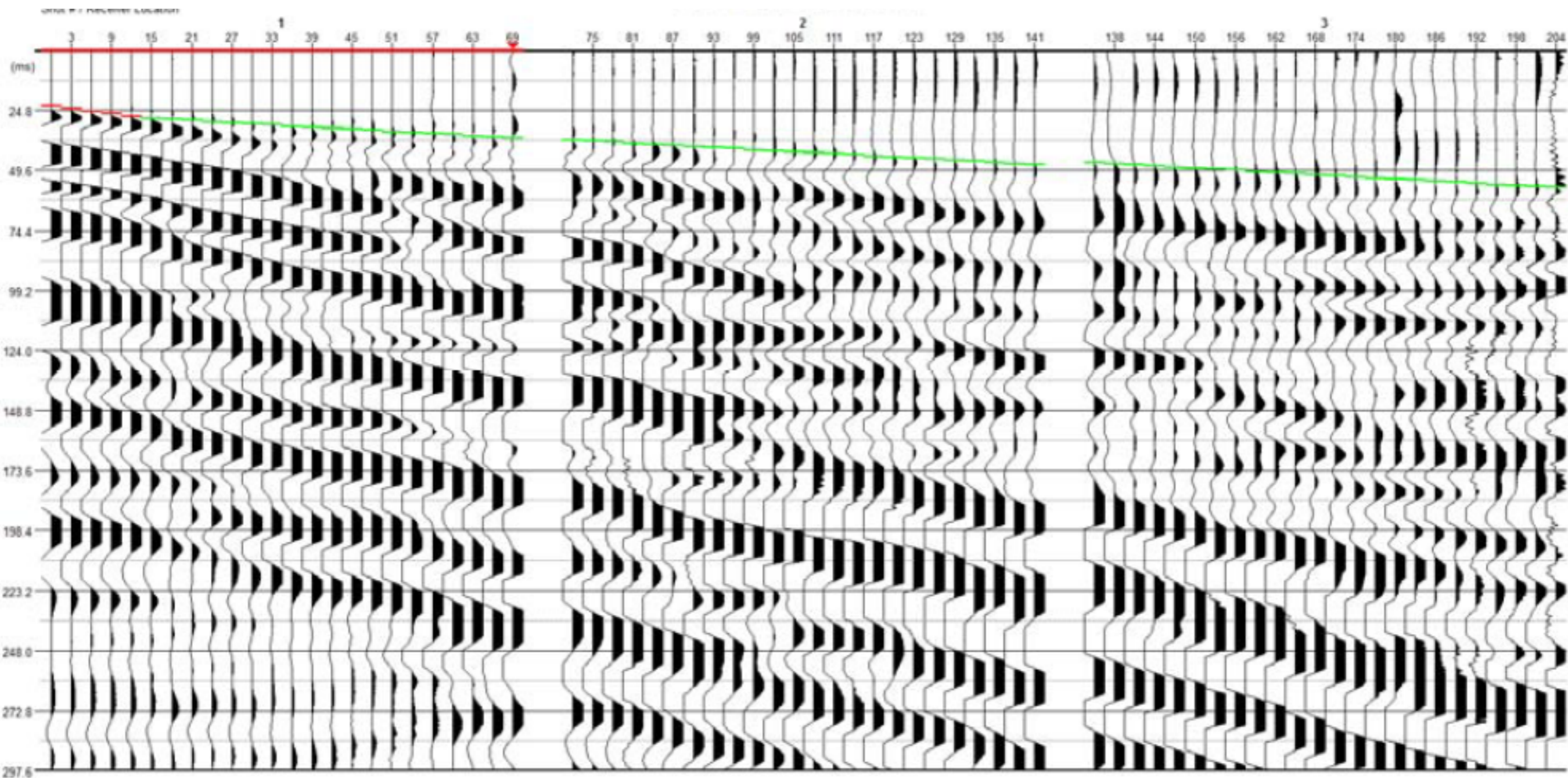


Shot 2

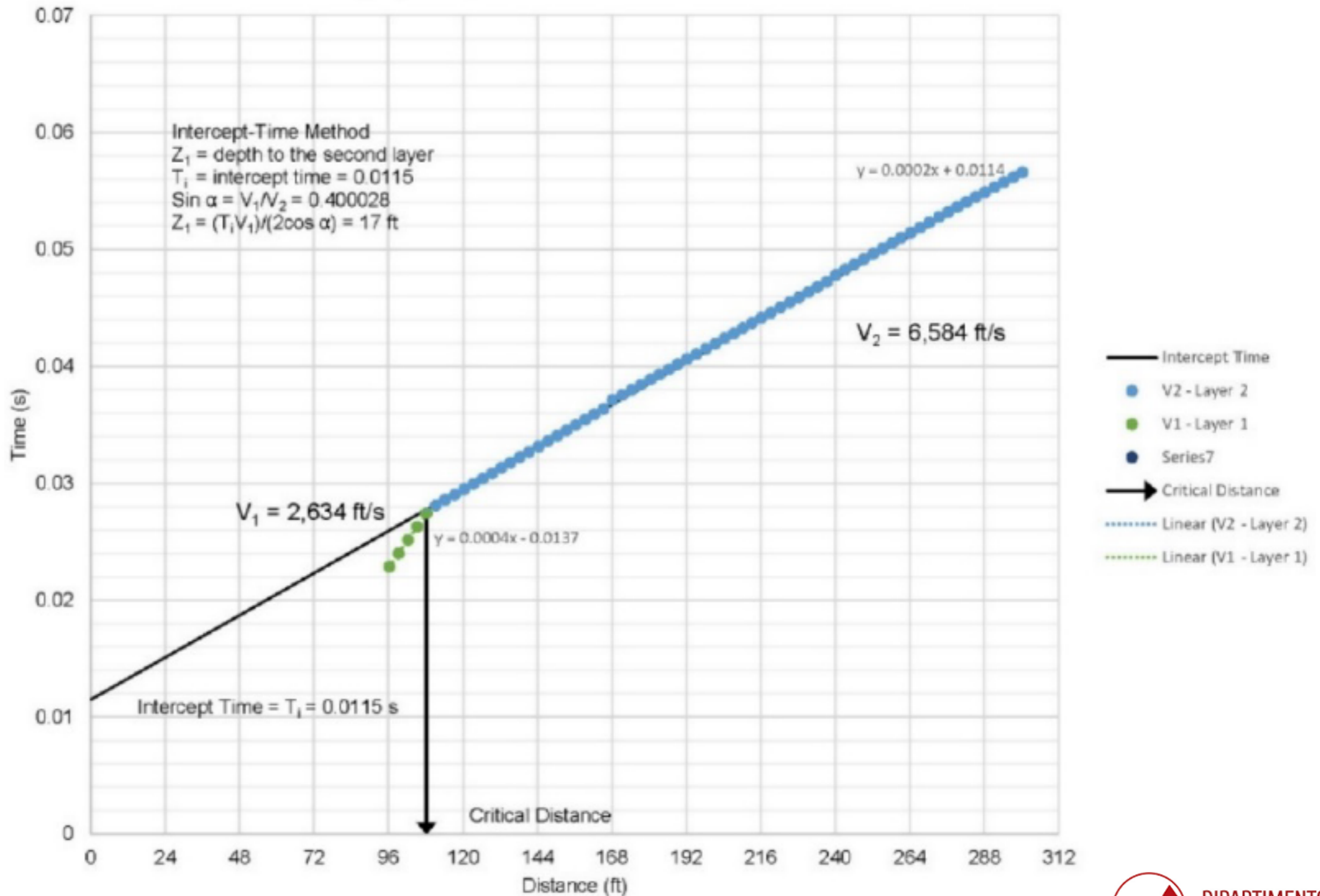
Shot 3



Seismic Refraction



Seismic Refraction



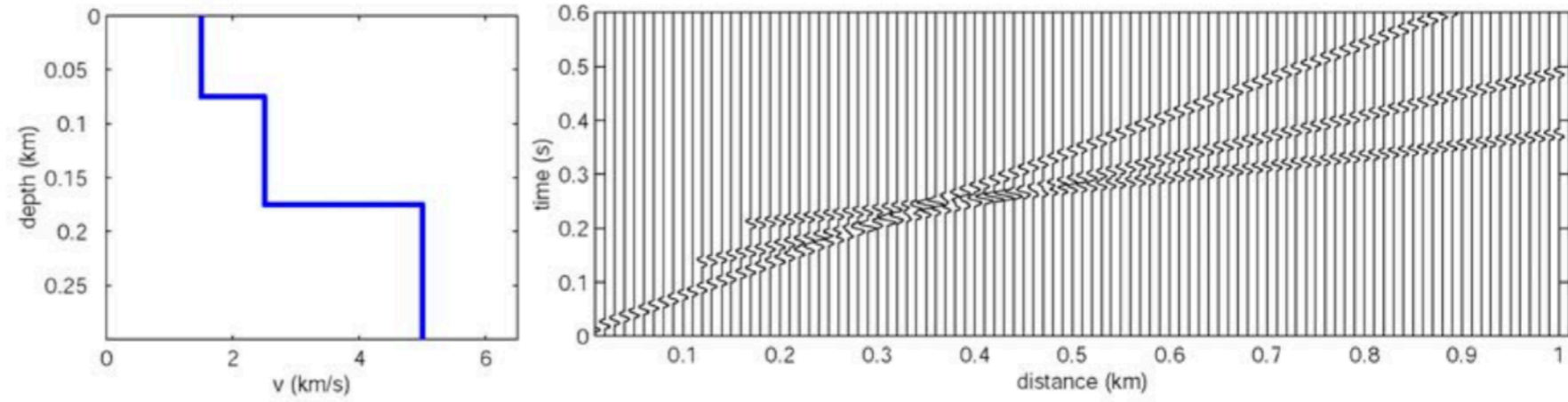
C3.2 Seismic refraction - with a low velocity zone (LVZ)

3 layers

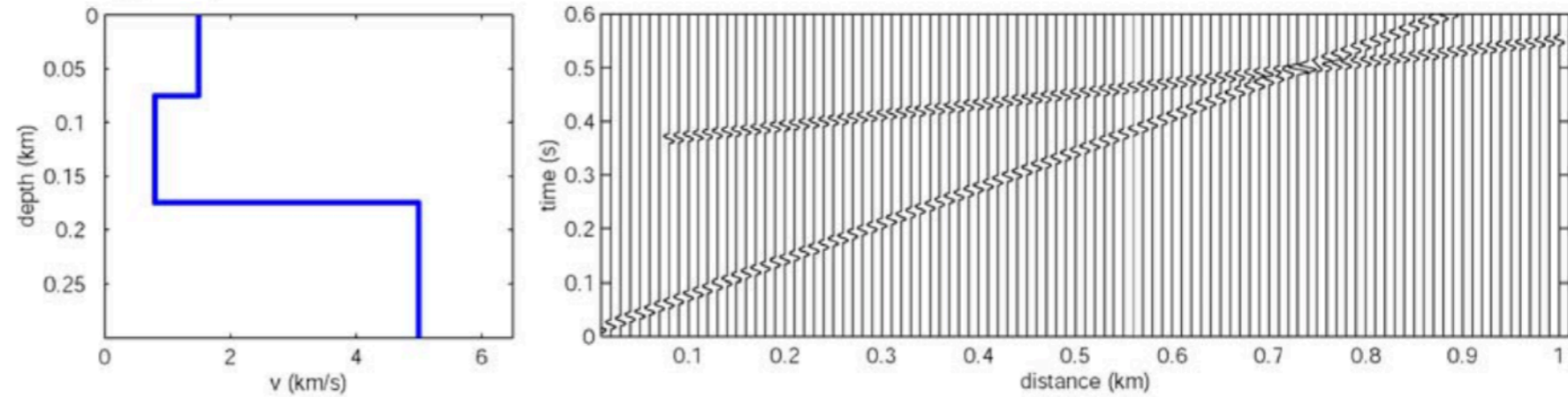
Hidden layer
limit (low velocity
Zone LVZ)

2 layers

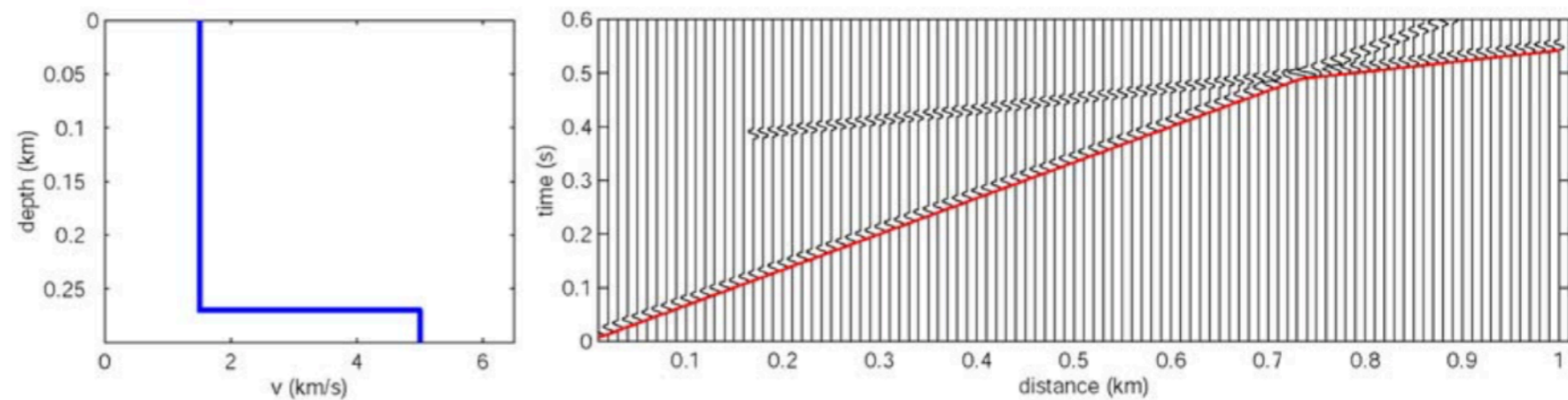
(a) 3-layer model with no LVZ



(b) 3-layer model with LVZ



(c) Interpretation of first arrivals from (b)



- Time Intercept and Crossover Distance Methods (planar refractors)
- Common Reciprocal Methods (non-planar refractors)
 - Plus-Minus Method
 - ABC Method
 - Hagiwaras Method
- Generalized Reciprocal Methods (non-planar refractors)
 - Delay Time Method
 - Hales Method

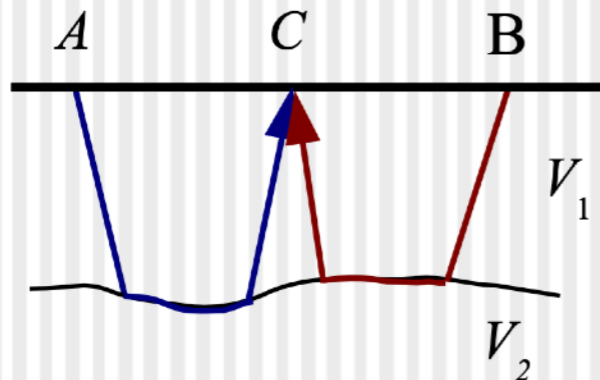
Reciprocal methods= you need reversal shots!



Seismic Refraction

Common Reciprocal Methods : ABC method

- Combine the refraction times recorded along A-C, B-C, and A-B:



$$t_{AC} + t_{CB} - t_{AB} \approx 2t_{\text{Delay}(C)} = \frac{2h_c \cos i_c}{V_1}$$

Knowing arrival times in A, B, C and Velocities, you get HC

The ABC method

*Get the thickness in C (Hc)
(Knowing velocities)*

- Therefore:

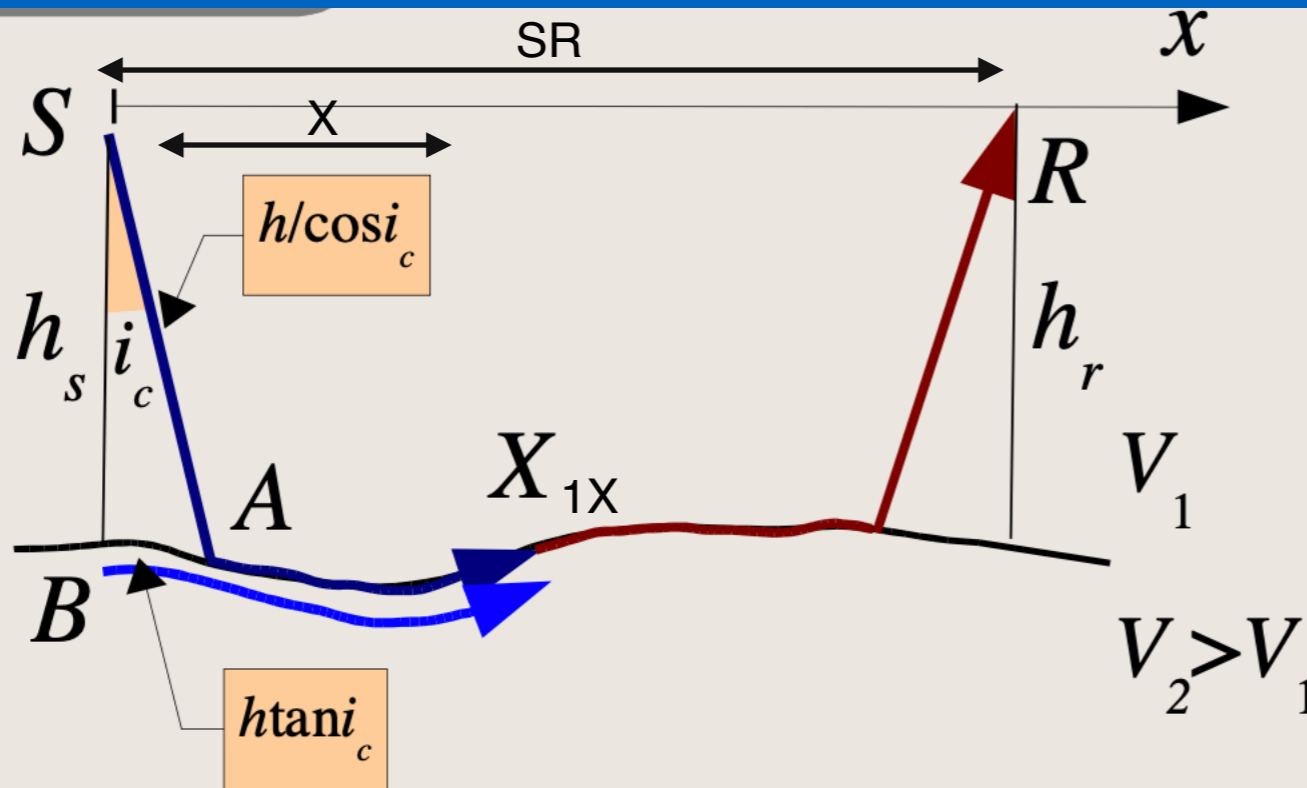
$$h_c \approx \frac{V_1}{2 \cos i_c} (t_{AC} + t_{CB} - t_{AB})$$

- Note the typical time-to-depth conversion factor:

$$\frac{V_1}{\cos i_c} = \frac{V_1}{\sqrt{1 - \sin^2 i_c}} = \frac{V_1 V_2}{\sqrt{V_2^2 - V_1^2}}$$

Seismic Refraction

Delay Time method



Consider a nearly horizontal, shallow interface with strong velocity contrast (a typical case for **weathering layer**).

In this case, we can separate the times associated with the source and receiver vicinities:

$$t_{SR} = t_{SX} + t_{XR}.$$

Relate the time t_{SX} to a time along the refractor, t_{BX}

$$t_{SX} = t_{SA} - t_{BA} + t_{BX} = t_{S\text{delay}} + X/V_2$$

$$t_{S\text{Delay}} = \frac{SA}{V_1} - \frac{BA}{V_2} = \frac{h_s}{V_1 \cos i_c} - \frac{h_s \tan i_c}{V_2} = \frac{h_s}{V_1 \cos i_c} (1 - \sin^2 i_c) = \frac{h_s \cos i_c}{V_1}.$$

Note that $V_2 = V_1 / \sin i_c$

Thus, source and receiver **delay times** are:

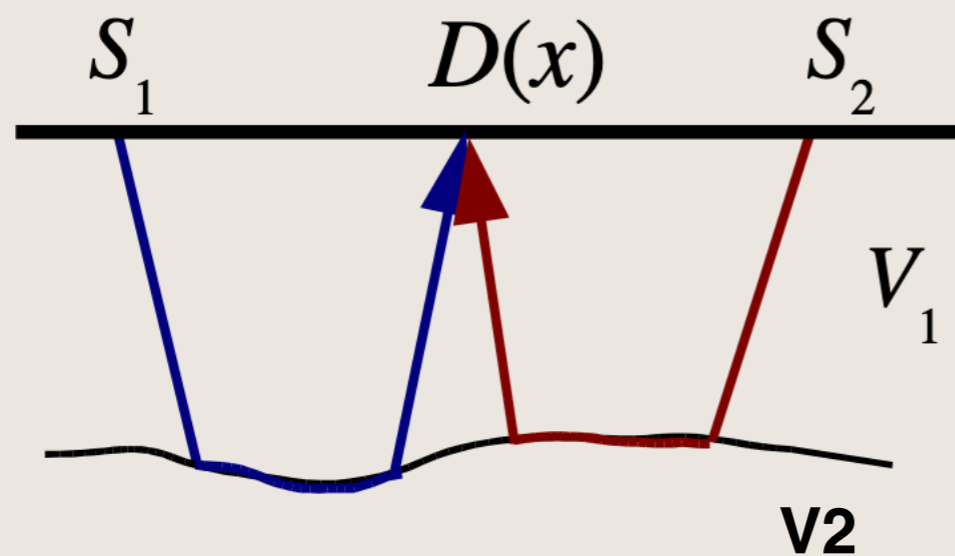
$$t_{S,R\text{Delay}} = \frac{h_{s,r} \cos i_c}{V_1}.$$

and

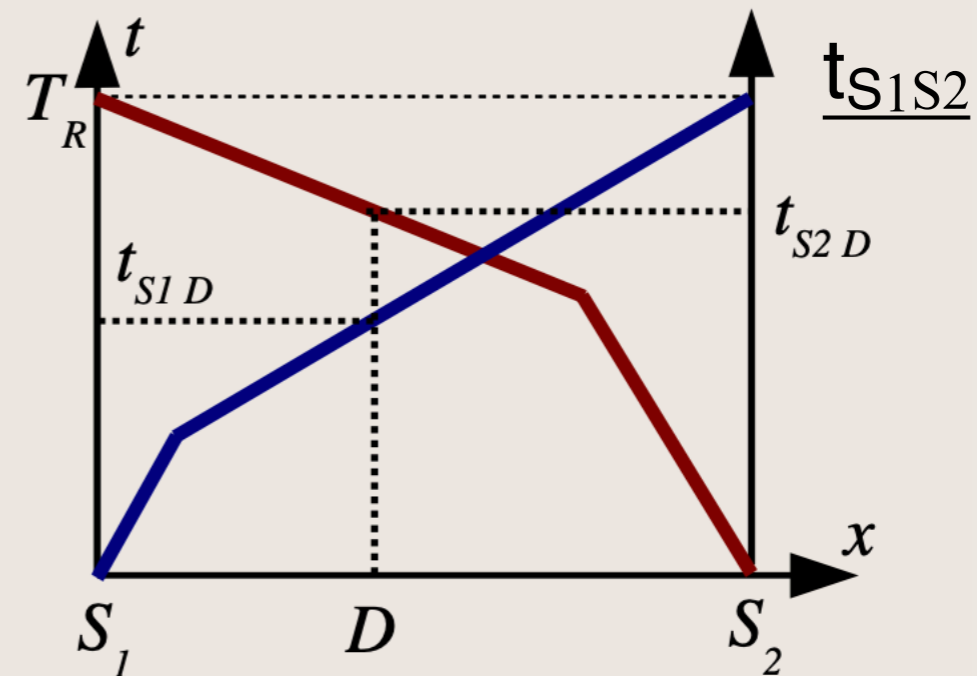
$$t_{SR} = t_{S\text{Delay}} + t_{R\text{Delay}} + \frac{SR}{V_2}.$$

Assume that we have recorded two headwaves in opposite directions, and have estimated the velocity of overburden, V_1 .

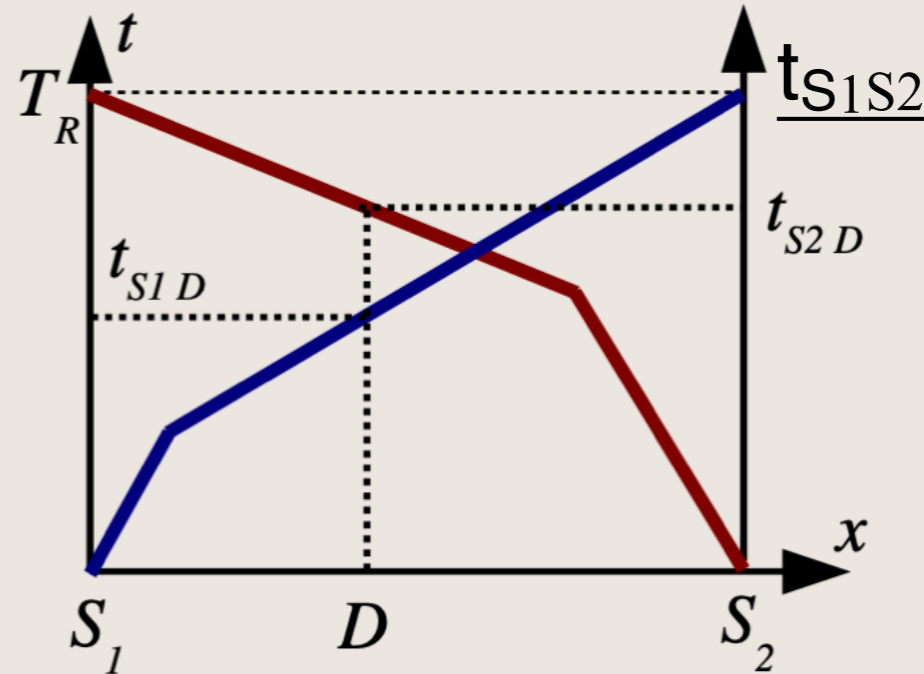
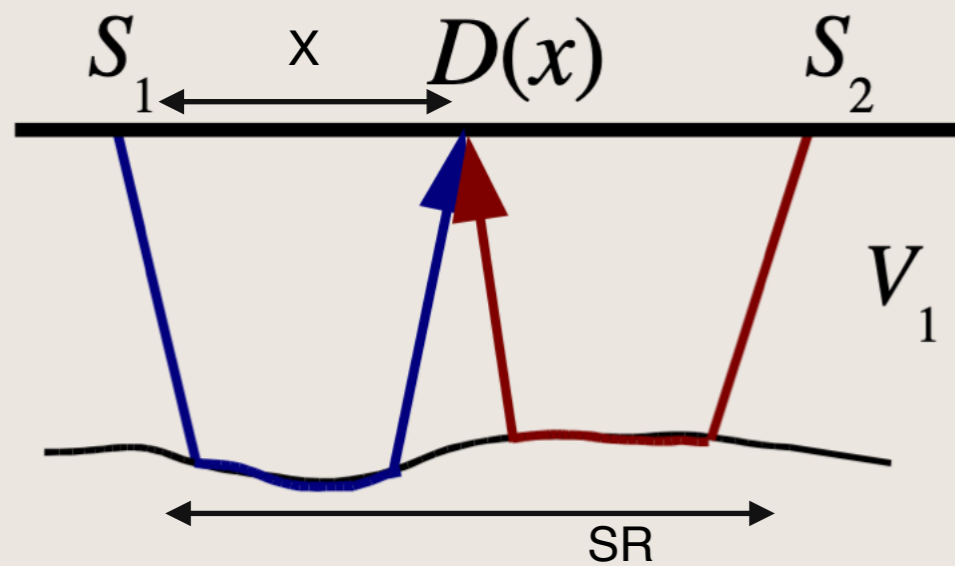
- ◆ How can we map the refracting interface?



Solution:



We want to estimate Delay time in D (T_d) to get thickness below point D, and Velocities of refractor V_2



Solution:

- Profile $S_1 \rightarrow S_2$: $t_{S_1 D} = \frac{x}{V_2} + t_{S_1} + t_D$;
- Profile $S_2 \rightarrow S_1$: $t_{S_2 D} = \frac{(SR - x)}{V_2} + t_{S_2} + t_D$.

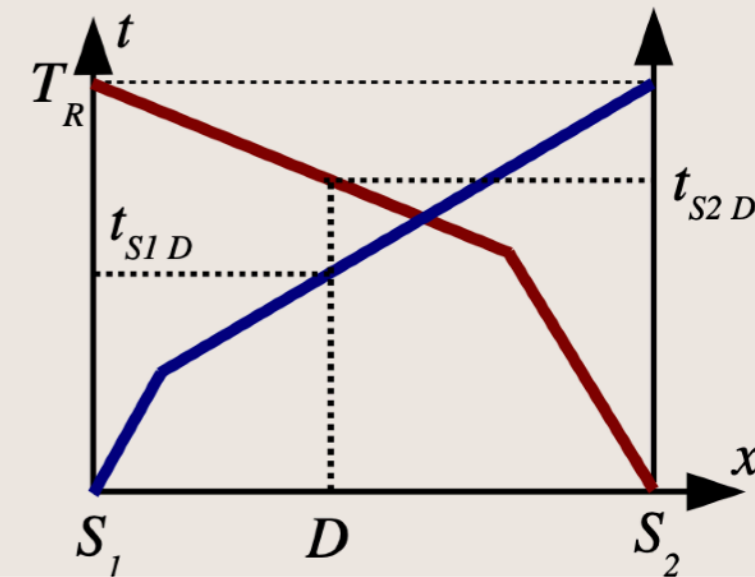
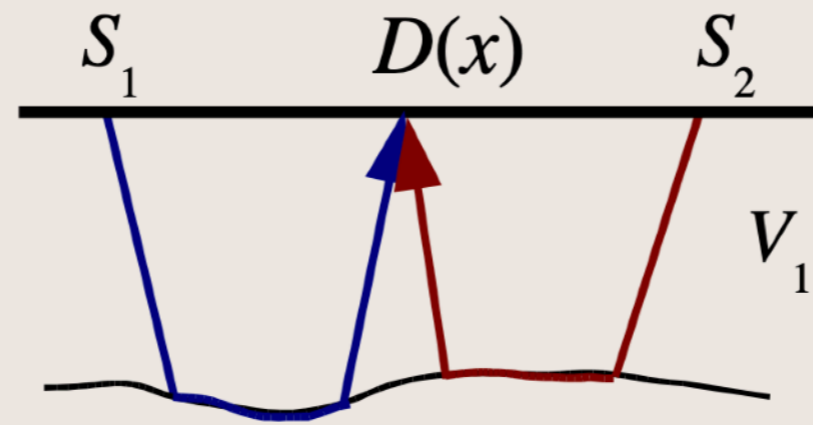
$$t_{SR} = t_{S \text{ Delay}} + t_{R \text{ Delay}} + \frac{SR}{V_2}$$

◆ Form PLUS travel-time:

$$t_{PLUS} = t_{S_1 D} + t_{S_2 D} = \frac{SR}{V_2} + t_{S_1} + t_{S_2} + 2t_D = t_{S_1 S_2} + 2t_D$$

Hence: $t_D = \frac{1}{2}(t_{PLUS} - t_{S_1 S_2})$.

◆ To determine i_c (and depth), still need to find V_2 .



To determine V_2 :

- Form MINUS travel-time:

this is a constant!

$$t_{MINUS} = t_{S_1 D} - t_{S_2 D} = \frac{2x}{V_2} - \frac{SR}{V_2} + t_{s_1} - t_{s_2}$$

Hence:

$$\text{slope} [t_{MINUS}(x)] = \frac{2}{V_2}$$

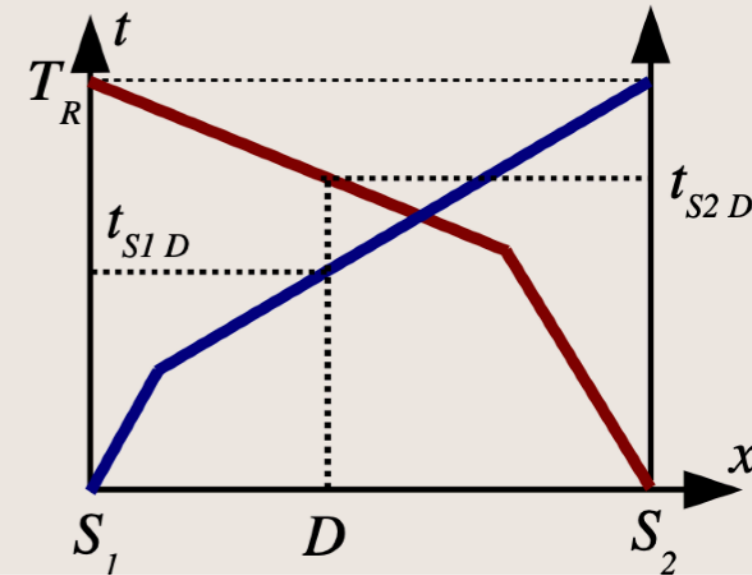
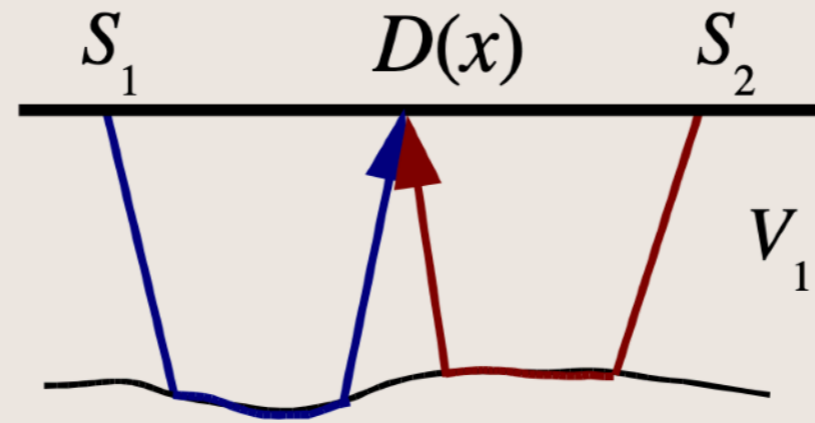
Plotting $t_{S_1 D} - t_{S_2 D}$

vs $2x$ give you the slope
= $1/v_2$

(For several geophones)

Note that $V_2 = V_1 / \sin i_c$

$$t_D = \frac{h_D \cos i_c}{V_1}$$



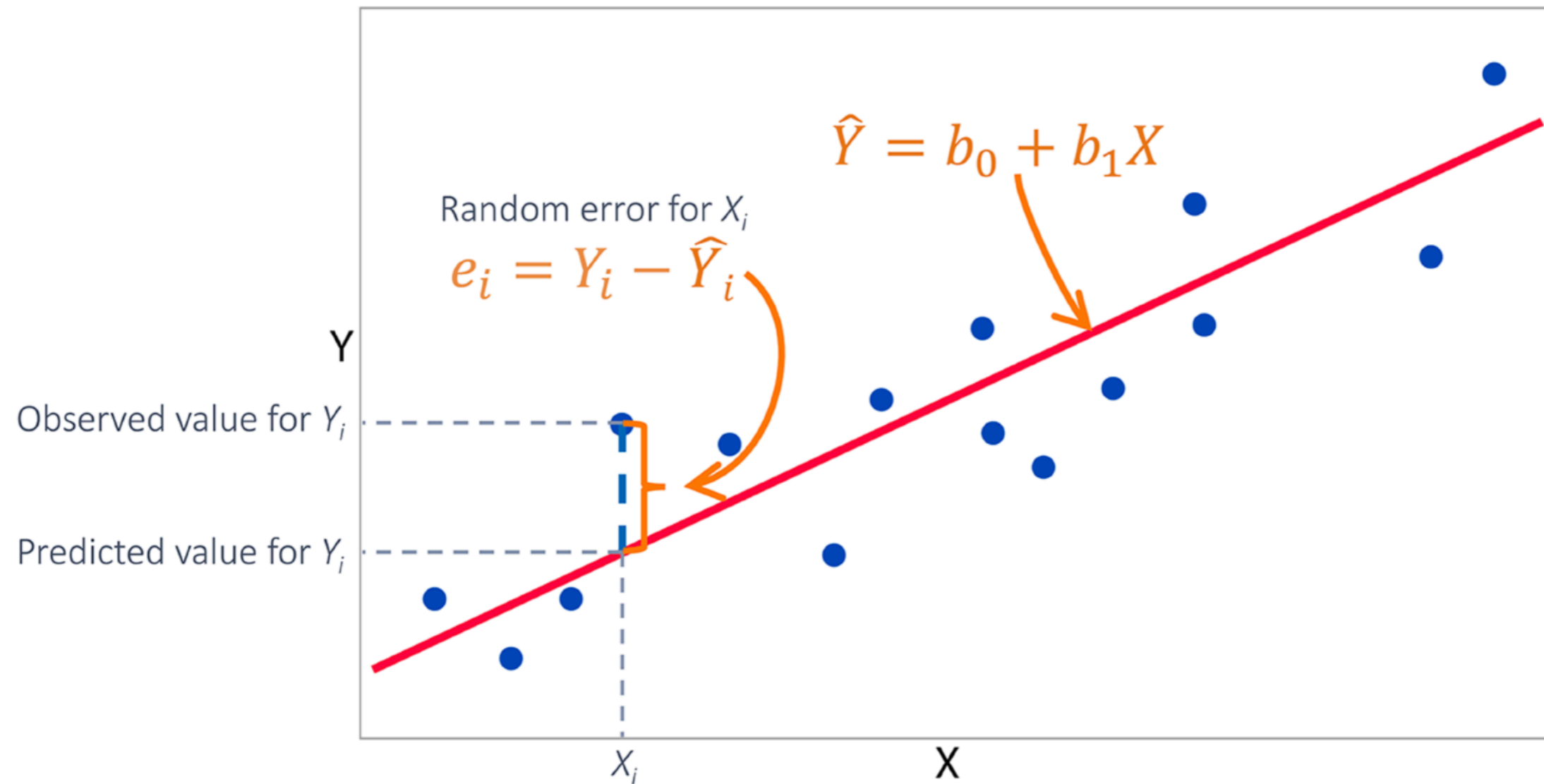
$$\text{slope} [t_{\text{MINUS}}(x)] = \frac{2}{V_2}$$

You have $(V_1), V_2, i_c$ and can retrieve **Hd** (thickness below D) for each geophones

- ◆ The slope is usually estimated by using the *Least Squares method*.

Seismic Refraction

Least square regression



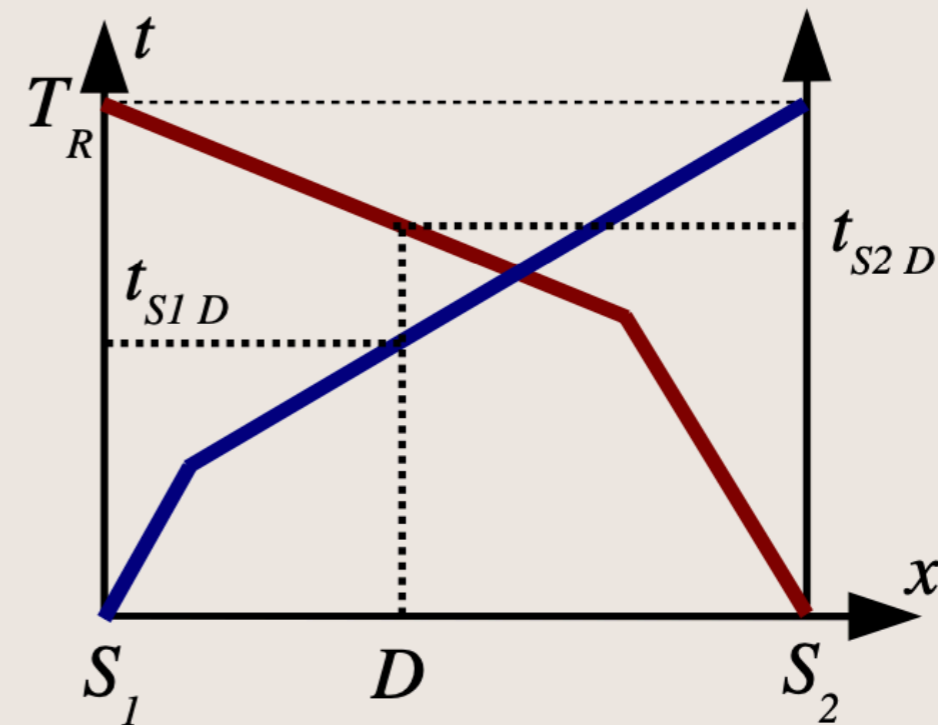
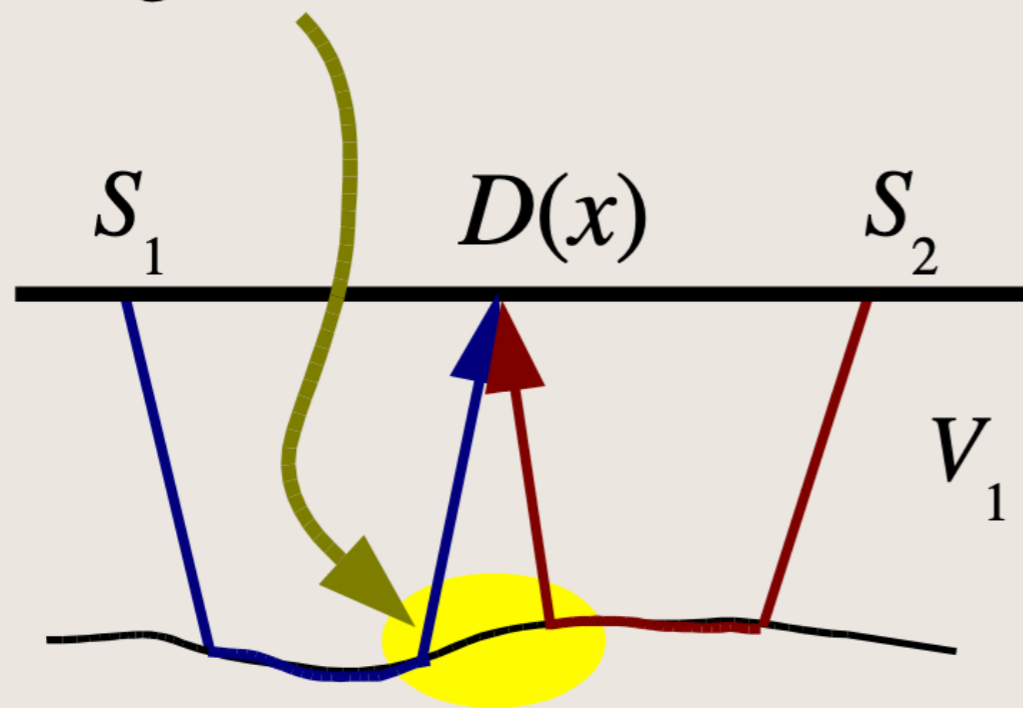
If we add up all of the errors, the sum will be zero. To measure overall error we square the errors and find a line that minimizes this sum of the squared errors.

$$\sum e_t^2 = \sum (Y_i - \bar{Y}_i)^2$$

The method of least squares finds values of the intercept and slope coefficient that minimize the sum of the squared errors.

- ◆ The slope is usually estimated by using the *Least Squares method*.

Drawback of this method – averaging over the pre-critical region.



Seismic Refraction

Generalised Reciprocal Method

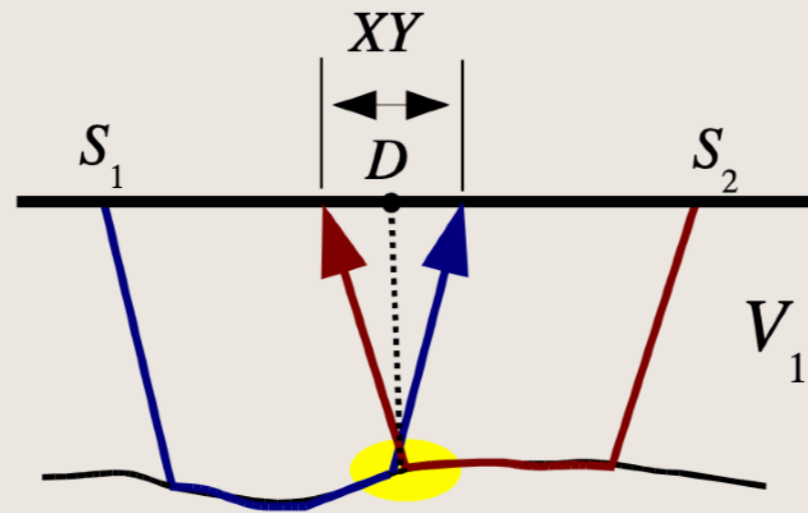
Introduces offsets (' XY ') in travel-time readings in the forward and reverse shots;

- so that the imaging is targeted on a compact interface region.

Proceeds as the plus-minus method;

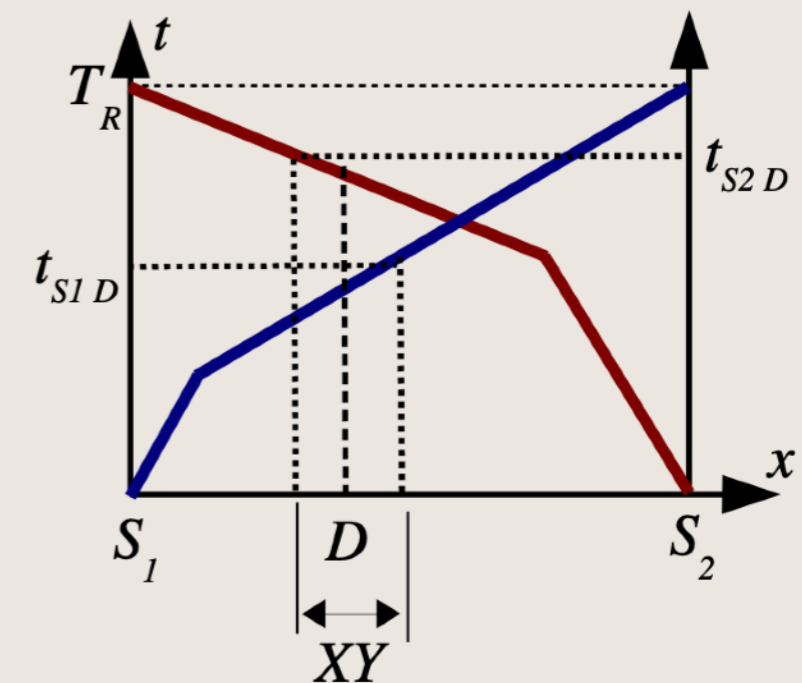
Determines the '*optimal*' XY :

- 1) Corresponding to the most linear *time-depth function*;
- 2) Corresponding to the *most detail* of the refractor.

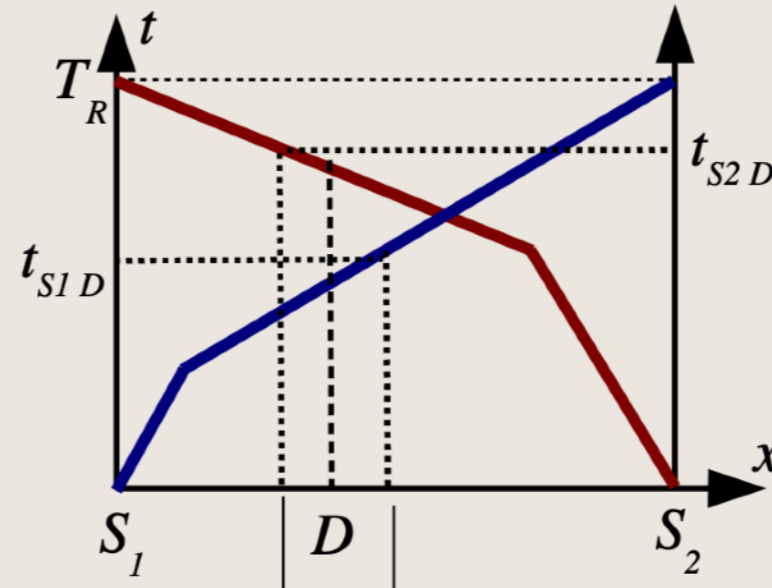
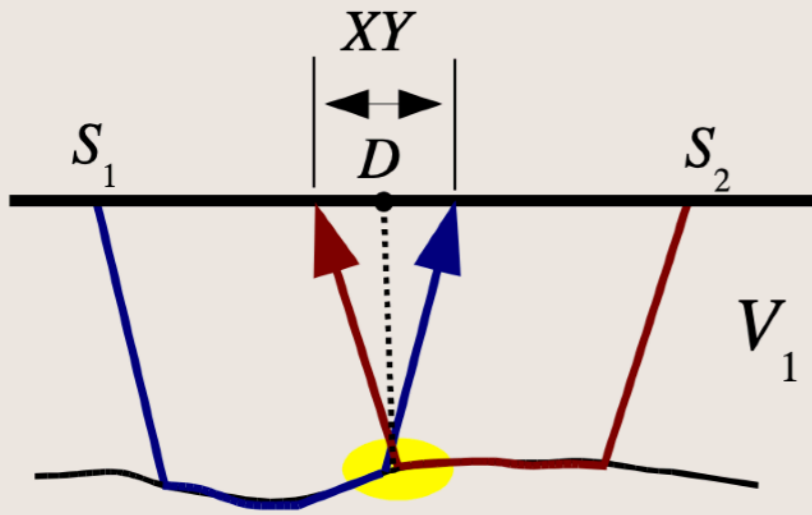


The *velocity analysis function*:

$$t_V = \frac{1}{2} (t_{S_1 D} - t_{S_2 D} + t_{S_1 S_2}),$$



should be linear, slope = $1/V_2$;



The *time-depth function*:

$$t_D = \frac{1}{2} \left(t_{S_1 D} + t_{S_2 D} - t_{S_1 S_2} - \frac{XY}{V_2} \right).$$

this is related to the desired image:

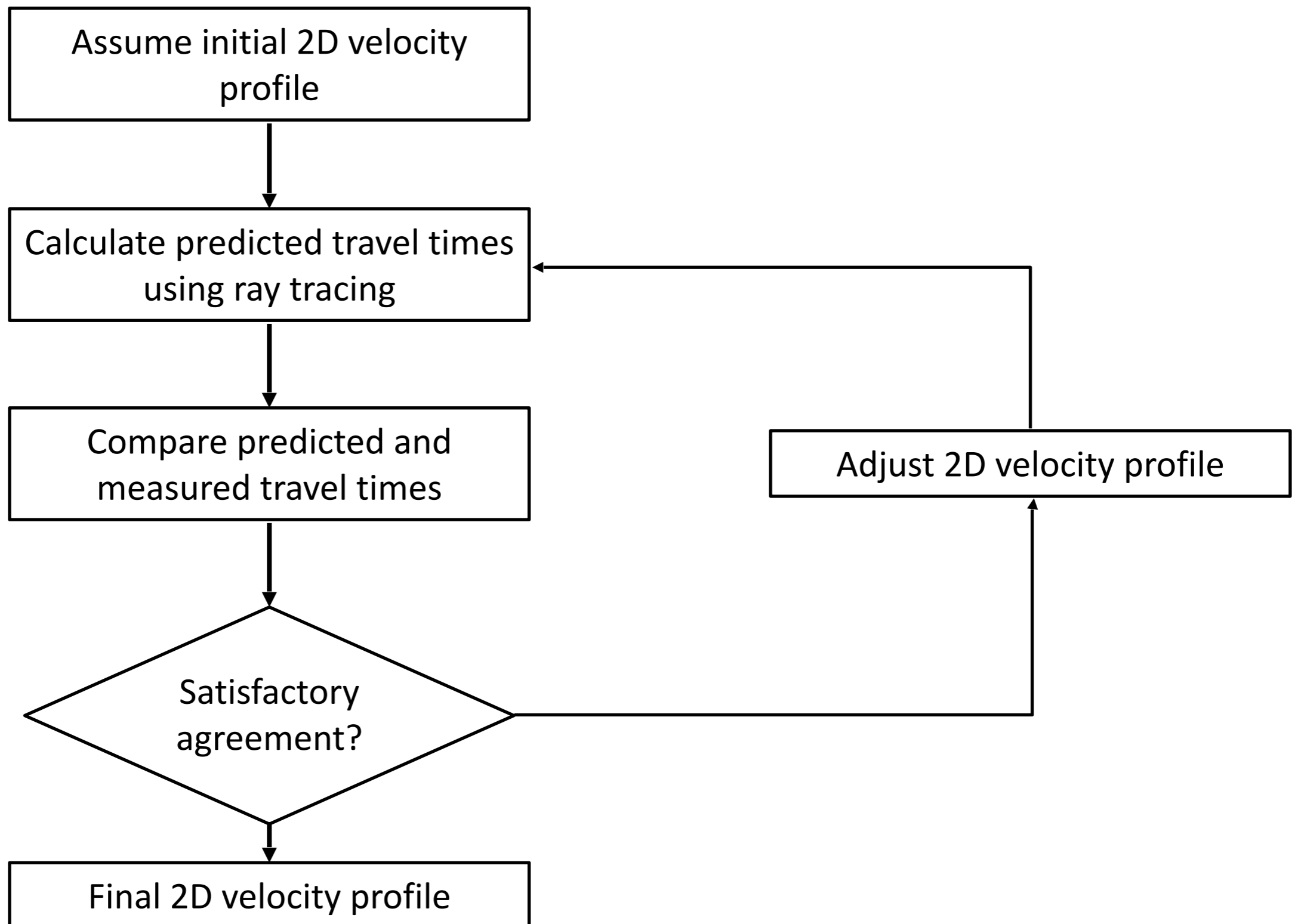
$$h_D = \frac{t_D V_1 V_2}{\sqrt{V_2^2 - V_1^2}}$$

- The two-dimensional (2D) velocity structure is estimated by minimizing the difference between predicted and observed first-arrival travel times (i.e., an **inversion** procedure).



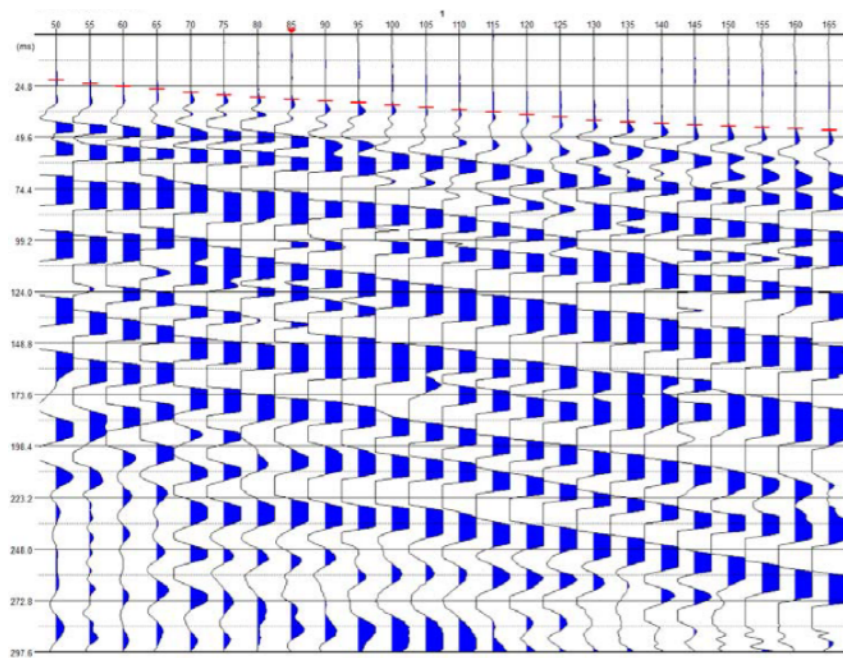
Computational
Refraction tomography

Seismic Refraction

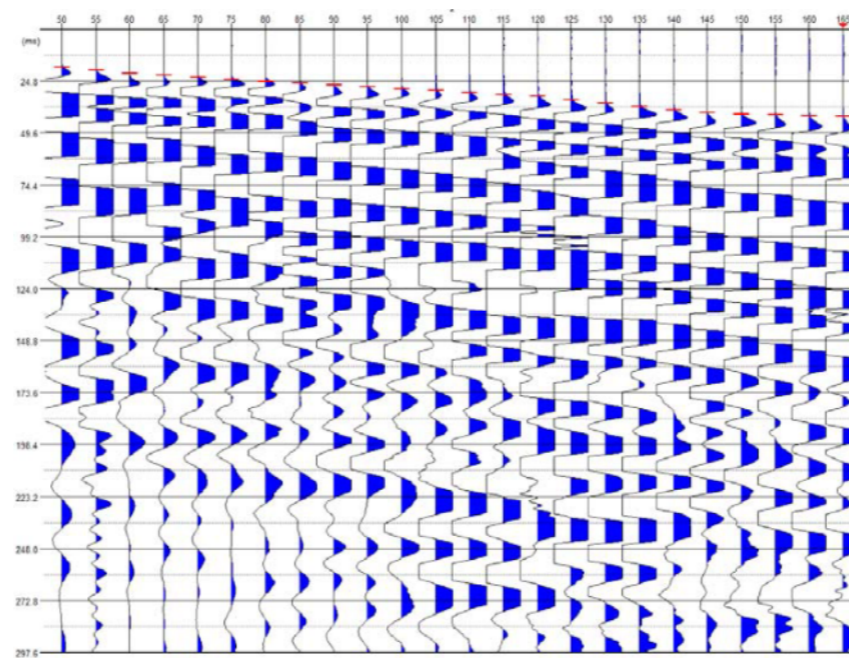


Seismic Refraction Examples

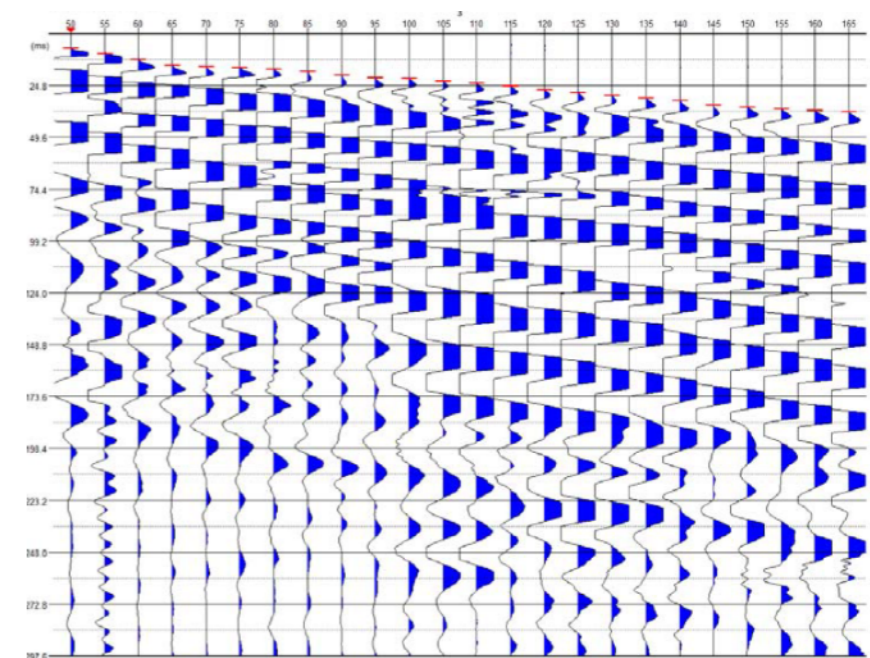
Shot 1



Shot 2

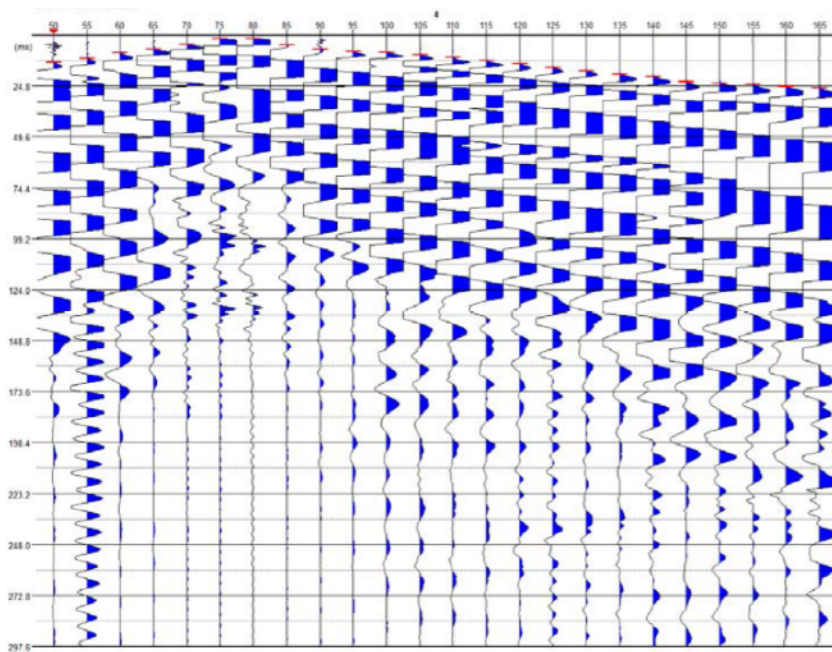


Shot 3

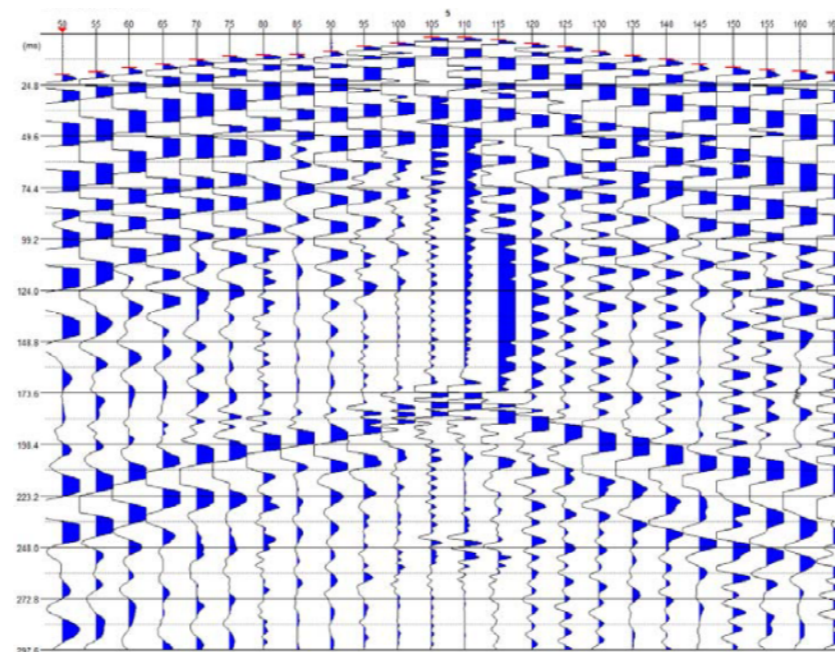


Seismic Refraction

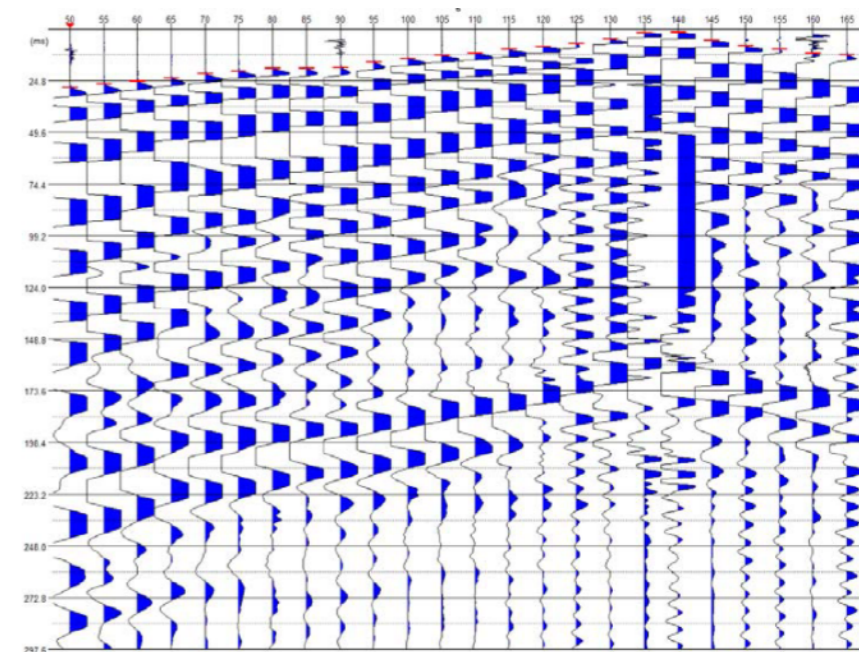
Shot 4



Shot 5

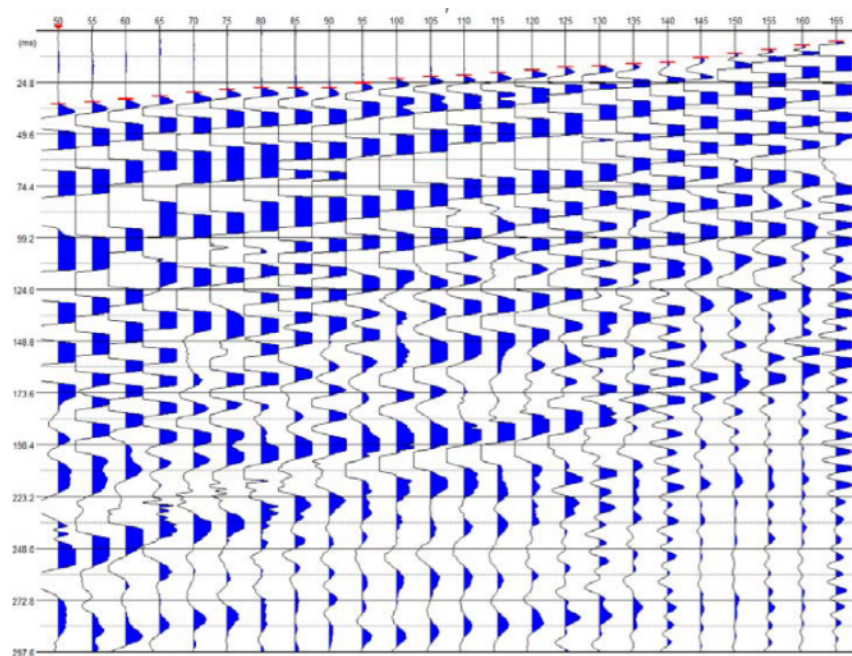


Shot 6

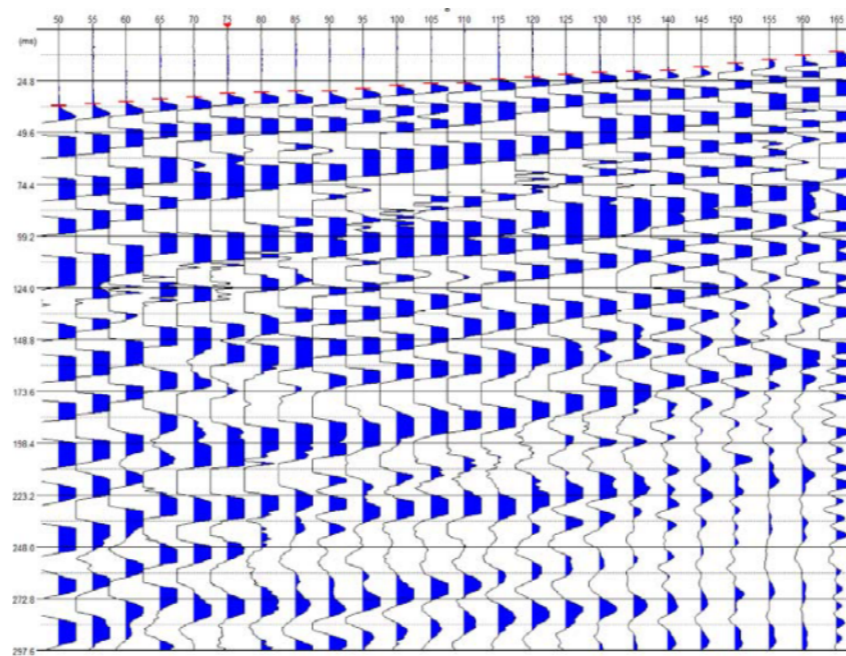


Seismic Refraction

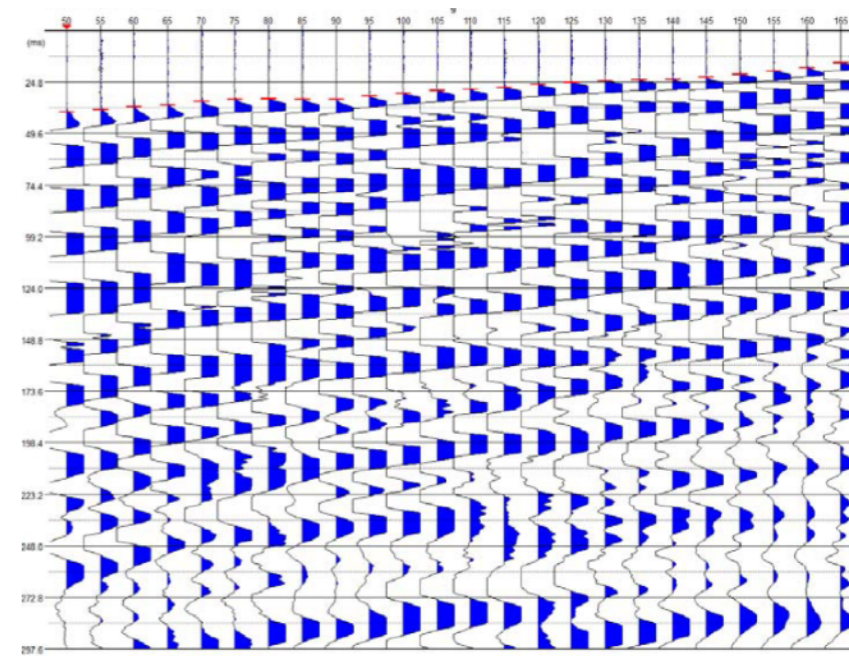
Shot 7



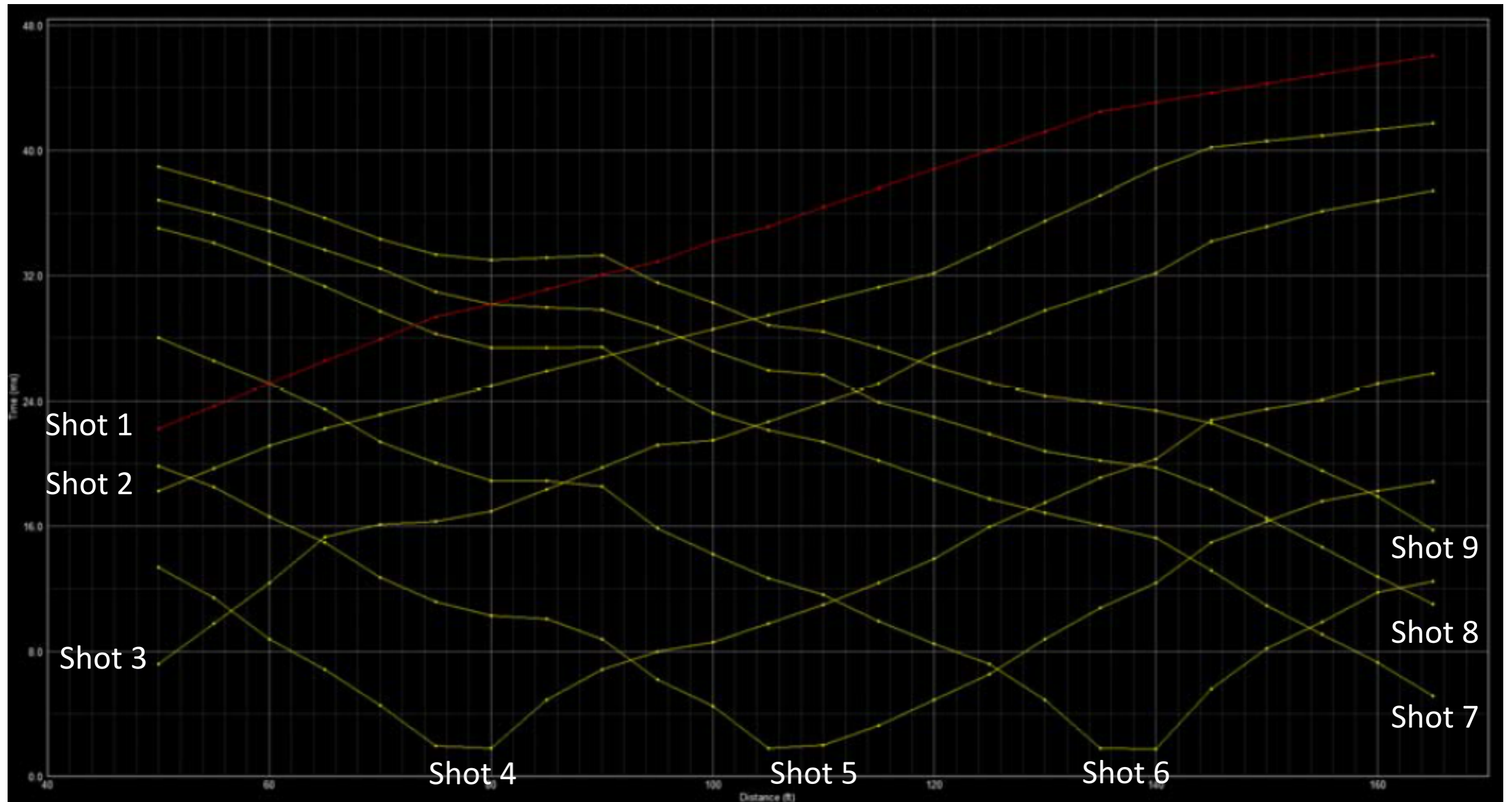
Shot 8



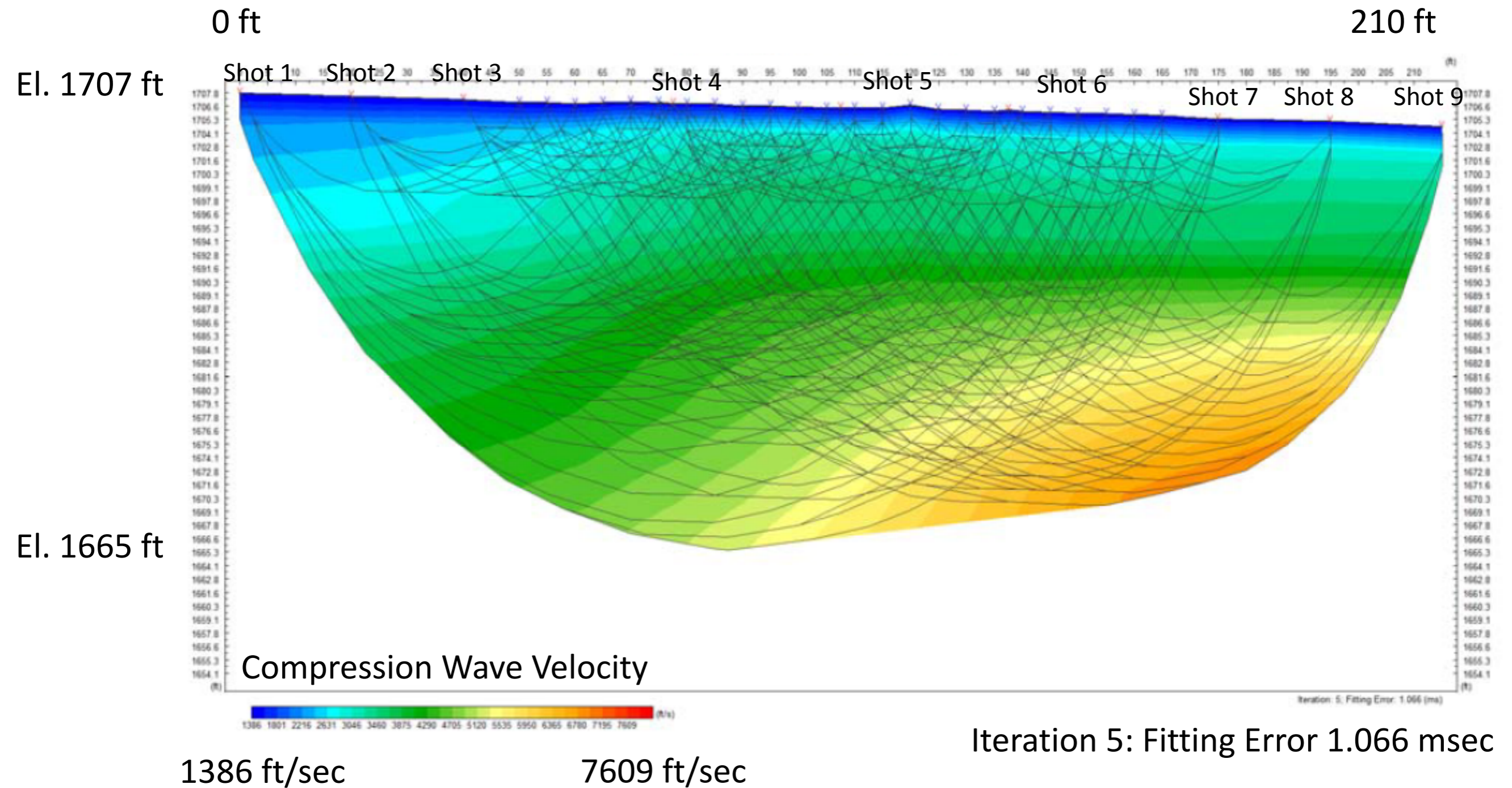
Shot 9



Seismic Refraction



Seismic Refraction

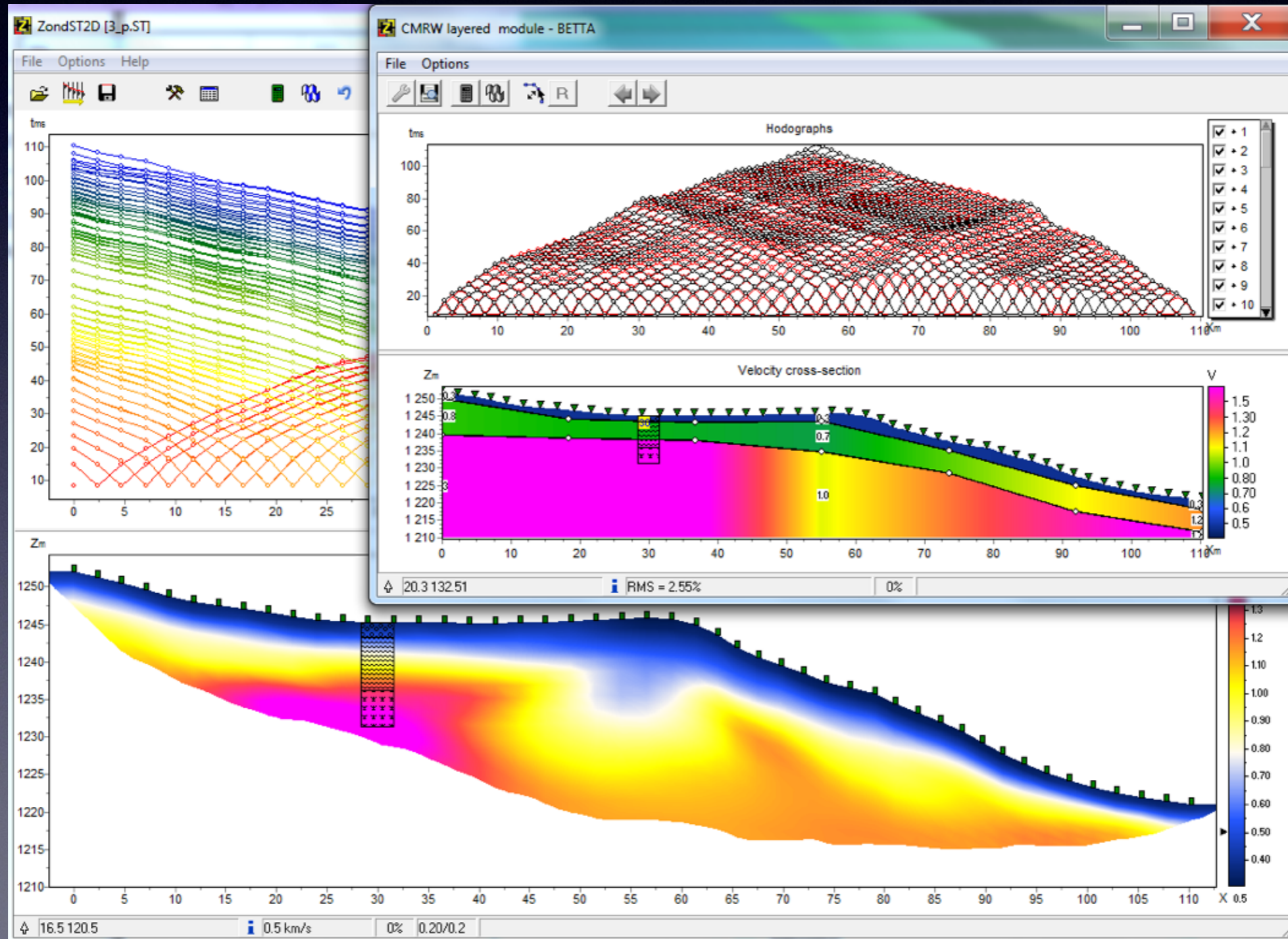


REFRACTION SEISMIC

Dozens of shot, dozen of ray paths

Software

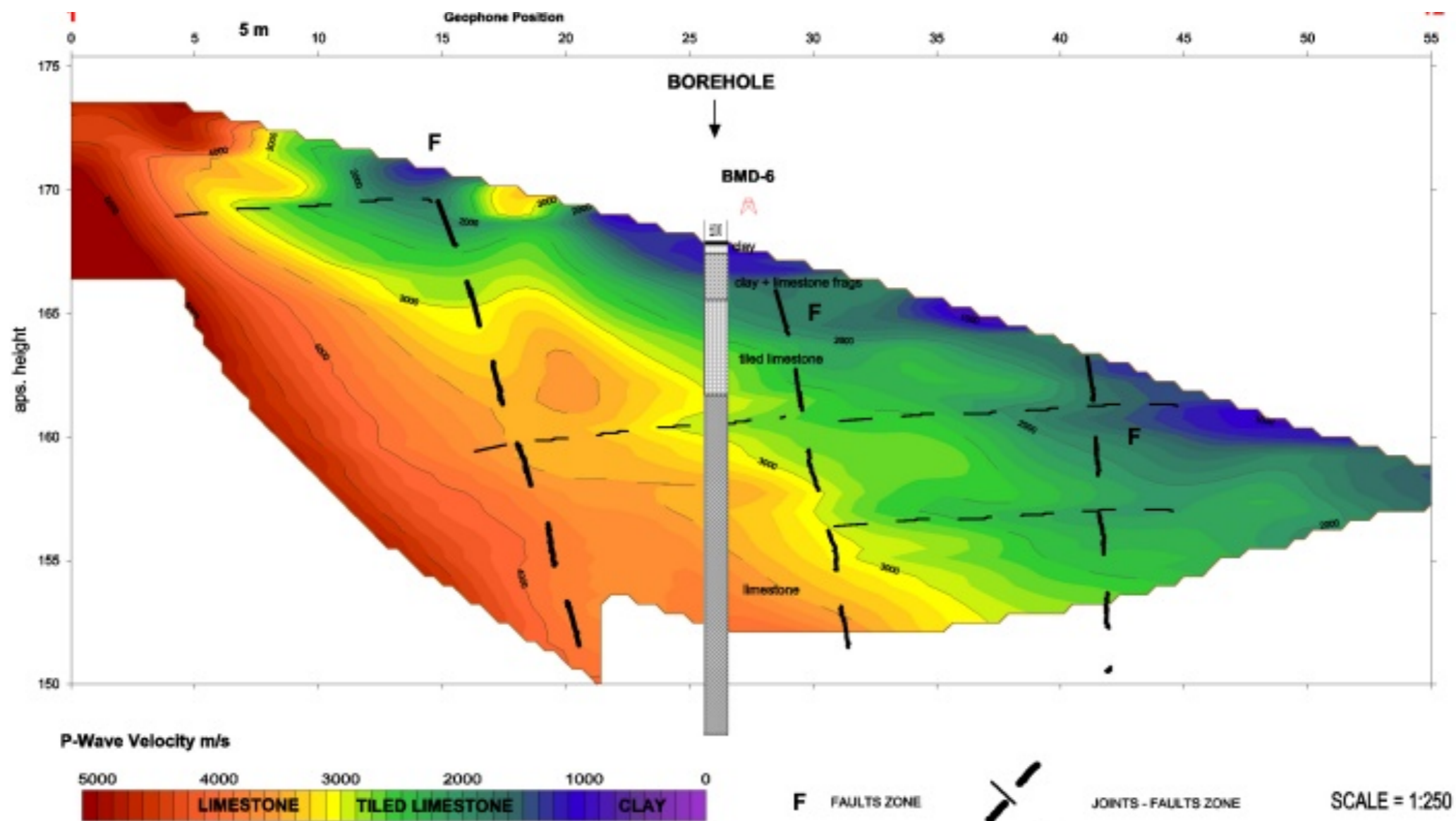
Seismic tomography



Velocities fields
In 2D -3D

Seismic Tomography

2D section of velocities distribution



V_p

Do I need this course ?

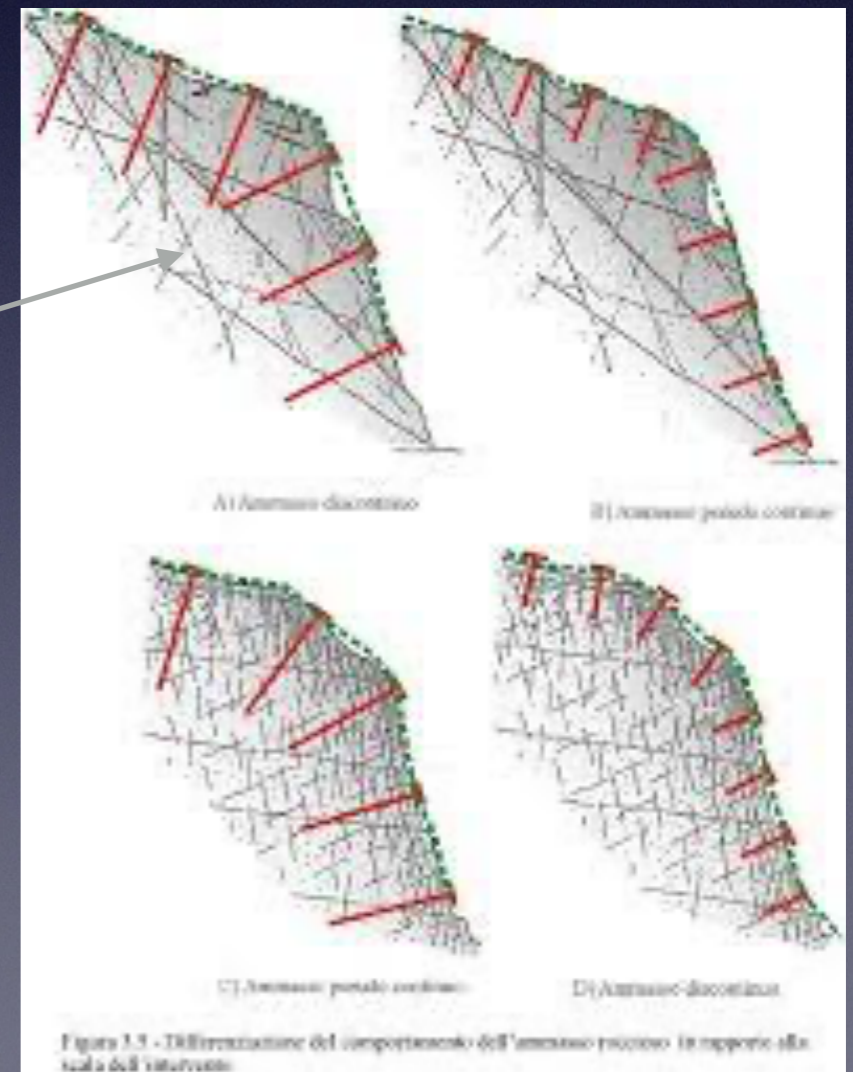


Practical problem:
Design a classical net
defence for rock falls



Nails must be anchored
in the solid rock
underneath debris...

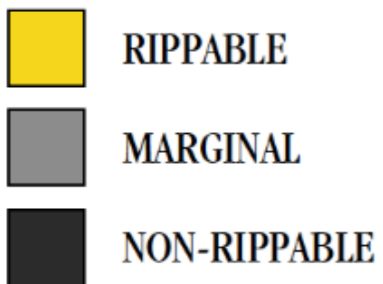
How to do?



Seismic Refraction

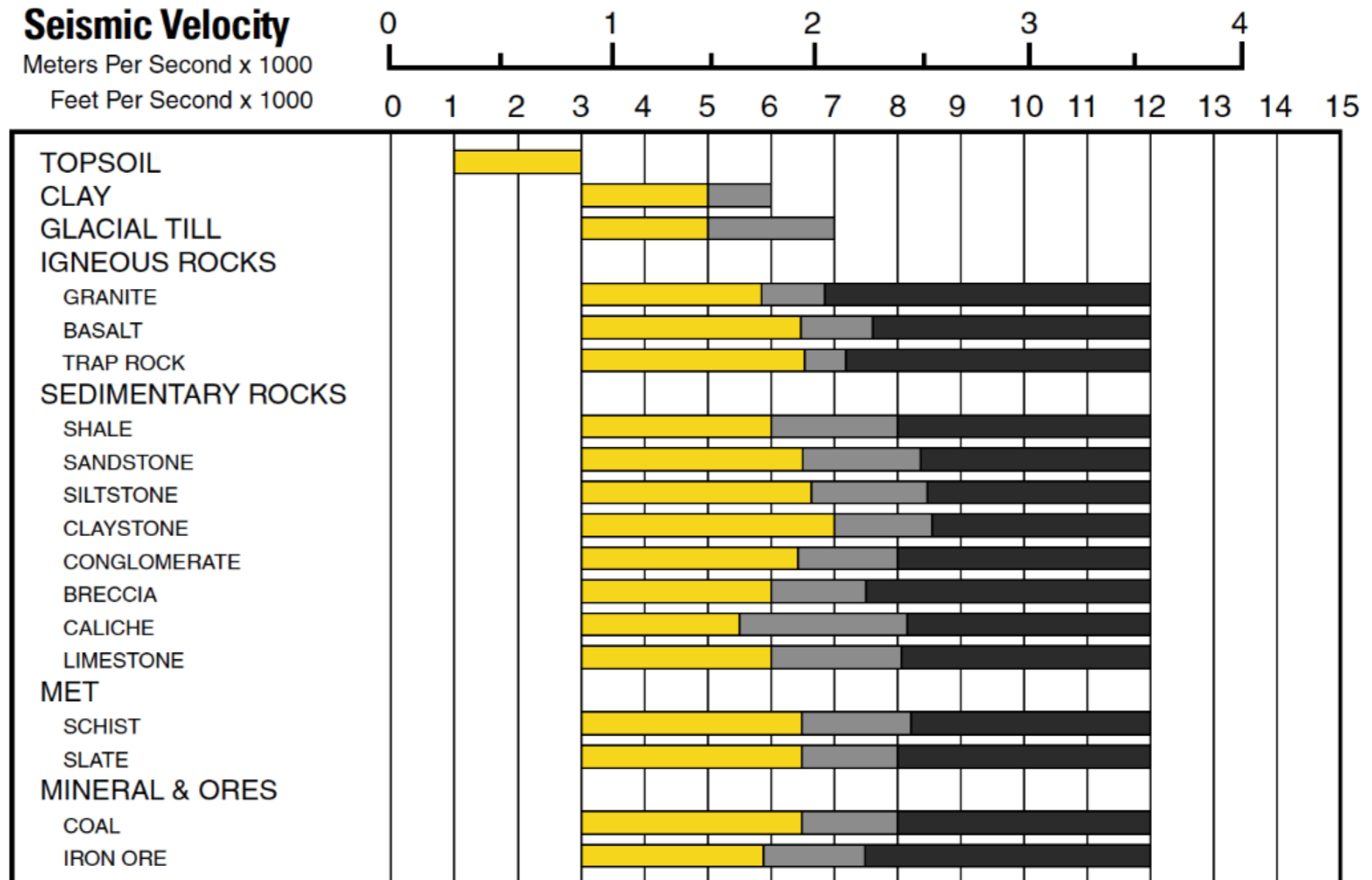
D8R Ripper Performance

- Multi or Single Shank No. 8 Series D Ripper
- Estimated by Seismic Wave Velocities



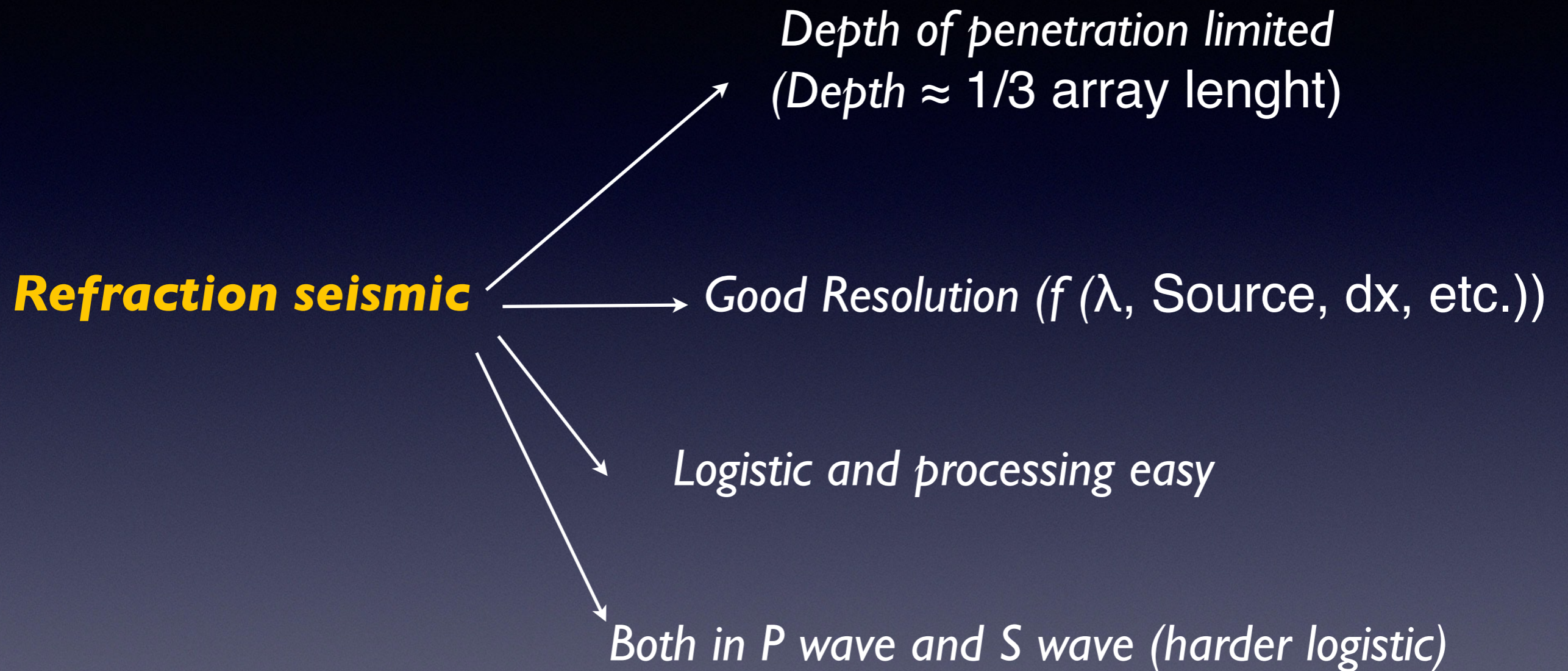
Seismic Velocity

Meters Per Second x 1000
Feet Per Second x 1000



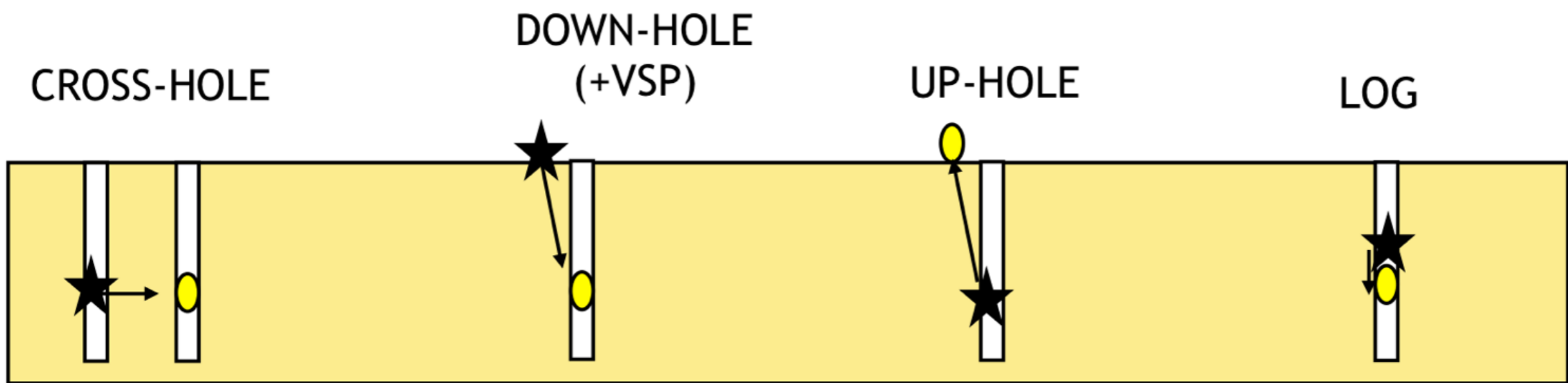
Source: Caterpillar

Seismic Methods

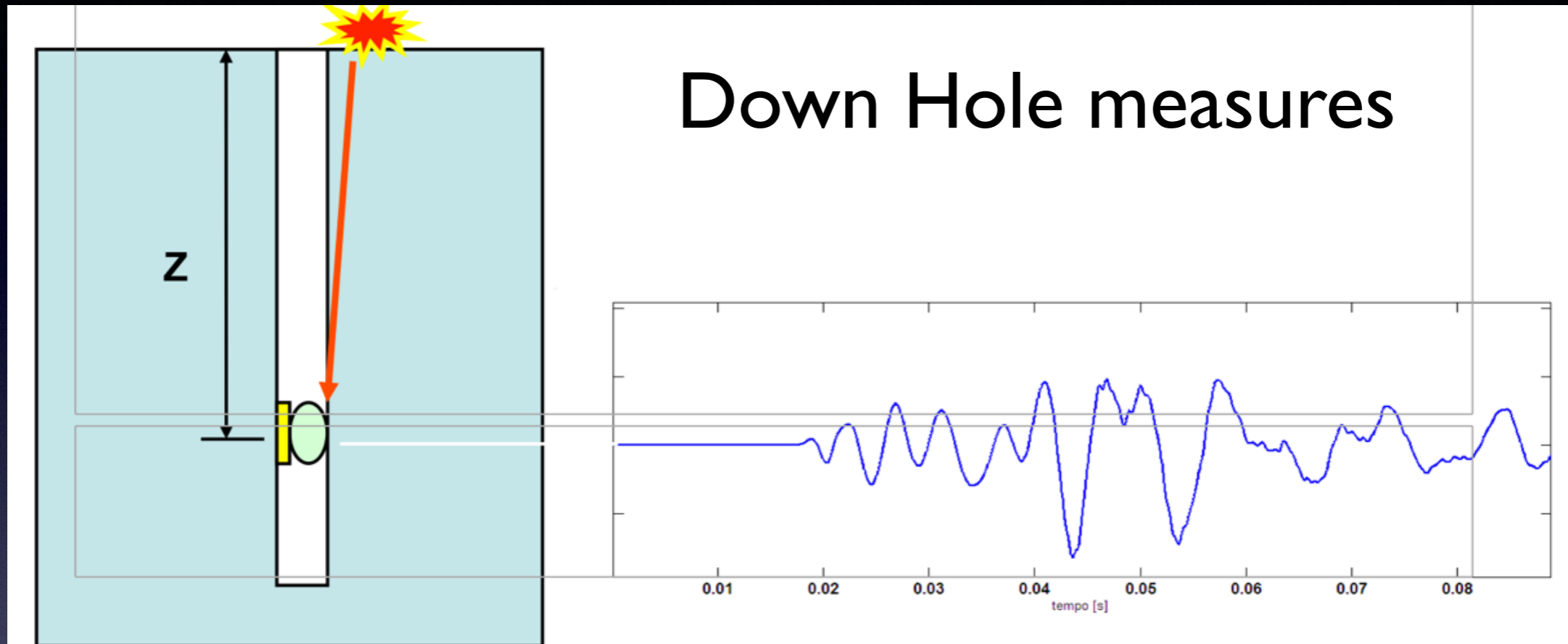


Blind to inversion velocity!

Borehole seismic



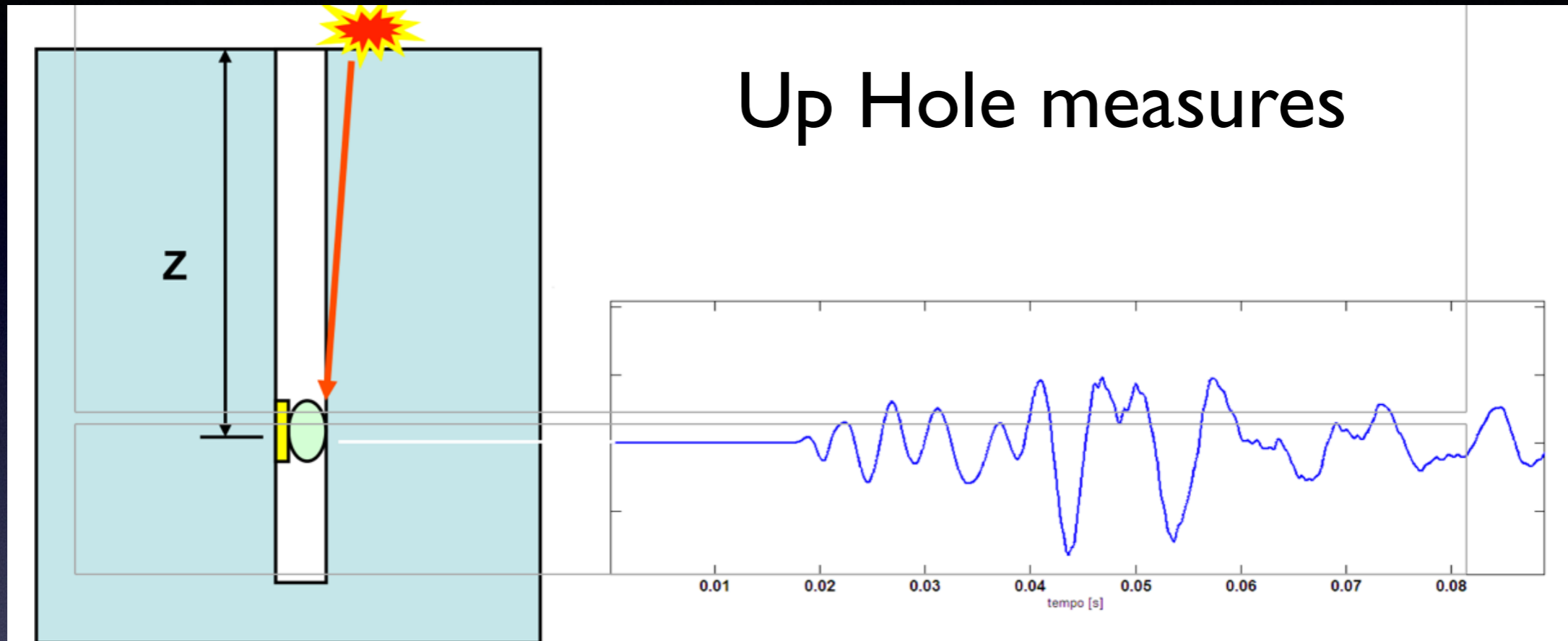
Borehole seismic



principles

Generate waves at the surface and measure time arrivals with receivers placed in the borehole at several depth.
Compute the velocity of the ray path

Borehole seismic

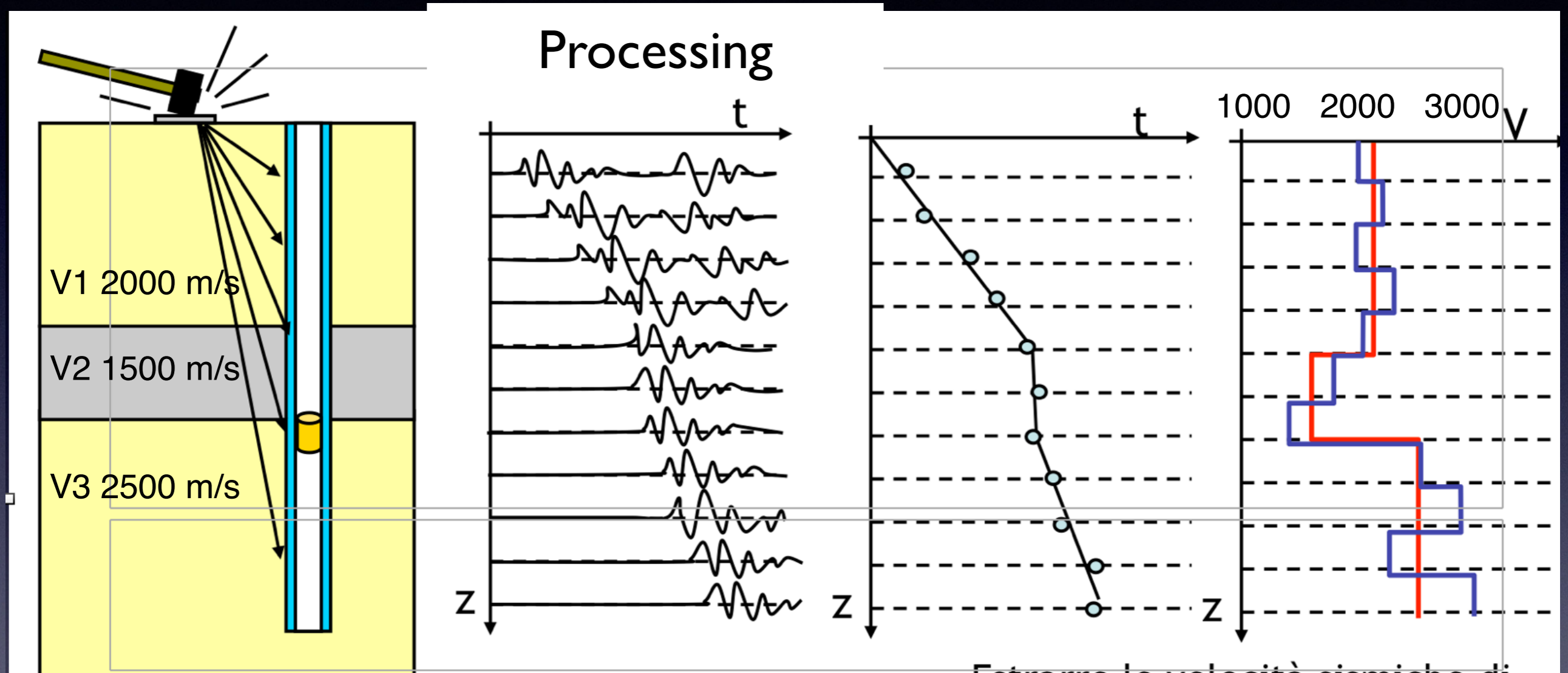


Up Hole measures

principles

Several shots in the borehole keeping fixed a receiver

Borehole seismic



Estimare le velocità sismiche di

Acquisition methods

1. SEISMIC WAVE SOURCES



2. RECEIVERS OF MOTION (Geophones)



3. RECORDING (Seismograph)



Seismic

I. SEISMIC WAVE SOURCES

Must be:

- POWERFUL

(Narrow in time, wide in frequency)

$$\ll \lambda$$



$$\lambda = v/f$$

- RIPETIBLE

To perform stack (sum) of the single and increase the signal/noise ratio

Sources



IMPULSIVE

VIBROTIONAL

Seismic

I. SEISMIC WAVE SOURCES

Sledge Hammer



(Impulsive)

Vibroseis

(vibro)



Air gun (sea)

(imp.)



I. SEISMIC WAVE SOURCES

Accelerated
Mass (imp)



$$f = m * a$$

Seismic gun (imp)



Explosive (imp)



Seismic

I. SEISMIC WAVE SOURCES

30kg tnt

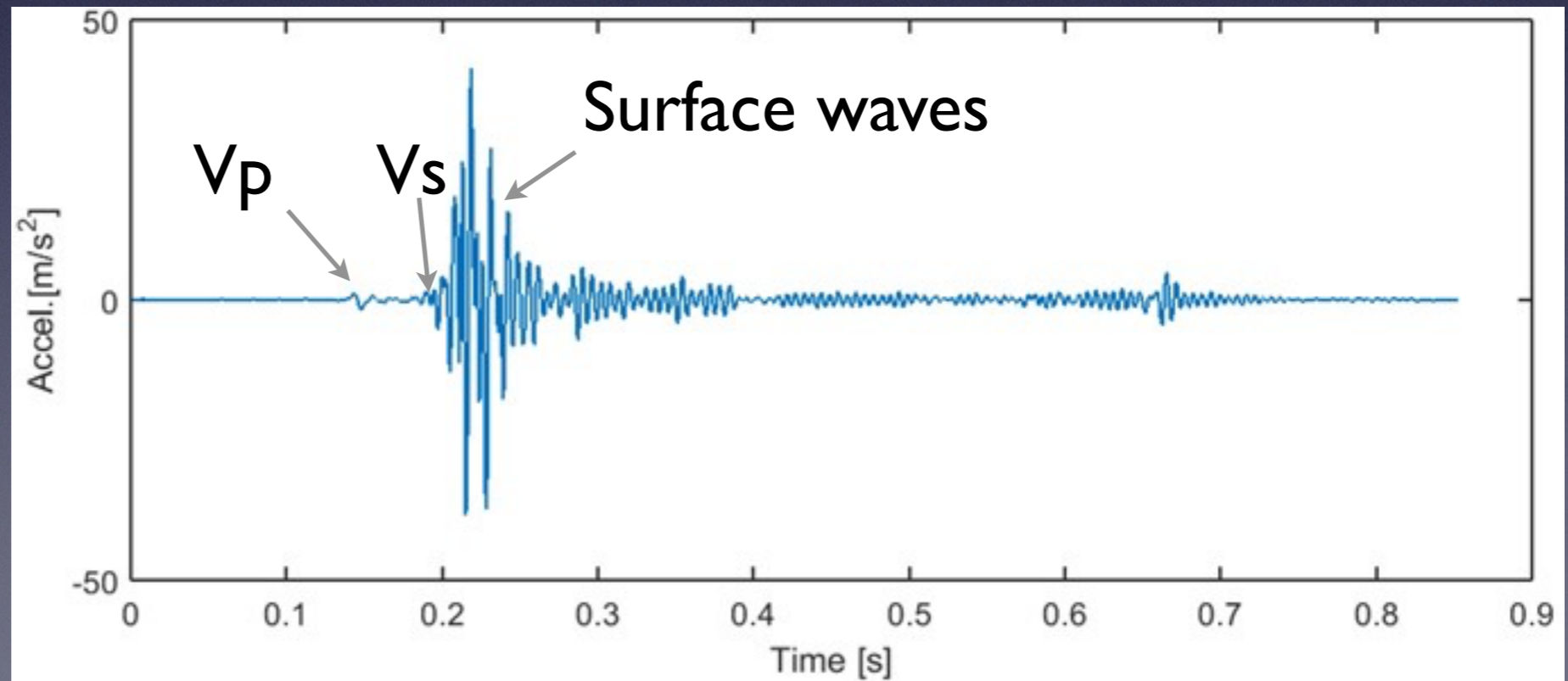


I. SEISMIC WAVE SOURCES



IMPULSIVE

Seismic trace
We want collect



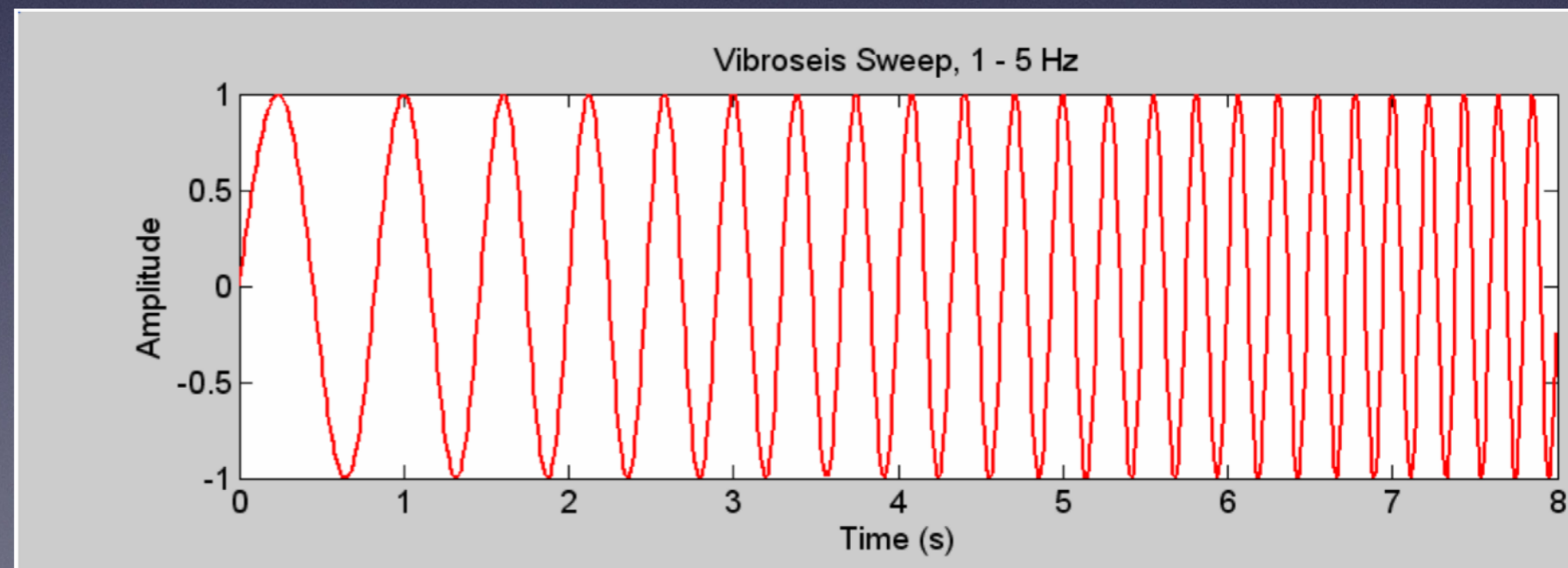
I. SEISMIC WAVE SOURCES

Vibrational

VIBROSEIS TRUCK
(Leader of industrial reflection surveys)



Source of vibration with constant replicable signals
(Called the **sweep**)



e.g, 1 Hz - 5 Hz 8 seconds sweep

Seismic

I. SEISMIC WAVE SOURCES

Vibrational

VIBROSEIS

Convolution

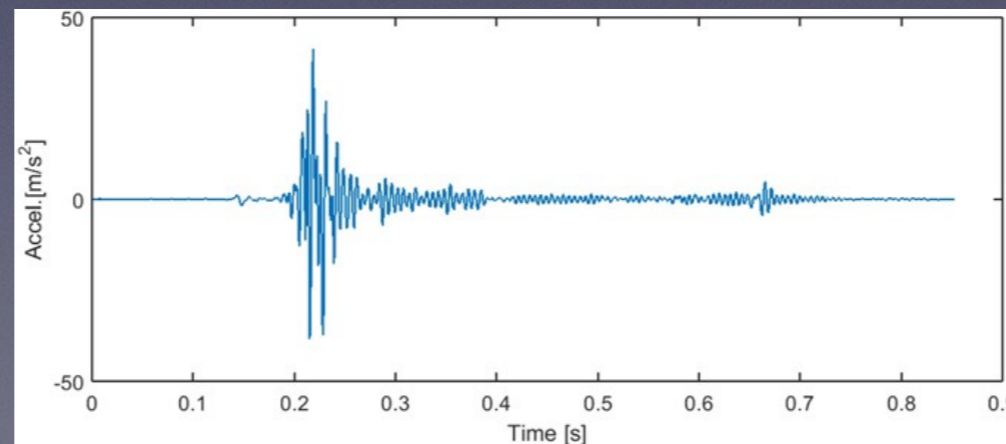
$$u(t) = sw(t) * e(t)$$

Sweep

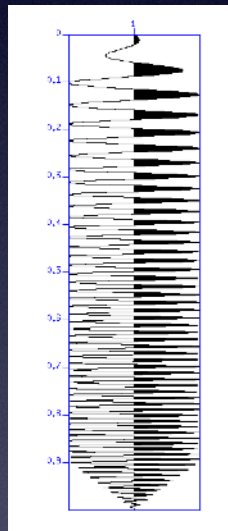
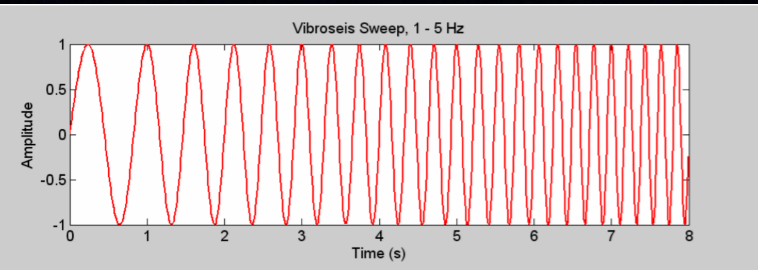
Earth Filter

Recorded
Seismogram

Trace target
 $s(t)$



?



I. SEISMIC WAVE SOURCES

VIBROSEIS

Cross -correlation

$$s(t) = sw(t) \star u(t)$$

Correlated
Seismogram

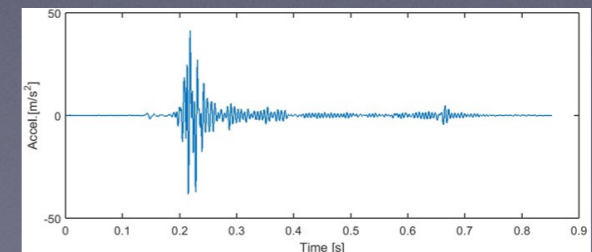
Sweep

Recorded seismogram

Cross correlation of the Sweep (source) with the recorded signal

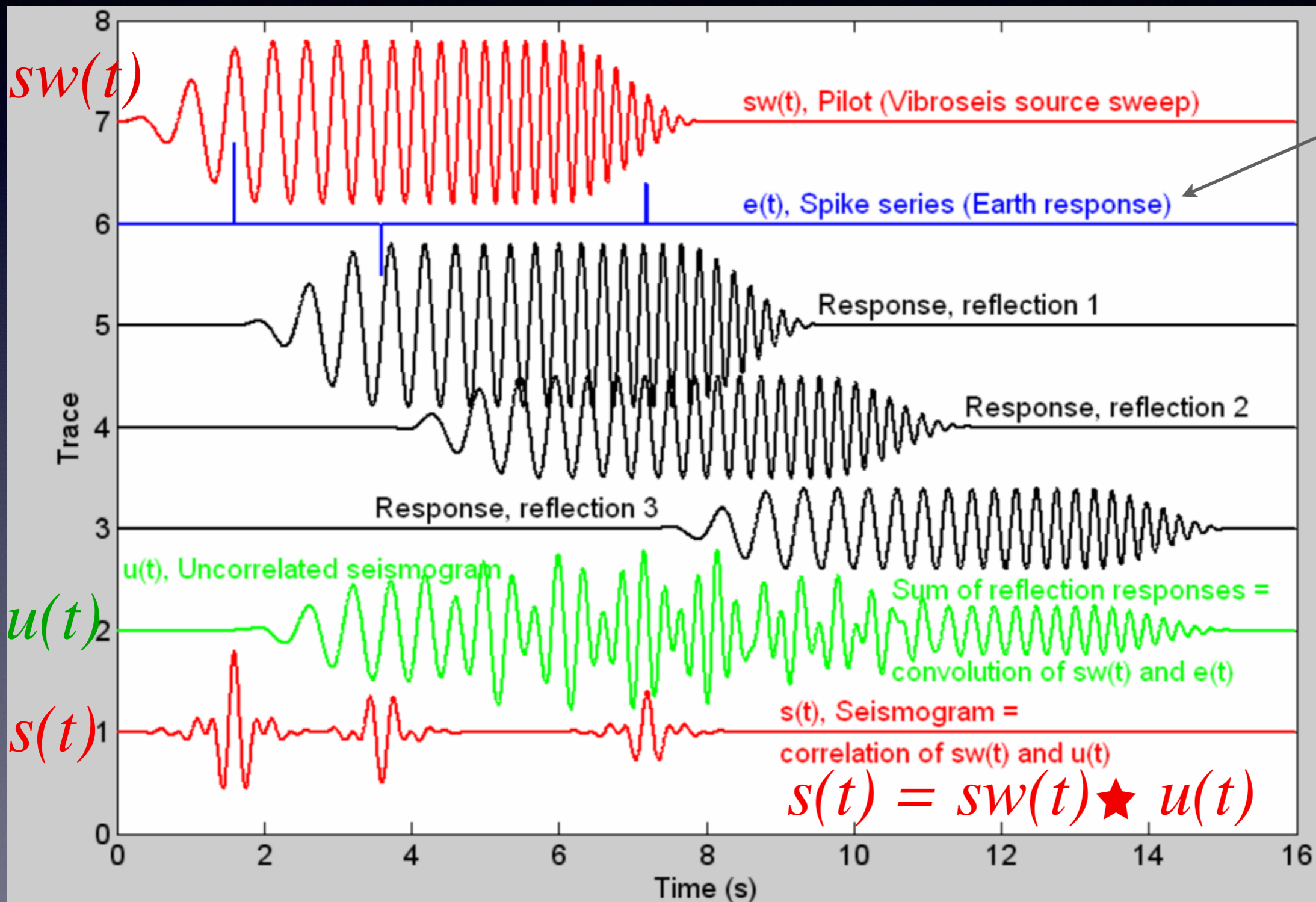


Impulsive signal



I. SEISMIC WAVE SOURCES

VIBROSEIS



Examples with 3 Layers



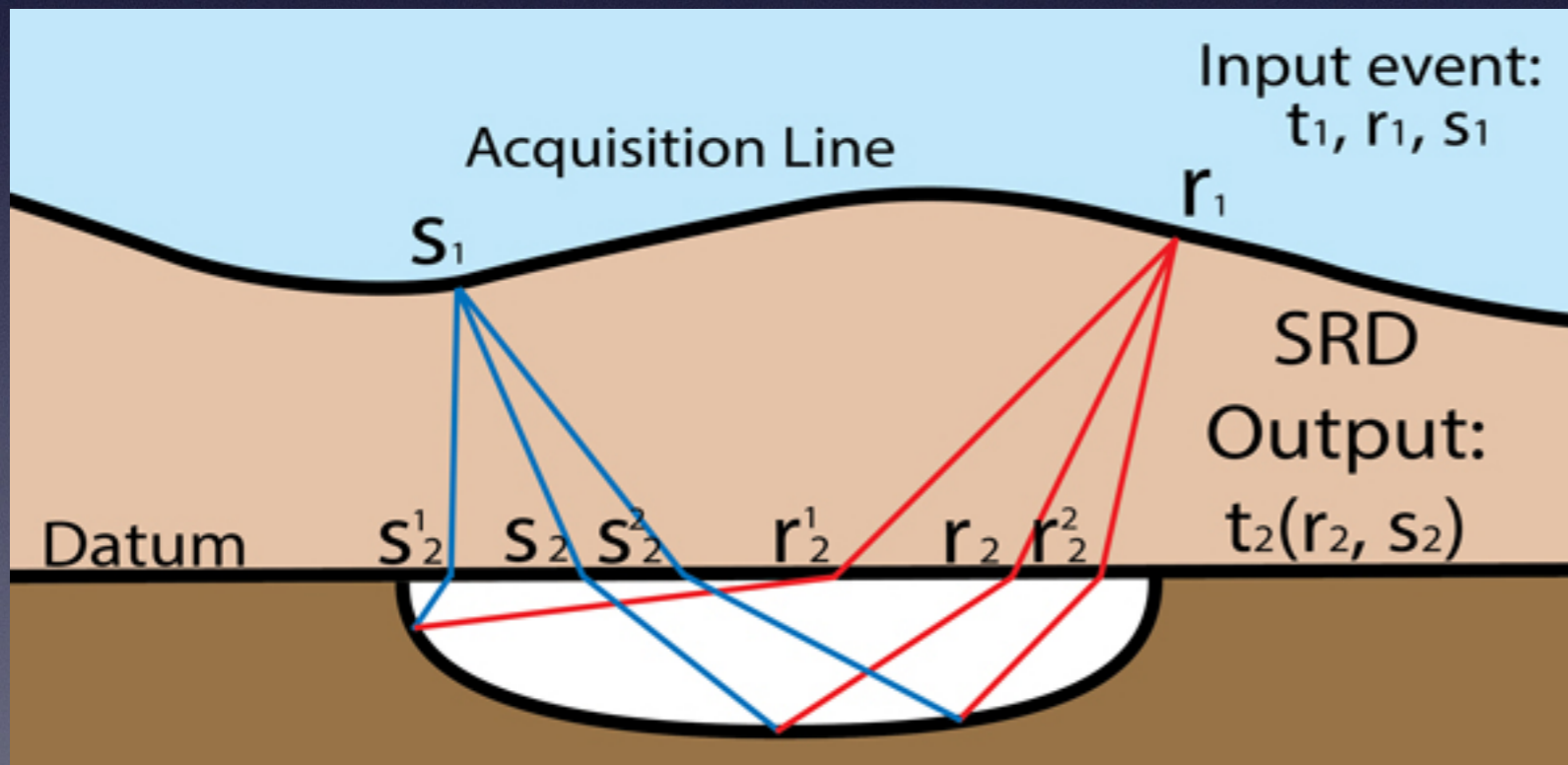
Seismic

I. SEISMIC WAVE SOURCES

Increase source quality

Better to put source in depth, avoiding weathered layer that attenuates the signal

+ Energy
- Attenuation



Topography is relevant

In case you can refer to a unique

*Topo
(DATUM
Static correction)*

Seismic

I. SEISMIC WAVE SOURCES

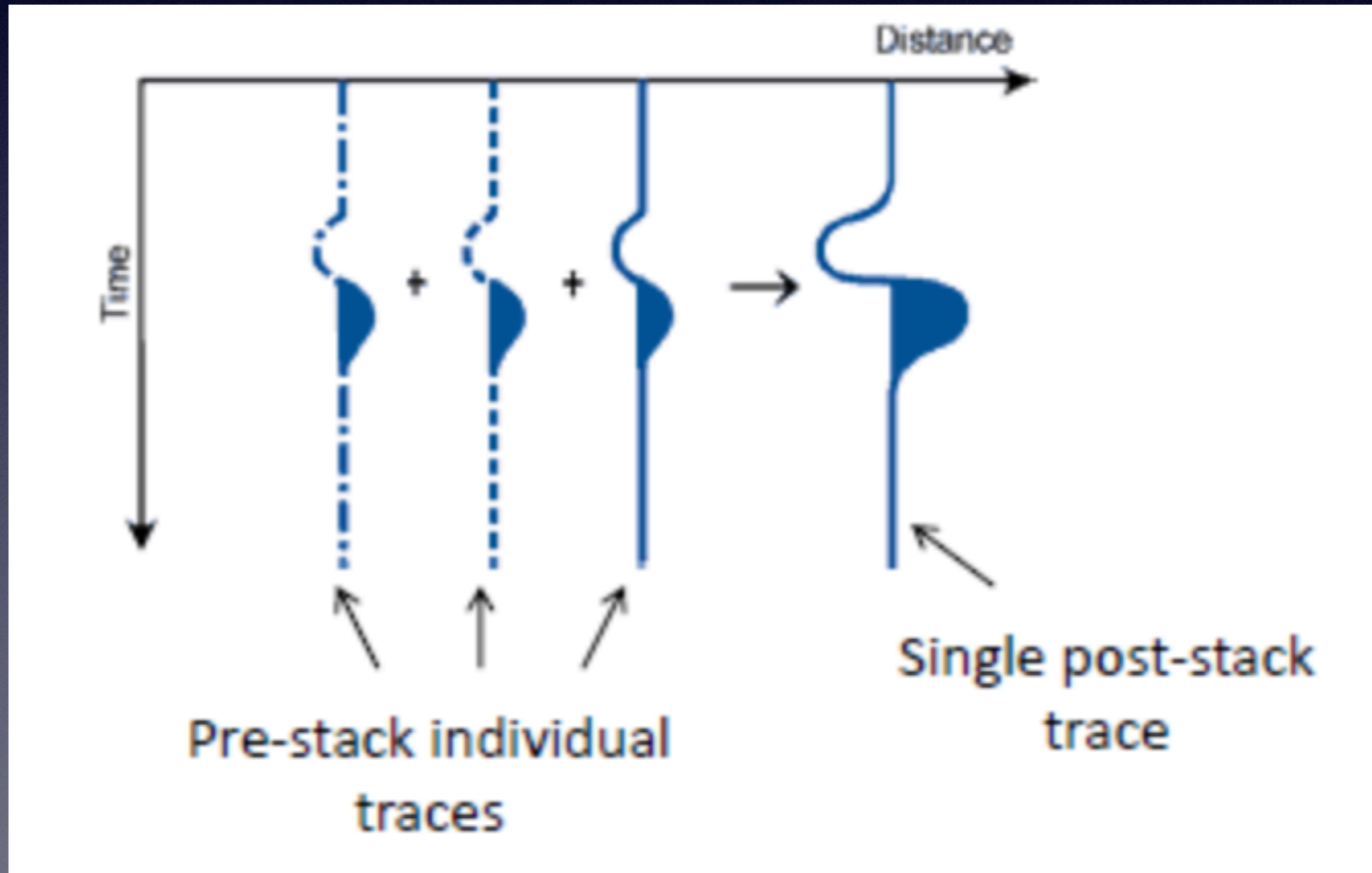
Increase source quality

Execute repeated measurements to sum all the recorded signals

STACKING

Signal is in phase, noise no!

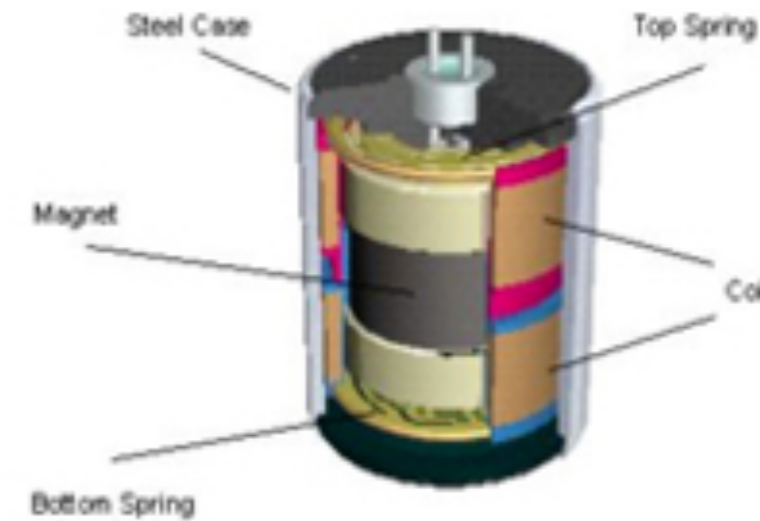
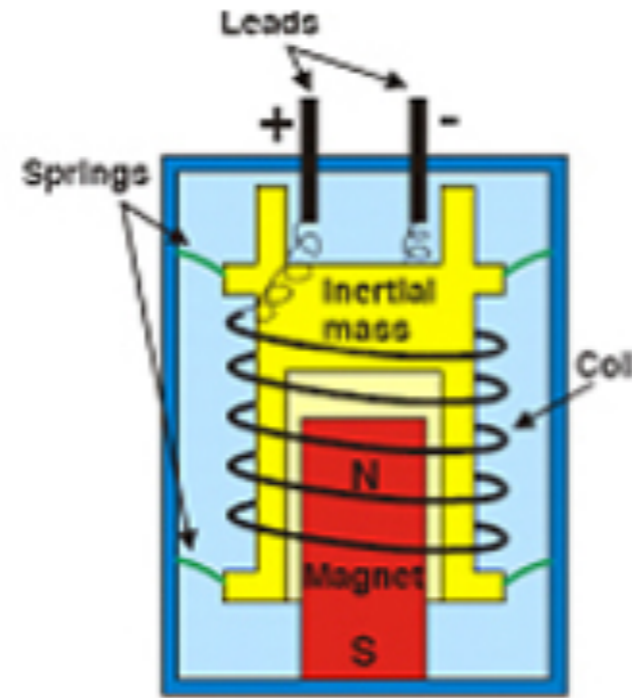
Increase signal to noise ratio (S/N)



Help the picking

RECEIVERS

GEOPHONES



They are **velocimeters** that convert the displacement velocity
In voltage (Faradays law)
For greater shaking also accelerometer are used

Seismic

RECEIVERS

GEOPHONES

I. BOREHOLE SEISMIC

Down Hole

BOREHOLE GEOPHONE

It is crucial the contact between sensors and borehole: clipping operation.



RECEIVERS

Seismic

GEPHONES

Surface ones

vertical



Horizontal



Tri-components



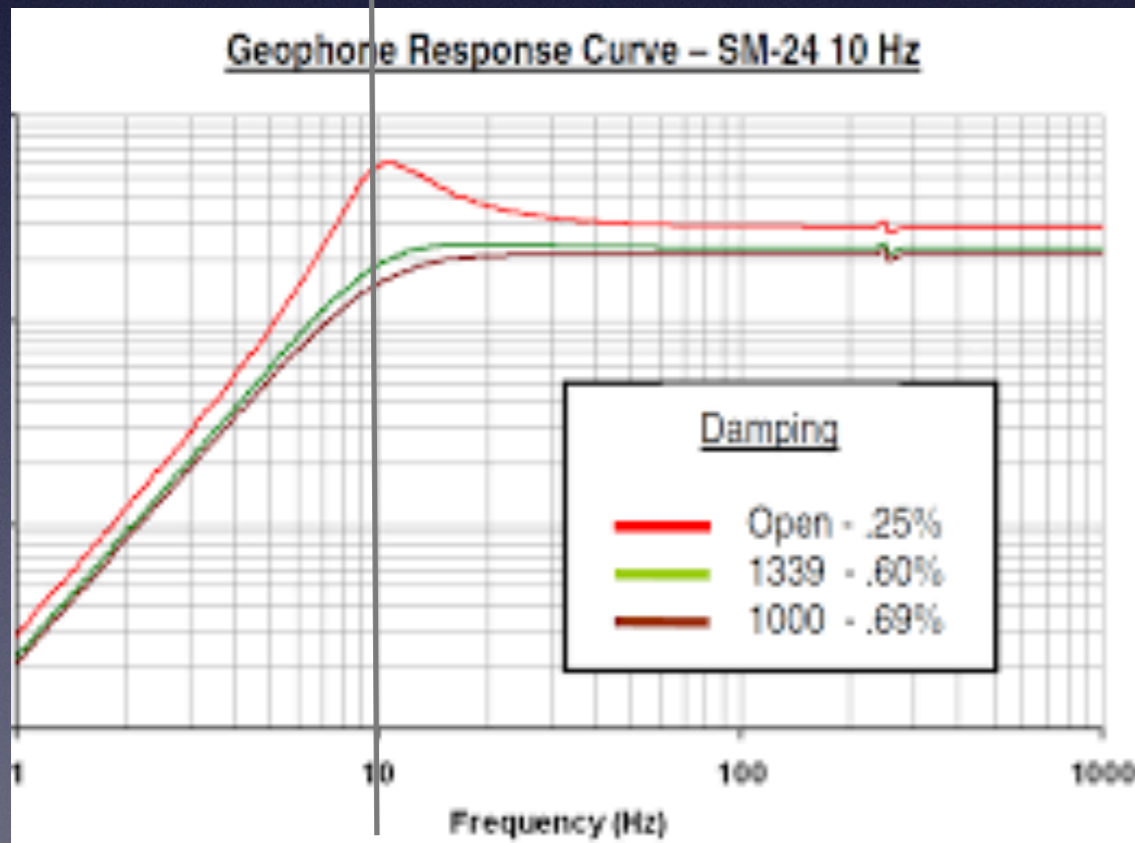
RECEIVERS

GEOPHONES

They are divided in base of the frequency response

NATURAL (CORNER) FREQUENCY OF THE GEOPHONE

Corner Freq.



Transfer function
(Instrumental response)
of a geophone

They are the high-pass filters

VERY IMPORTANT THE CORRECT CHOICE:

E.g. refraction: 50-100 Hz

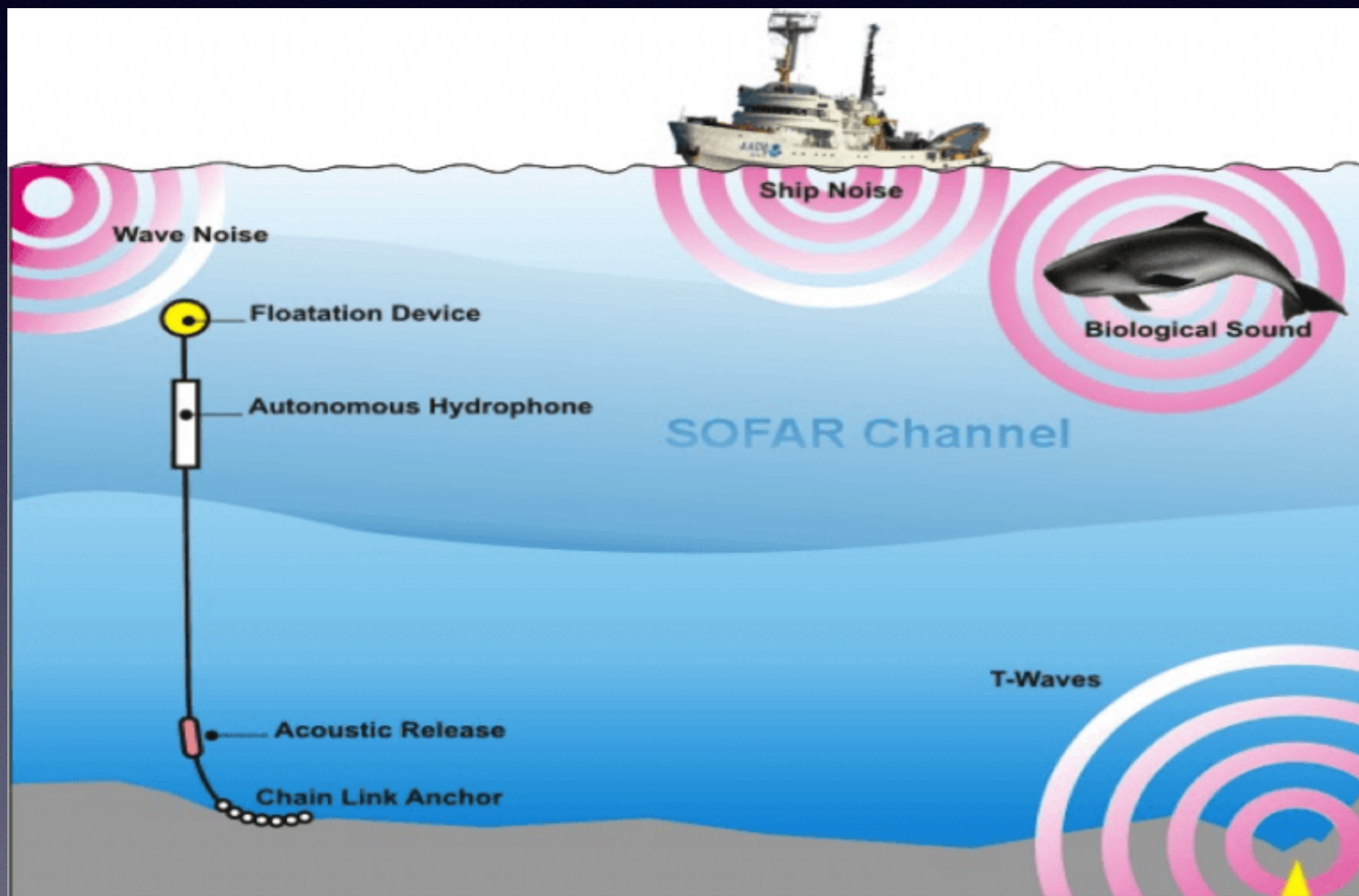
SW: 4 Hz

Seismic

RECEIVERS

GEOPHONES

In sea **HYDROPHONES**



*From 4 Hz to
Very high frequency*

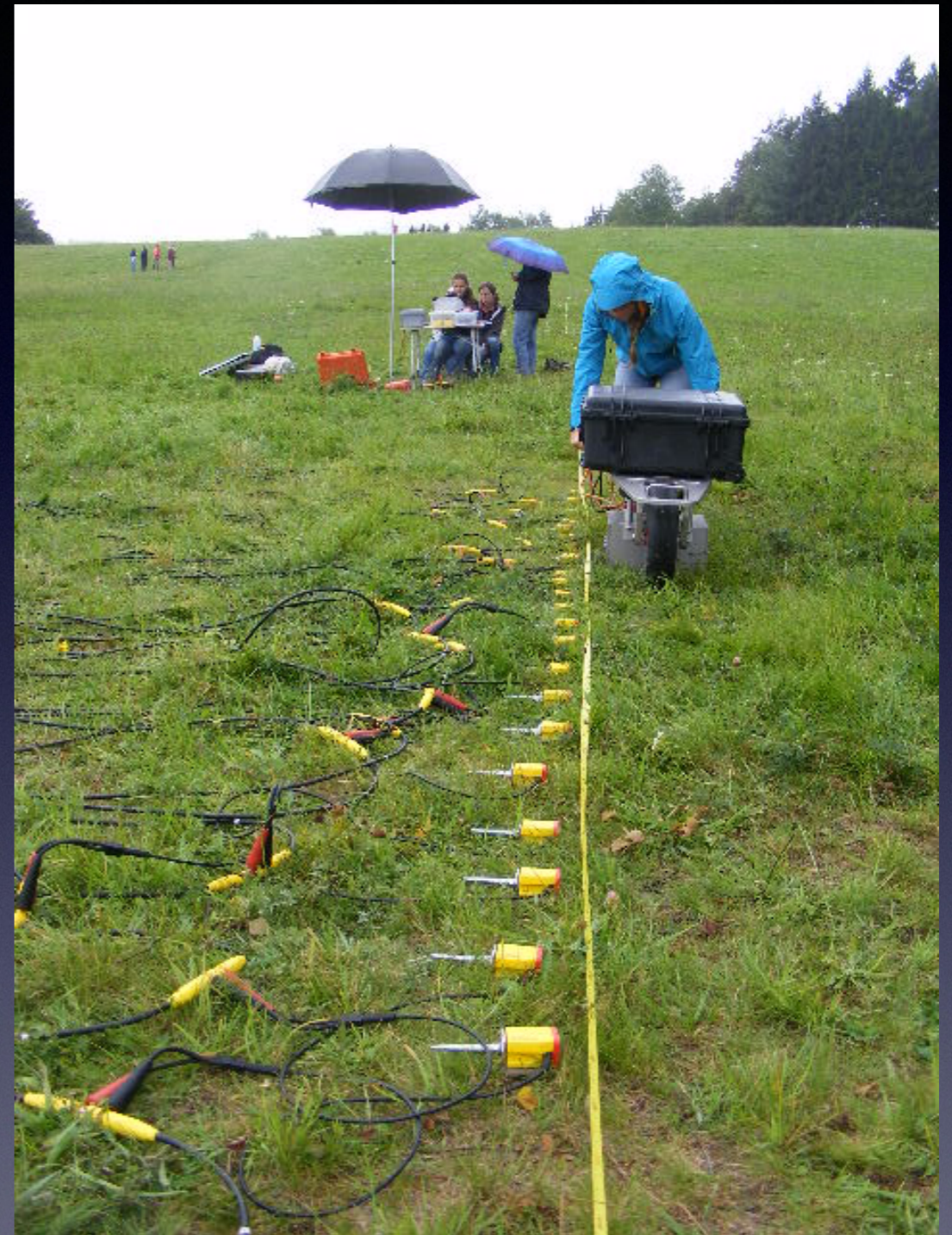
RECEIVER INSTALLATION



USUALLY equal-spaced
Array

<< dx (spacing) >> Resolution

>> x (total length) >> Penetration



A compromise between numbers of receivers, spacing, total length, power of the source

RECEIVER INSTALLATION

- Planted
- drilled in holes
- Leaning on pavement....



3. RECORDED (SEISMOGRAPH)

Digital
(16-24 bit)

Multi-channels
(24-48- n....)



COMPLEX AND EXPANSIVE INSTRUMENTS

Seismic Logistic

Methods	GEOPHONES	RESOLUTION	DEPTH
Refraction	24- N	cm -m	m - Km

COST: - Geophones 100 \$
- cables 5k \$
-Seismograph 24 nodes 25k\$